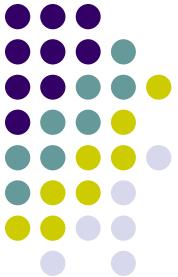


# Davis Logemann Loveland Algorithm Framework



```
while(1) {
    if (decide_next_branch()) { //Branching
        while(deduce()==conflict) { //Deducing
            blevel = analyze_conflicts();
            if (blevel < 0)
                return UNSAT;
            else back_track(blevel); //Backtracking
        }
    } else //no branch means all variables got assigned.
        return SATISFIABLE;
}
```



# Chronological Backtracking

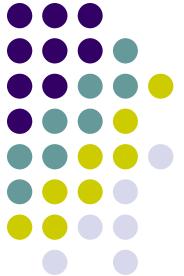
- Backtracking to the highest decision level that has not been tried with both values
- Originally proposed in the DLL paper in 1962
- OK for randomly generated instances, bad for instances generated in practical applications
- We can do better than that

# Conflict Driven Learning and Non-Chronological Backtracking



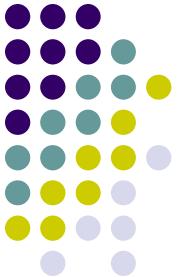
- Marques-Silva and Sakallah [SS96, SS99]
  - J. P. Marques-Silva and K. A. Sakallah, "GRASP -- A New Search Algorithm for Satisfiability," Proc. ICCAD 1996.
  - J. P. Marques-Silva and Karem A. Sakallah, "GRASP: A Search Algorithm for Propositional Satisfiability", *IEEE Trans. Computers*, C-48, 5:506-521, 1999.
- Bayardo and Schrag's RelSAT also proposed conflict driven learning [BS97]
  - R. J. Bayardo Jr. and R. C. Schrag "Using CSP look-back techniques to solve real world SAT instances." *Proc. AAAI*, pp. 203-208, 1997
- Practical SAT instances can be solved in reasonable time

# Conflict Driven Learning and Non-chronological Backtracking

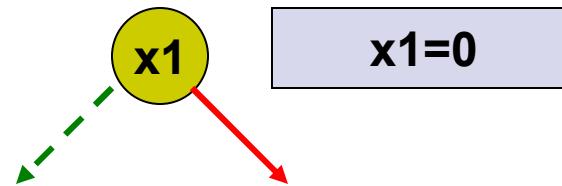


$x_1 + x_4$   
 $x_1 + x_3' + x_8'$   
 $x_1 + x_8 + x_{12}$   
 $x_2 + x_{11}$   
 $x_7' + x_3' + x_9$   
 $x_7' + x_8 + x_9'$   
 $x_7 + x_8 + x_{10'}$   
 $x_7 + x_{10} + x_{12'}$

# Conflict Driven Learning and Non-chronological Backtracking

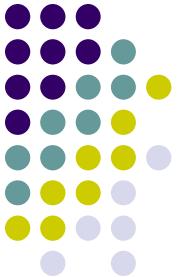


$x_1 + x_4$   
 $x_1 + x_3' + x_8'$   
 $x_1 + x_8 + x_{12}$   
 $x_2 + x_{11}$   
 $x_7' + x_3' + x_9$   
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 $x_7 + x_{10} + x_{12'}$

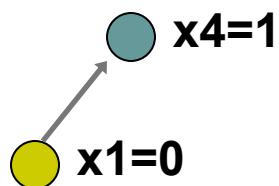
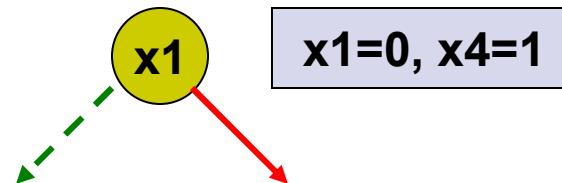


●  $x_1 = 0$

# Conflict Driven Learning and Non-chronological Backtracking



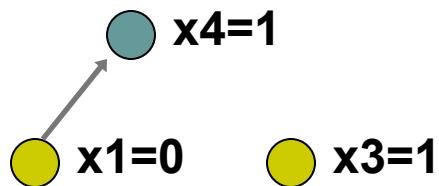
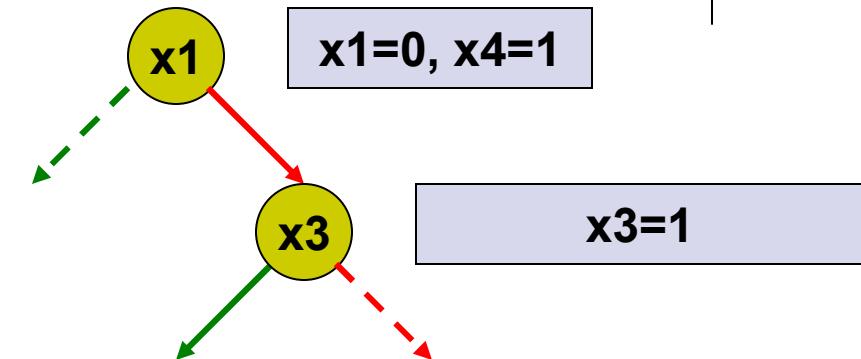
$x_1 + x_4$   
 $x_1 + x_3' + x_8'$   
 $x_1 + x_8 + x_{12}$   
 $x_2 + x_{11}$   
 $x_7' + x_3' + x_9$   
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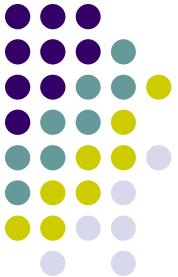
# Conflict Driven Learning and Non-chronological Backtracking



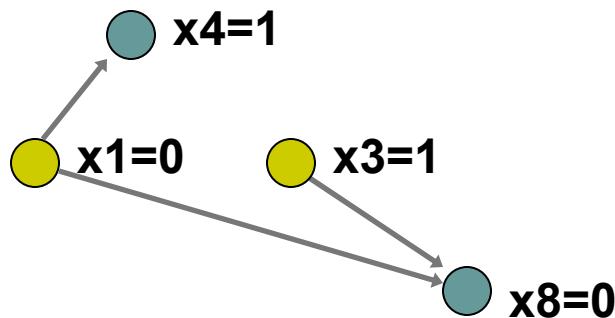
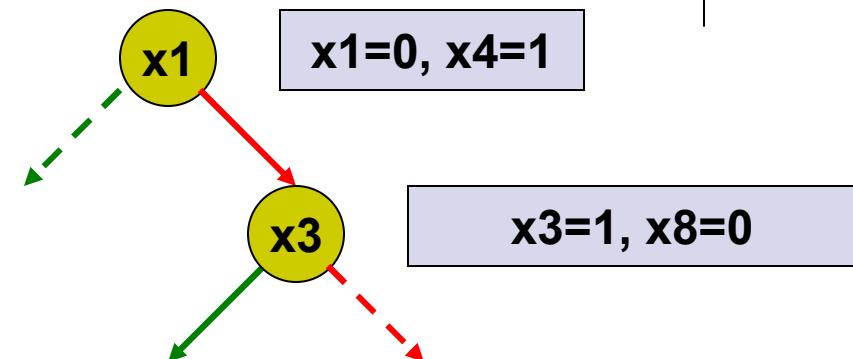
$x_1 + x_4$   
 $x_1 + x_{3'} + x_8'$   
 $x_1 + x_8 + x_{12}$   
 $x_2 + x_{11}$   
 $x_7' + x_{3'} + x_9$   
 $x_7' + x_8 + x_{9'}$   
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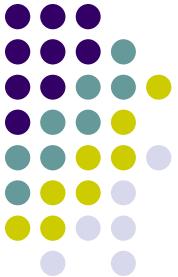
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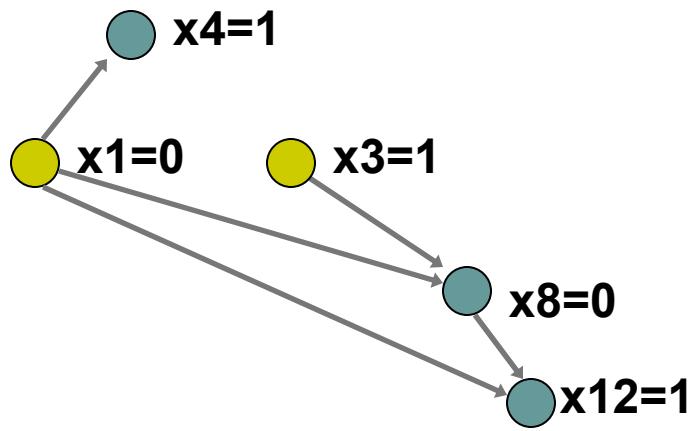
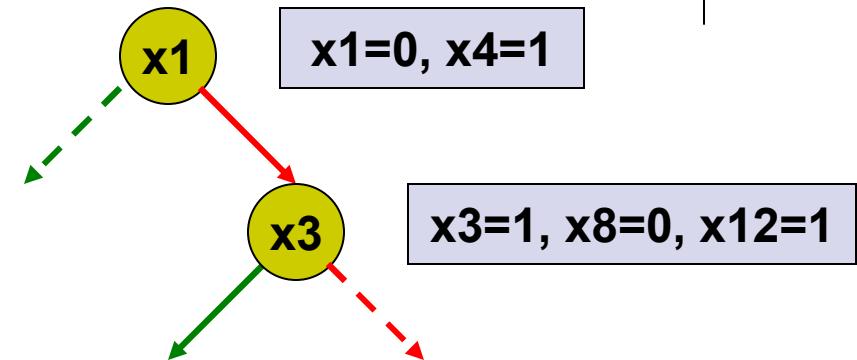
$x_1 + x_4$   
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 $x_1 + x_8 + x_{12}$   
 $x_2 + x_{11}$   
 $x_7' + x_3' + x_9$   
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# Conflict Driven Learning and Non-chronological Backtracking



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 $x_7' + x_3' + x_9$   
 $x_7' + x_8 + x_9'$   
 $x_7 + x_8 + x_{10}'$   
 $x_7 + x_{10} + x_{12}'$



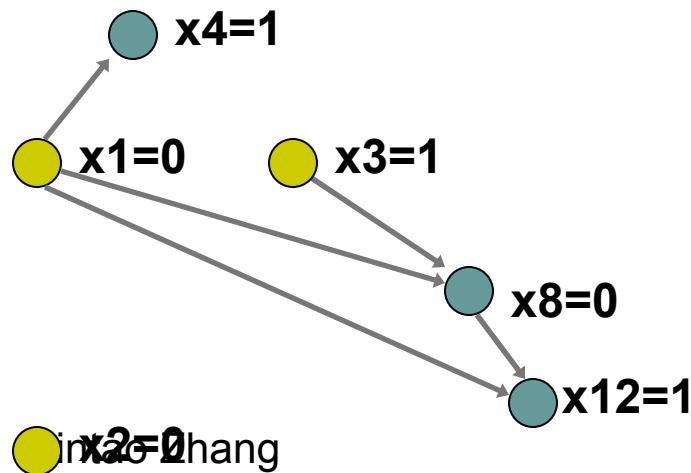
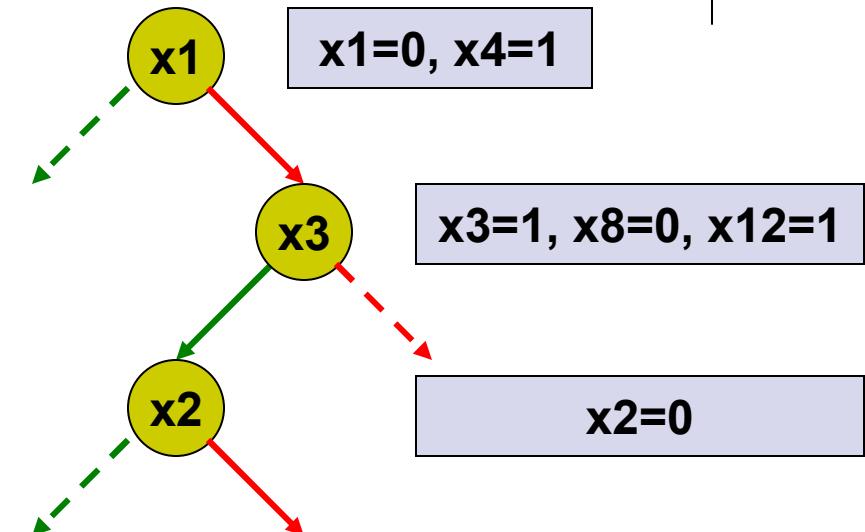
Lintao Zhang

Microsoft  
Research

# Conflict Driven Learning and Non-chronological Backtracking



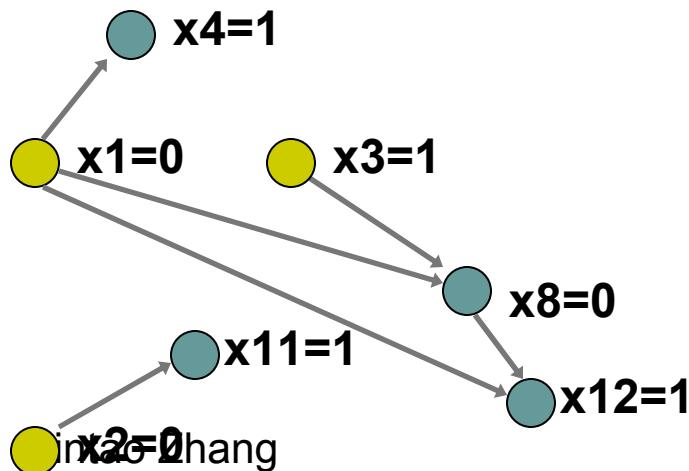
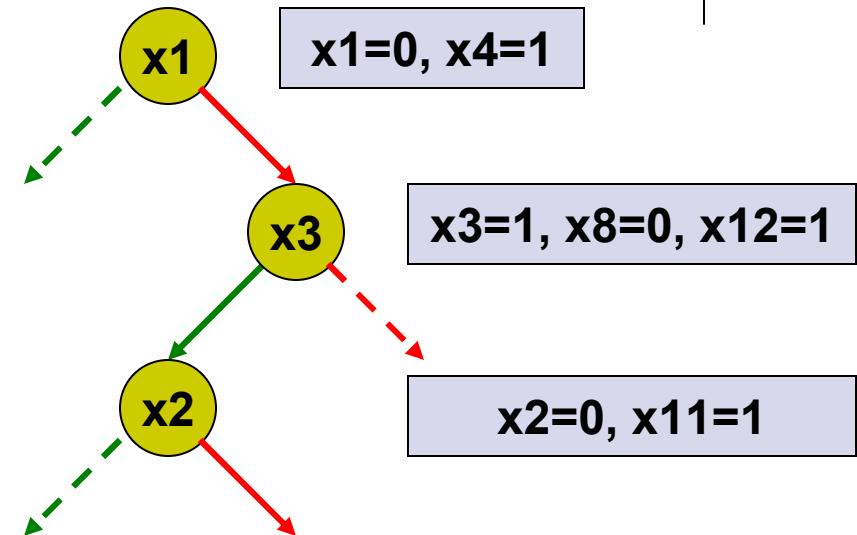
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# Conflict Driven Learning and Non-chronological Backtracking



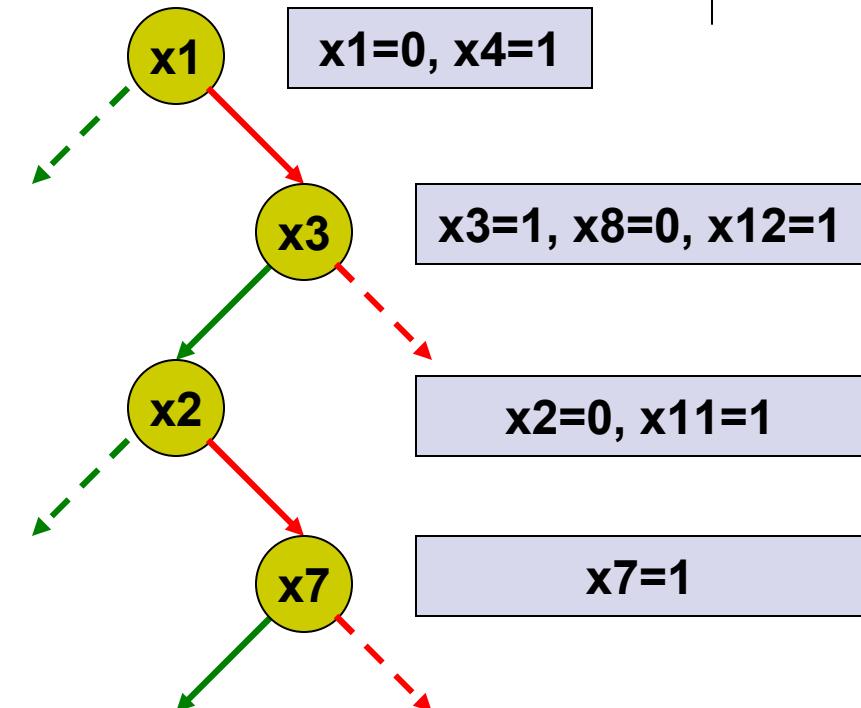
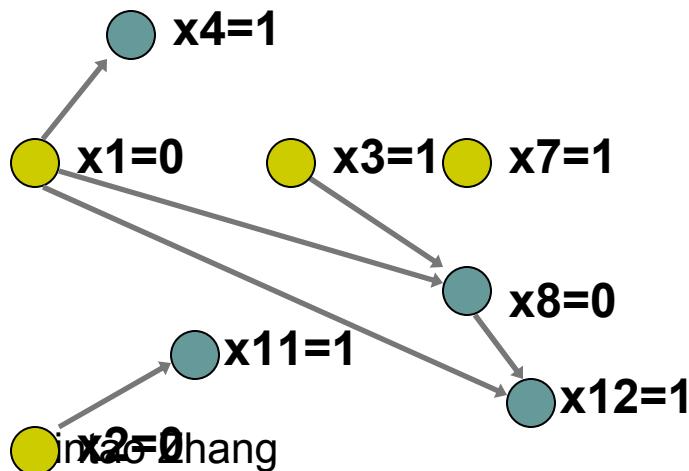
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# Conflict Driven Learning and Non-chronological Backtracking



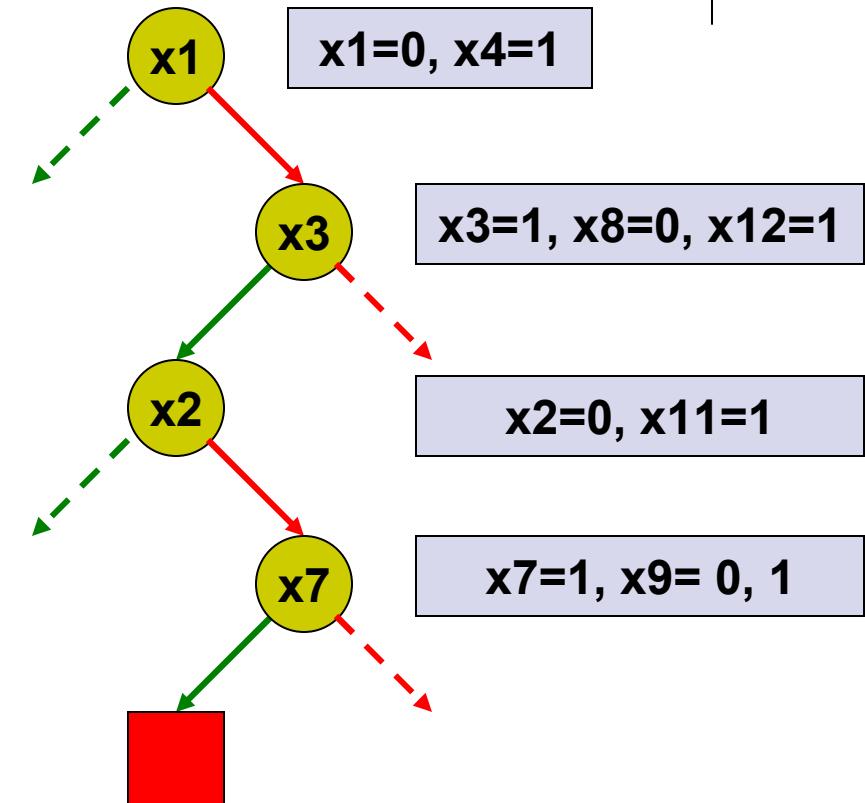
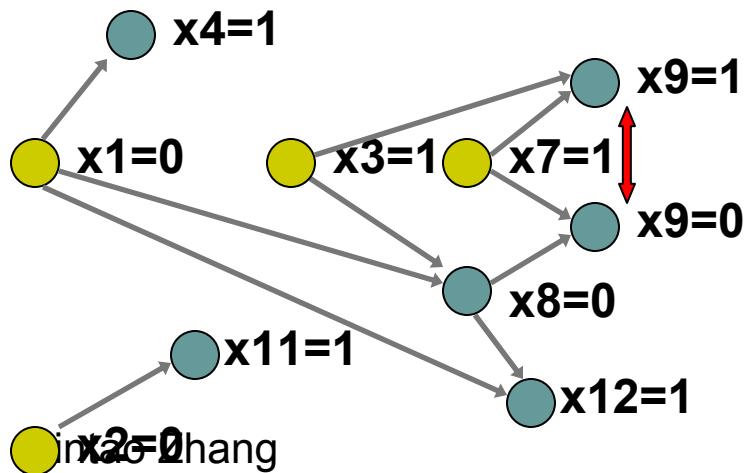
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 $x_7' + x_8 + x_9'$   
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# Conflict Driven Learning and Non-chronological Backtracking



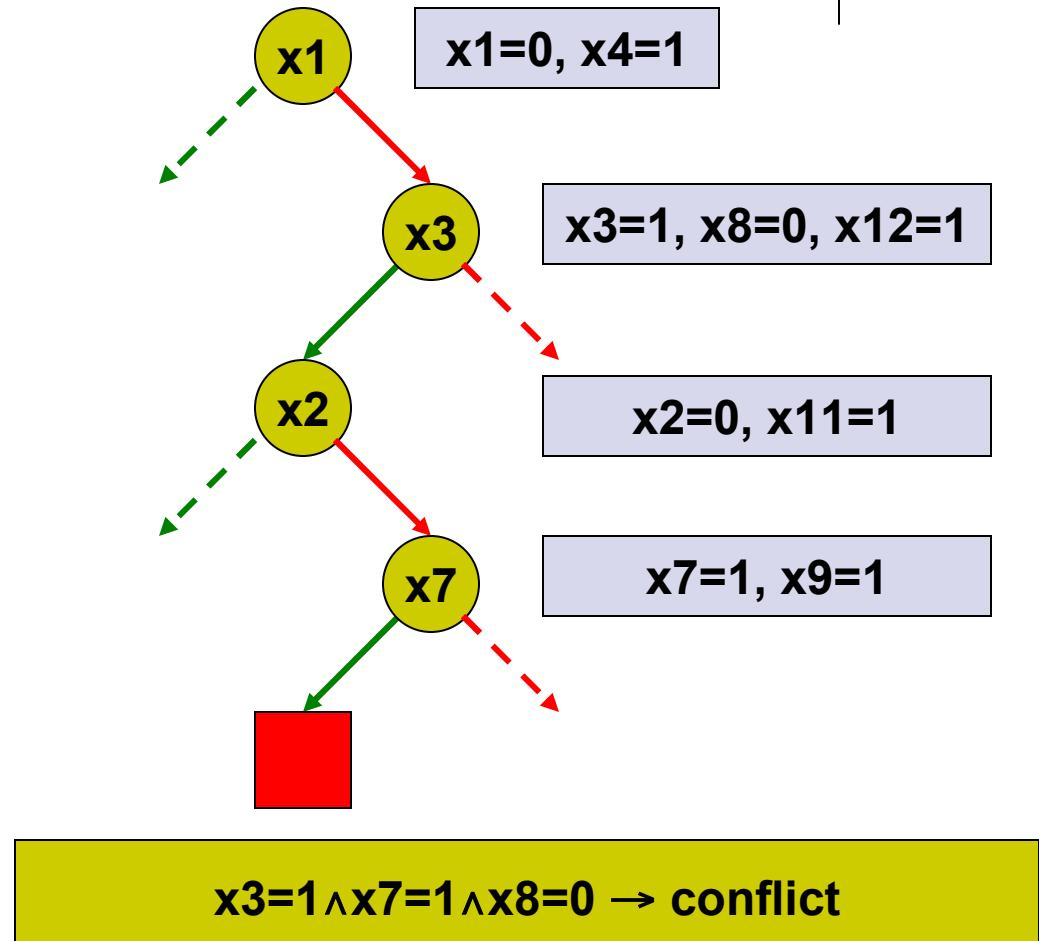
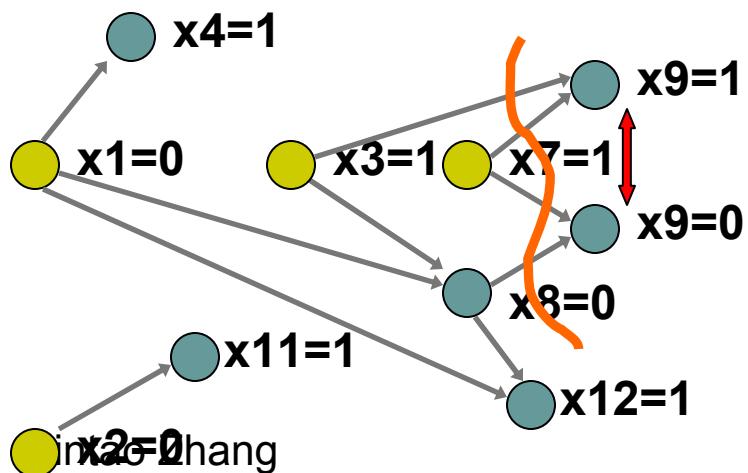
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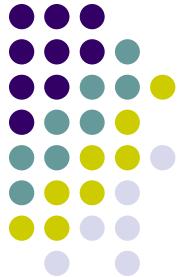


# Conflict Driven Learning and Non-chronological Backtracking



$x_1 + x_4$   
 $x_1 + x_3' + x_8'$   
 $x_1 + x_8 + x_{12}$   
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 $x_7' + x_8 + x_{9'}$   
 $x_7 + x_8 + x_{10'}$   
 $x_7 + x_{10} + x_{12'}$





# Contra-proposition:

- If  $a$  implies  $b$ , then  $b'$  implies  $a'$

$x_3=1 \wedge x_7=1 \wedge x_8=0 \rightarrow \text{conflict}$

Not conflict  $\rightarrow (x_3=1 \wedge x_7=1 \wedge x_8=0)'$

true  $\rightarrow (x_3=1 \wedge x_7=1 \wedge x_8=0)'$

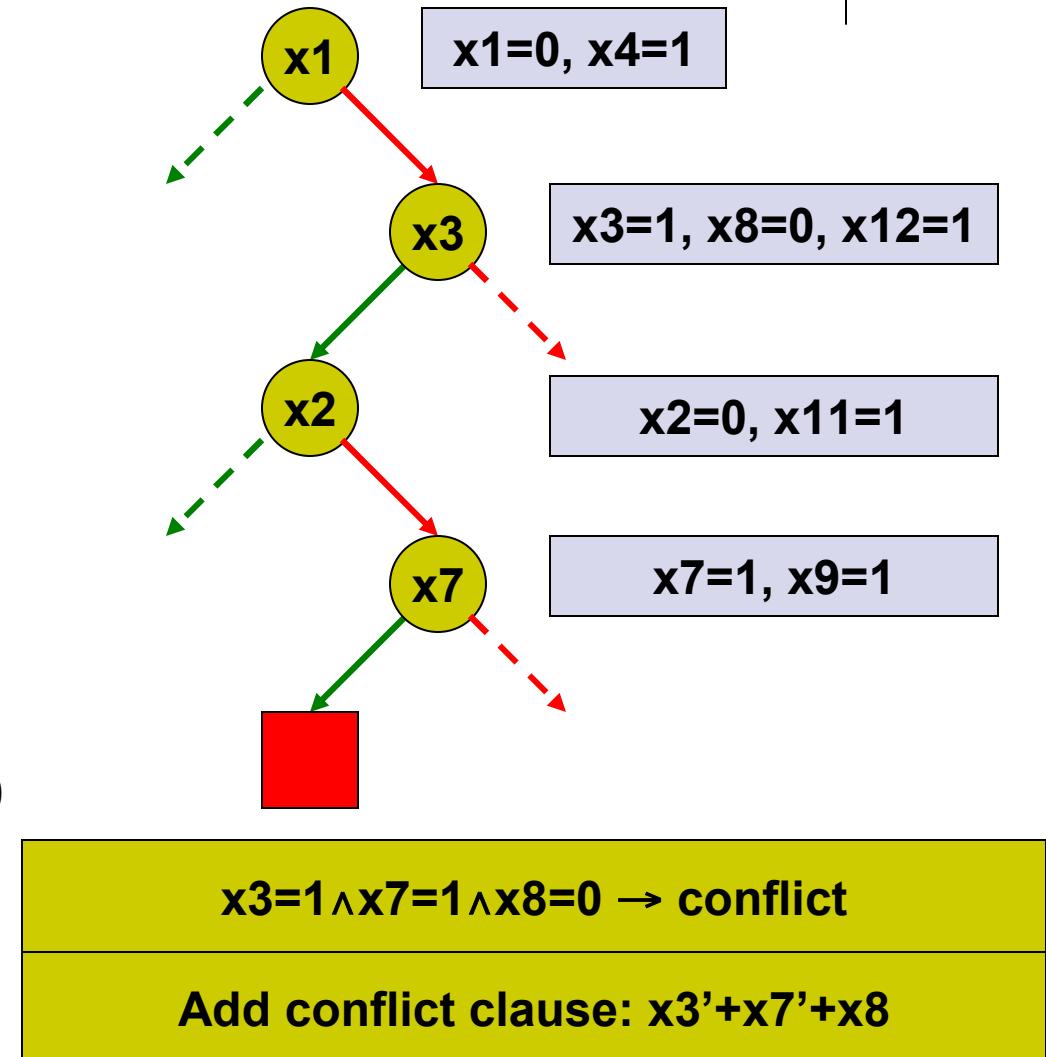
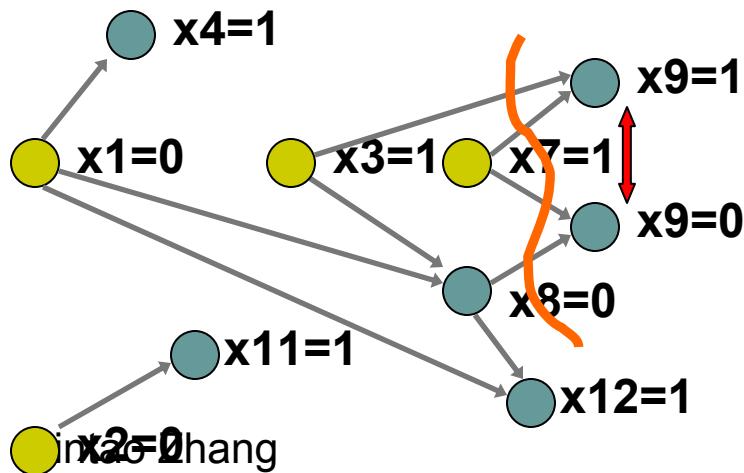
$(x_3=1 \wedge x_7=1 \wedge x_8=0)'$

$(x_3' + x_7' + x_8)$

# Conflict Driven Learning and Non-chronological Backtracking



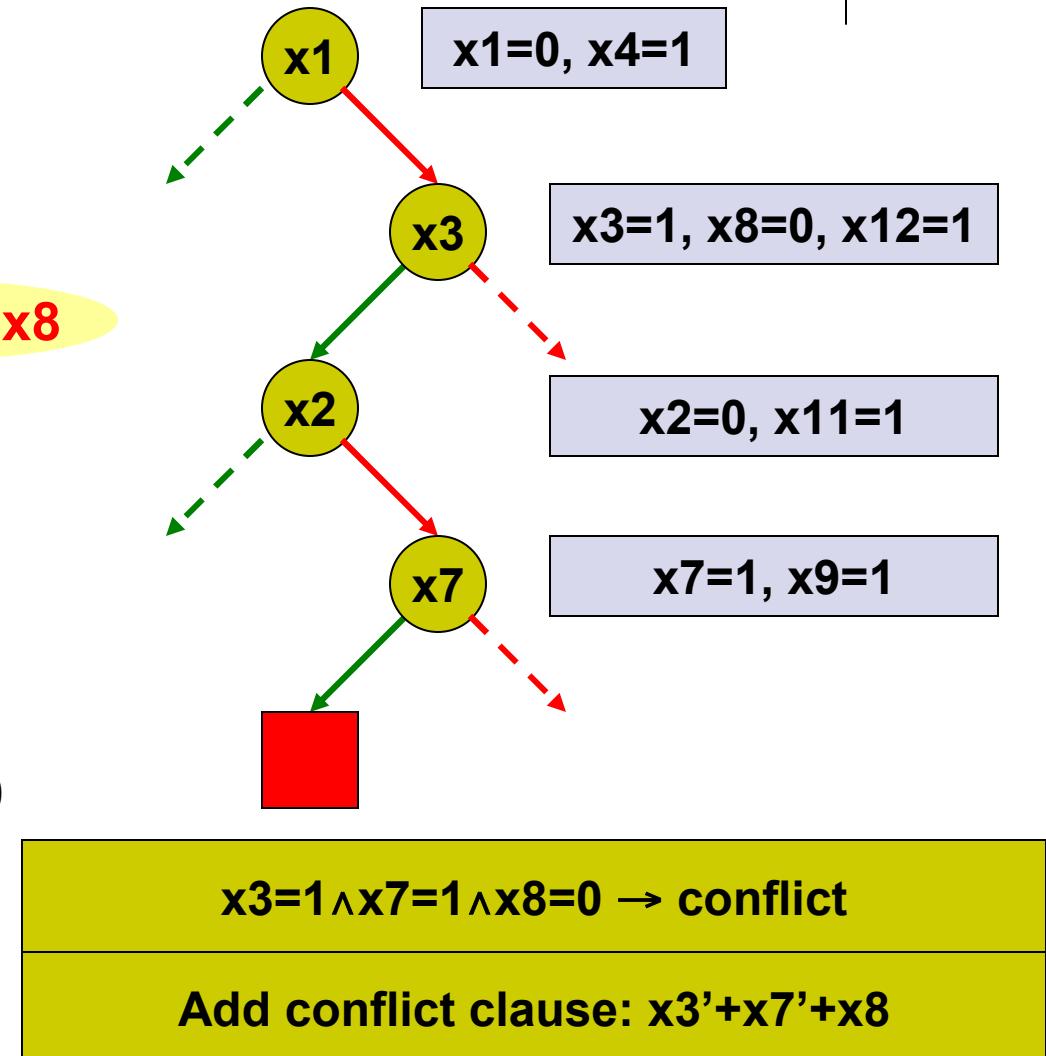
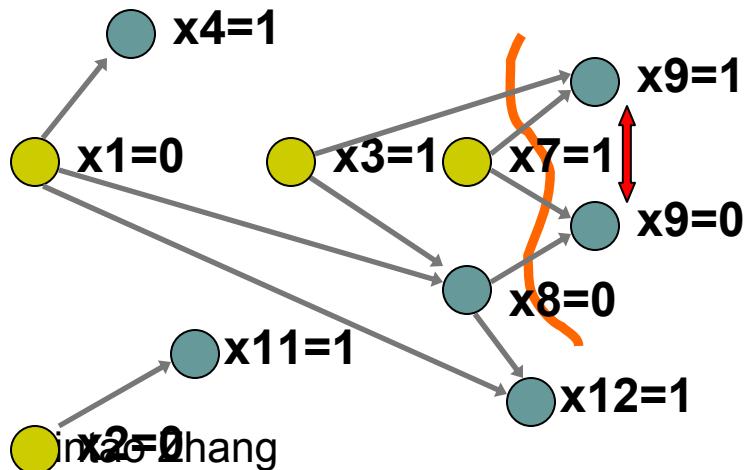
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# Conflict Driven Learning and Non-chronological Backtracking



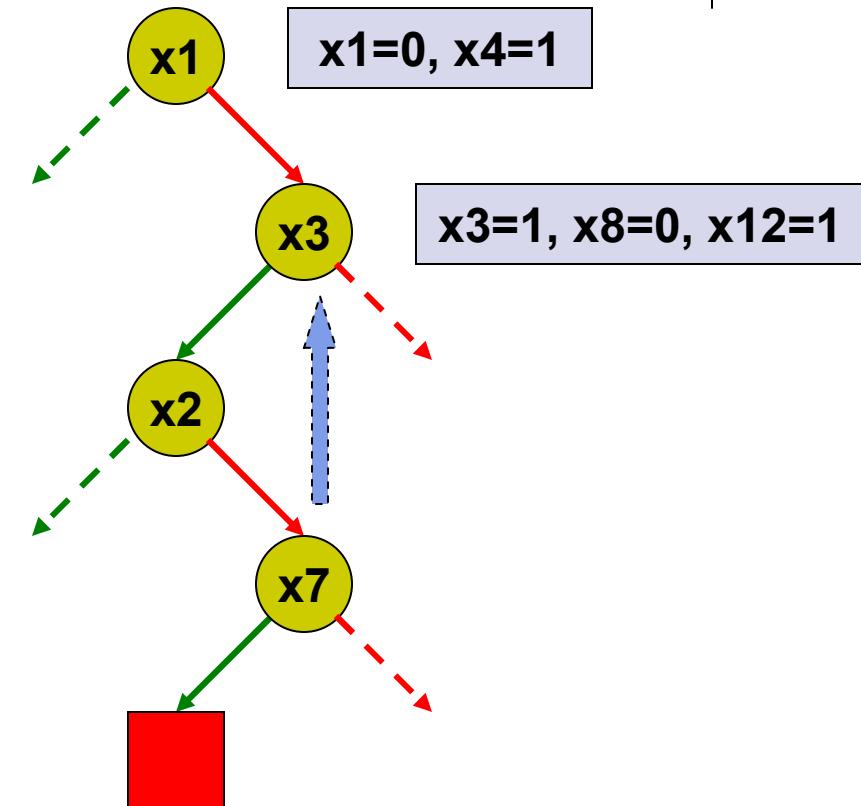
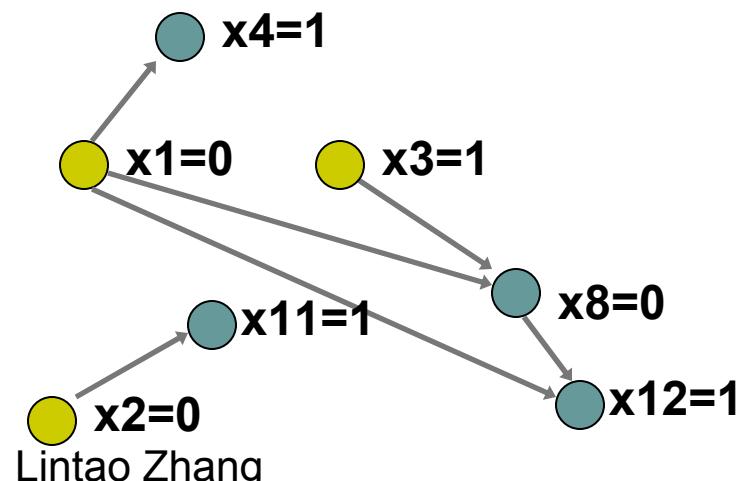
$x_1 + x_4$   
 $x_1 + x_3' + x_8'$   
 $x_1 + x_8 + x_{12}$   
 $x_2 + x_{11}$   
x<sub>7'</sub> + x<sub>3'</sub> + x<sub>9</sub>  
x<sub>7'</sub> + x<sub>8</sub> + x<sub>9'</sub>  
 $x_7 + x_8 + x_{10'}$   
 $x_7 + x_{10} + x_{12'}$



# DLL with Non-Chronological Backtracking and Learning



$$\begin{aligned} & x_1 + x_4 \\ & x_1 + x_3' + x_8' \\ & x_1 + x_8 + x_{12} \\ & x_2 + x_{11} \\ & x_7' + x_3' + x_9 \\ & x_7' + x_8 + x_9' \\ & x_7 + x_8 + x_{10}' \\ & x_7 + x_{10} + x_{12}' \\ & x_3' + x_8 + x_7' \end{aligned}$$



**Backtrack to the decision level of  $x_3=1$ :  
 $x_7 = 0$**

# DLL with Non-Chronological Backtracking and Learning



$x_1 + x_4$   
 $x_1 + x_3' + x_8'$   
 $x_1 + x_8 + x_{12}$   
 $x_2 + x_{11}$   
 $x_7' + x_3' + x_9$   
 $x_7' + x_8 + x_9'$   
 $x_7 + x_8 + x_{10}'$   
 $x_7 + x_{10} + x_{12}'$   
 $x_3' + x_8 + x_7'$

