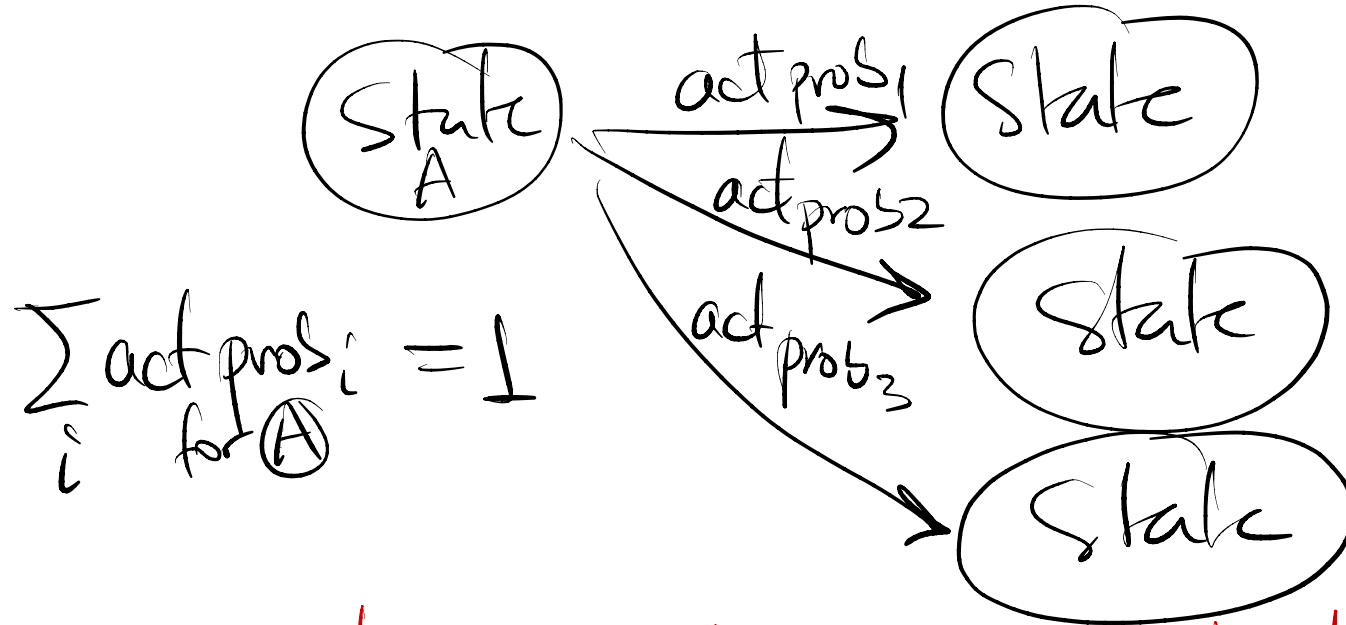


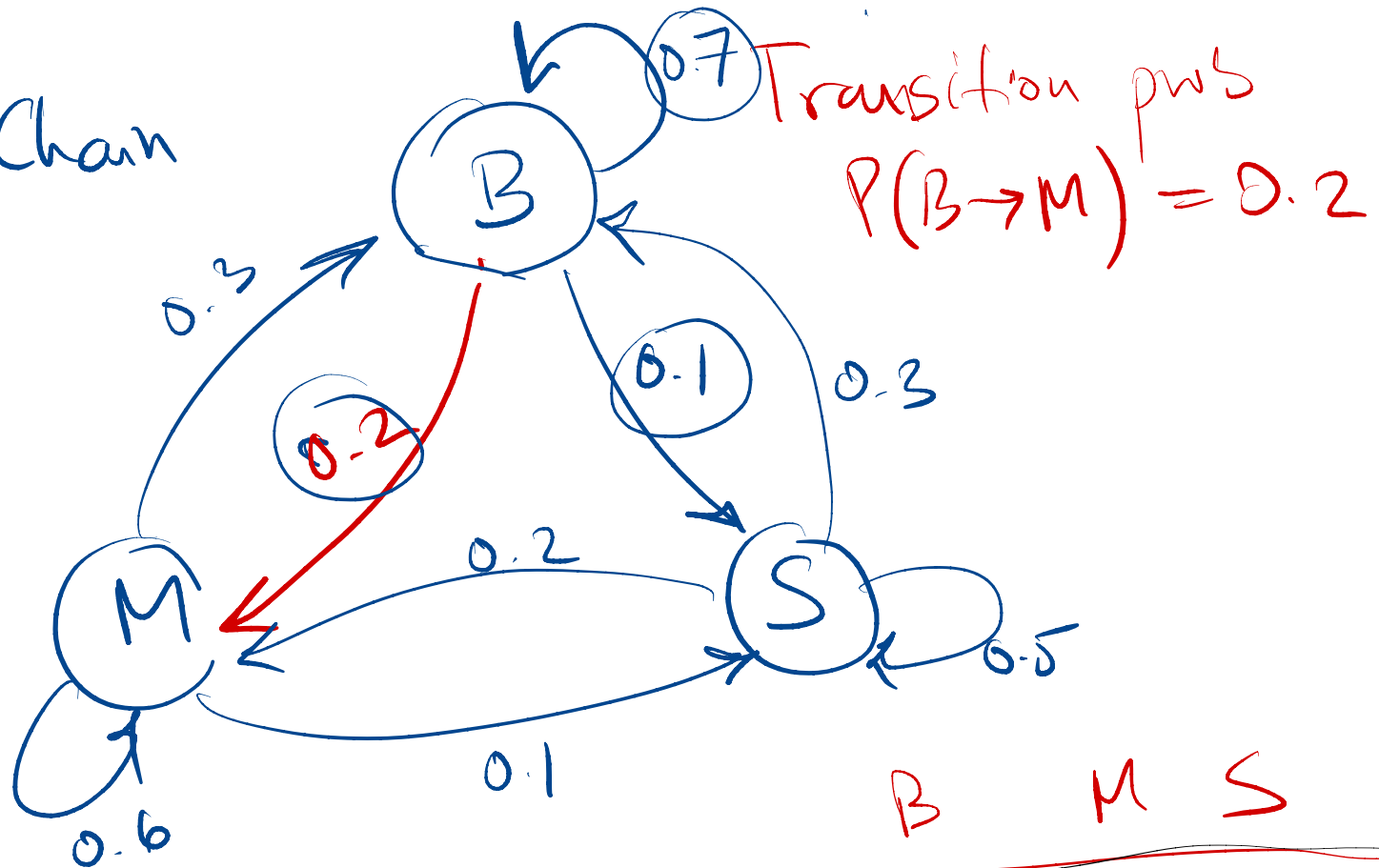
Markov Chains : transition state $\xrightarrow{\text{action}}$ state



memory less : the prob (destination state) depends only on current state (no past)

Markov Example. Boston population going to eat out every day; restaurants B, M, S.

Markov Chain



Trans probs matrix

$$P = \begin{matrix} & \begin{matrix} B & M & S \end{matrix} \\ \begin{matrix} B \\ M \\ S \end{matrix} & \begin{bmatrix} .7 & .2 & .1 \\ .3 & .6 & .1 \\ .3 & .2 & .5 \end{bmatrix} \end{matrix}$$

distribution of agents/population in day i
at restaurants B, M, S

$$\pi_i^B = \frac{1}{3}$$

B
1/3

M
1/3

S
1/3

$$\pi_{i+1}$$



$$\pi_i^B \cdot P(B \rightarrow B) + \pi_i^M \cdot P(M \rightarrow B) + \pi_i^S \cdot P(S \rightarrow B)$$

$$\pi_i^B \cdot P(B \rightarrow S) + \pi_i^M \cdot P(M \rightarrow S) + \pi_i^S \cdot P(S \rightarrow S)$$

$$\pi_{i+1}^B = \pi_{i+1}^B \cdot 7 + \pi_{i+1}^M \cdot 3 + \pi_{i+1}^S \cdot 3$$

$$\pi_{i+1}^{1 \times n} = \pi_i^{1 \times n} \cdot P^{n \times n}$$

Math $\Rightarrow \pi^* \cdot 1 = \pi^* \cdot P \Rightarrow \pi^* = \text{eigen vect}$
convergence
dist
STATIONARY
(P)
eigen val =
1

π^* = "importance / popularity"
of each restaurant B, M, S

unless
rare (weird) situation (periodicity) $\Rightarrow \exists \pi^*$

dist $u^* = \bar{u}^* \cdot p$
 B, M, S

$u^*_B = B$; $u^*_M = M$; $u^*_S = S$

$B + M + S = 1$

$-B + 2M - S = 0$ ← $\times 5$

$-B - M + 5S = 0$ ← $\times 10$

$3M = 1$
 $6S = 1$

$\Rightarrow M = 1/3$
 $S = 1/6$

$B = .7B + 2M + .3S$

$M = .2B + .6M + .2S$

$S = .1B + .1M + .5S$

incomplete rank

$-.2B + .4M - .2S = 0$

$-.1B - .1M + .5S = 0$

$\Rightarrow B = 1/2$

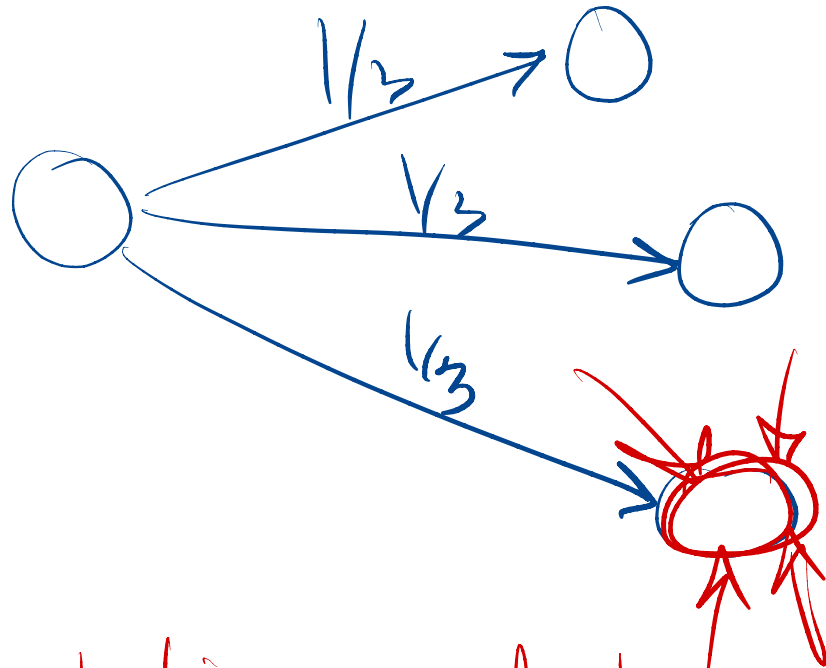
Page Rank

States = web pages.

actions/edges = links.

pros = uniform
(default)

no-unif
(by design)



not realistic for web browsing

PageRank = stationary dist
(same Markov chain)

• stuck \Rightarrow teleportation (still easy math) $\left. \begin{array}{l} \text{transition } 80\% \\ \text{teleport random } 15\% \end{array} \right\}$

• at scale different math method
(not eigenvalue)

instead manual/iterative convergence

$$\pi_0 = \text{init}$$

$$\pi_{i+1} = \pi_i \cdot P \quad \text{until convergence.}$$