unified model for metasearch, pooling and system evaluation

Javed Aslam Virgil Pavlu Robert Savell



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problem setup

- Set of underlying systems
 - On the same query
- User feedback
- Goal
 - Find relevant documents
 - Produce metasearch lists
 - Do partial system evaluation (distinction)
- We are looking for an adaptive approach

this talk

- Hedge algorithm
- The new model
- Loss function
- Pooling
- System evaluation
- Metasearch
- Experiments





 $\beta \in [0,1]$ N strategies (systems)

initial weights
$$\mathbf{w}^1 \in [0,1]^{\mathsf{v}}; \sum_{i=1}^{\mathsf{N}} w_i^1 = 1$$



 $\beta \in [0,1]$ N strategies (systems)

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$$\mathbf{w}^1 \in [0,1]^V; \sum_{i=1}^N w_i^1 = 1$$

LOOP for episode t=1,2,...,T



 $\beta \in [0,1] N$ strategies (systems)

initial weights $\mathbf{w}^1 \in [0,1]^V$; $\sum_{i=1}^N w_i^1 = 1$

LOOP for episode t=1.2

Choose allocation





 $\beta \in [0,1] N \text{ strategies (systems)}$

initial weights $\mathbf{w}^1 \in [0,1]^V$; $\sum_{i=1}^N w_i^1 = 1$

LOOP for episode t=1.2...

Choose allocation

Receive loss vector







 $\beta \in [0,1] N \text{ strategies (systems)}$

initial weights $\mathbf{w}^1 \in [0,1]^V$; $\sum_{i=1}^N w_i^1 = 1$

LOOP for episode t=1.2....

- Choose allocation
- Receive loss vector
- Suffer loss





$$p^t \! \prec^t$$



initial weights $\mathbf{w}^{1} \in [0,1]^{\vee}$; $\sum_{i=1}^{N} w_{i}^{1} = 1$ LOOP for episode t=1.2....T

 $\beta \in [0,1]$ N strategies (systems)

- Choose allocation
- Receive loss vector
- Suffer loss
- Update weights



$$l^t \in [0,1]^{\mathbb{N}}$$

$$p^t \rtimes^t$$

$$w_i^{t+1} = w_i^t \rtimes \beta^{l_i^t}$$





Hedge loss

$$L_{HEDGE} = \sum_{t=1}^{T} p^{t} \varkappa^{t}$$

$$\left|\sum_{i=1}^{N} w_{i}^{T+1} \leq \left(\sum_{i=1}^{N} w_{i}^{T} \stackrel{}{\xrightarrow{}} \left(1 - (1 - \beta)p^{T} \varkappa^{T}\right) \leq \dots\right.\right|$$

$$\sum_{i=1}^{N} w_i^{T+1} \leq \left(\sum_{i=1}^{N} w_i^T \frac{1}{p!} (1 - (1 - \beta) p^T \times T) \right) \leq \dots$$

$$hedge \text{ loss at episode } T = p^T \times T$$

$$\sum_{i=1}^{N} w_i^{T+1} \leq \left(\sum_{i=1}^{N} w_i^T\right) \stackrel{!}{\to} (1 - (1 - \beta) p^T \times^T) \leq \dots$$
$$\dots \leq \exp(-(1 - \beta) \sum_{t=1}^{T} p^t \times^t) \qquad hedge \text{ loss at episode } T = p^T \times^T$$





$$L_{HEDGE} \leq \frac{\ln\left(\frac{1}{\beta}\frac{1}{j}L_{SYSTEM} + \ln N\right)}{1 - \beta}$$

param
$$\beta \in [0,1]$$
; *N* systems; *T* trials
init $w_s^0 = \frac{1}{N} \quad \forall s \in \{1,2,...,N\}$;
FOR $t = 1,2,...,T$:
 $-\text{select } d_t = \underset{d \text{ not labeled}}{\max} \left[\sum_{s=1}^N w_s^{t-1} * LOSS(d,s \mid d = NR) \right]$
 $-\text{ judge } d_t$: find out $label(d_t)$
 $-\text{ apply feedback } w_s^t = w_s^{t-1} * \beta^{LOSS(d,s)}$
FACT : if we label all docs : $w_s^{final} = \beta^{C*(Z-2*TP(s))}$

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- select $d_t = \underset{d \text{ not labeled}}{\operatorname{arg max}} \left[\sum_{s=1}^N w_s^{t-1} * LOSS(d, s \mid d = NR) \right]$



pooling value(d)

- select
$$d_t = \underset{d \text{ not labeled}}{\operatorname{arg max}} \left[\sum_{s=1}^{N} w_s^{t-1} * LOSS(d, s \mid d = NR) \right]$$

pooling value(d)
 $LOSS(d, s \mid d = NR) = \left(\frac{1}{r} + \frac{1}{r+1} + \ldots + \frac{1}{Z} \right) \approx \ln \frac{Z}{r}$

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$$d_t = \underset{d \text{ not labeled}}{\operatorname{arg max}} \left[\sum_{s=1}^{N} w_s^{t-1} * LOSS(d, s \mid d = NR) \right]$$

pooling value(d)
 $LOSS(d, s \mid d = NR) = \left(\frac{1}{r} + \frac{1}{r+1} + \ldots + \frac{1}{Z} \right) \approx \ln \frac{Z}{r}$

- Naturally "want" top ranks
- If NON RELEVANT, then a NR in top ranks of the system lists
- If RELEVANT, bingo.

$$LOSS(d,s) = label(d) * \left(\frac{1}{r} + \frac{1}{r+1} + \dots + \frac{1}{Z}\right) \approx label(d) * \ln \frac{Z}{r}$$

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if d is not judged, assuming d NONRELEVANT we write :
$$LOSS(d,s \mid d = NR) = \left(\frac{1}{r} + \frac{1}{r} + \dots + \frac{1}{r}\right) \approx \ln \frac{Z}{r}$$

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r = rank of doc d in system s

Z = # of documents returned by system s

label(d) = -1 if d is RELEVANT ; +1 if d is NONRELEVANT

$$LOSS(d,s) = label(d) * \left(\frac{1}{r} + \frac{1}{r+1} + \dots + \frac{1}{Z}\right) \approx label(d) * \ln \frac{Z}{r}$$

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r = rank of doc d in system s

Z = # of documents returned by system s

label(d) = -1 if d is RELEVANT ; +1 if d is NONRELEVANT

TP(s) = total precision of s = average precizion at all ranks FACT : $\sum_{all \ docs} LOSS(d, s) = C * (Z - 2 * TP(s))$

$$LOSS(d,s) = label(d) * \left(\frac{1}{r} + \frac{1}{r+1} + \dots + \frac{1}{Z}\right) \approx label(d) * \ln \frac{Z}{r}$$

if *d* is not judged, assuming *d* NONRELEVANT we write :

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label(d) = -1 if d is RELEVANT ; +1 if d is NONRELEVANT

TP(s) = total precision of s = average precizion at all ranks

FACT:
$$\sum_{\text{all docs}} LOSS(d, s) = C * (Z - 2 * \underline{TP(s)})$$

"total" precizion

- Average the precision at ALL ranks
 - Normalize so ideal system gets TP=1
- math is more simple
 - we still work on it though
- Bad with "long tails"

pooling - comparison with Cormack



12

[partial] system evaluation – howto

[partial] system evaluation – howto

Before the next episode

- Assume all docs not judged (so many ?) to be NR
- Compute AvegPrecision for every system
- For comparison with depth-pooling we use average number of pools (over queries)
- Two situations
 - One (or few) very good systems use small β
 - No singles

metasearch – howto

Before the next episode

Compute "pooling value"

for each doc

$$\left[\sum_{s=1}^{N} w_s^{t-1} * LOSS(d, s \mid d = NR)\right]$$

 Instead of "select the top doc" for pooling do "select the top 1000 doc" for metasearch

- In fact almost 1000 docs already pooled are automatically in top of metasearch list
 - Fair both ways



TREC

- ~100 systems
- 50 queries each competition
- Use TREC qrels as user feedback
 - incomplete feedback



TREC

- ~100 systems
- 50 queries each competition
- Use TREC qrels as user feedback
 - incomplete feedback

Goal

- Find relevant documents
- Produce metasearch lists
- Do partial system evaluation (distinction)











17







experiments - relevant docs found



metasearch - no feedback (yet)

TREC	MNZ	COND	Hedge-0	% MNZ	% COND
3	0.423	0.403	0.418	-0.012	+0.037
5	0.294	0.307	0.309	+0.051	+0.006
6	0.341	0.315	0.345	+0.012	+0.095
7	0.320	0.308	0.323	+0.009	+0.049
8	0.350	0.343	0.352	+.0014	+0.026

metasearch - no feedback (yet)

TREC	MNZ	COND	Hedge-0	% MNZ	% COND
3	0.423	0.403	0.418	-0.012	+0.037
5	0.294	0.307	0.309	+0.051	+0.006
6	0.341	0.315	0.345	+0.012	+0.095
7	0.320	0.308	0.323	+0.009	+0.049
8	0.350	0.343	0.352	+.0014	+0.026

metasearch - no feedback (yet)



experiments - metasearch



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experiments - metasearch



<u>conclusion</u>

- A powerful machine learning approach
 - Hedge = AdaBoost core
- Works [usually] better than anything else we've seen
- True, it uses feedback
 - But without feedback there are provable limitations
- It is missing a rigorous analysis
 - We are not very far away with that
 - Need a model assumption

differentiate (clasify) the search engines

RANK	SYS1	SYS2	SYS3	SYS129
1	8	111	2	1013
2	2	2	821	466
3	1	4	134	84
4	134	7284	9725	5
5	14215	769	106	2038
6	24	84	439	4
	10 A			
	8			
1000	8521	11003	84	3967
84=REL	EVANT	821	=NON RELEVANT	

TREC8 competition

129 search engines (systems)

 \sim 1000 docs returned /query

TR	FC	Fval	luation	DFPTH	100
					TOO

-judge top 100 docs (each sys); use MAP to rank systems

READWARE2 0.469245750504929 orcl99man 0.413044919590457 iit99ma1 0.410361163615777 READWARE 0.400062083026587 CL99XTopt 0.376552749280167 CL99XT 0.373043274256318 CL99SDopt1 0.368216861184875 CL99SD 0.353710984082113 CL99SDopt2 0.351955930155801 8manexT3D1N0 0.334646677365296 0.330293582307575 pir9Aatd ok8alx 0.324046294809153 0.323972048518037 Flab8atdn MITSLStdn 0.32268558626124 pir9Attd 0.320651128642633 ok8amxc 0.31687789001205 att99atde 0.316549112790725 Flab8ax 0.316270864248346 ap18p 0.315425192468865 ap18c221 0.314991172213836 UniNET8Lq 0.313842898958697 ap18c621 0.312624929467966 fub99tt 0.310608000938879 fub99tf 0.309923242027166 att99atdc 0.308935872304471 fub99a 0.306768289435422 GE8MTD2 0.306560441783452 fub99td 0.306376965574526 pir9At0 0.306288595615414 pir9Atd0 0.302238406288713

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the big picture



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