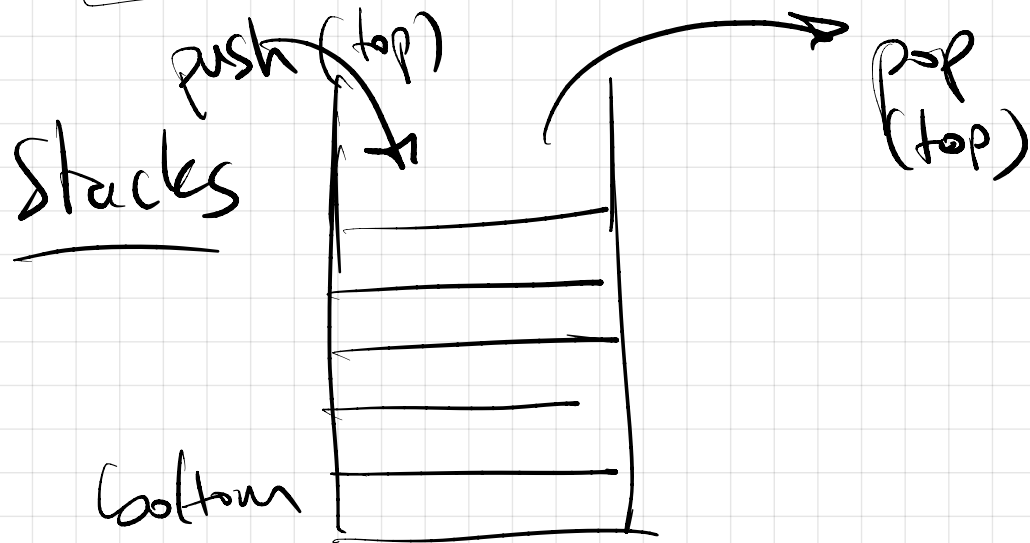
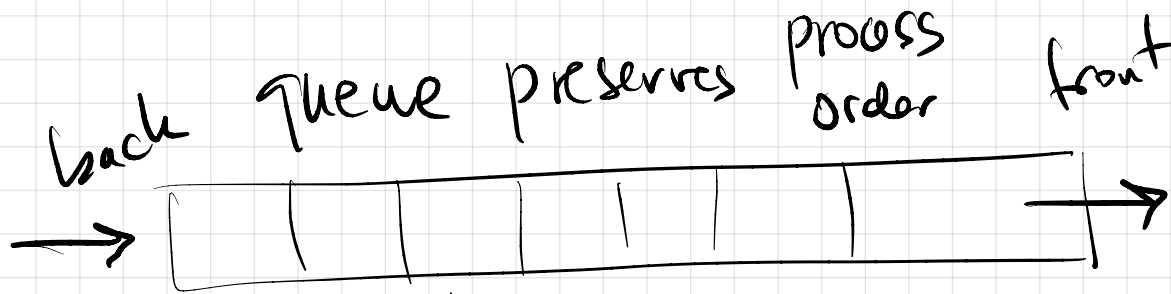
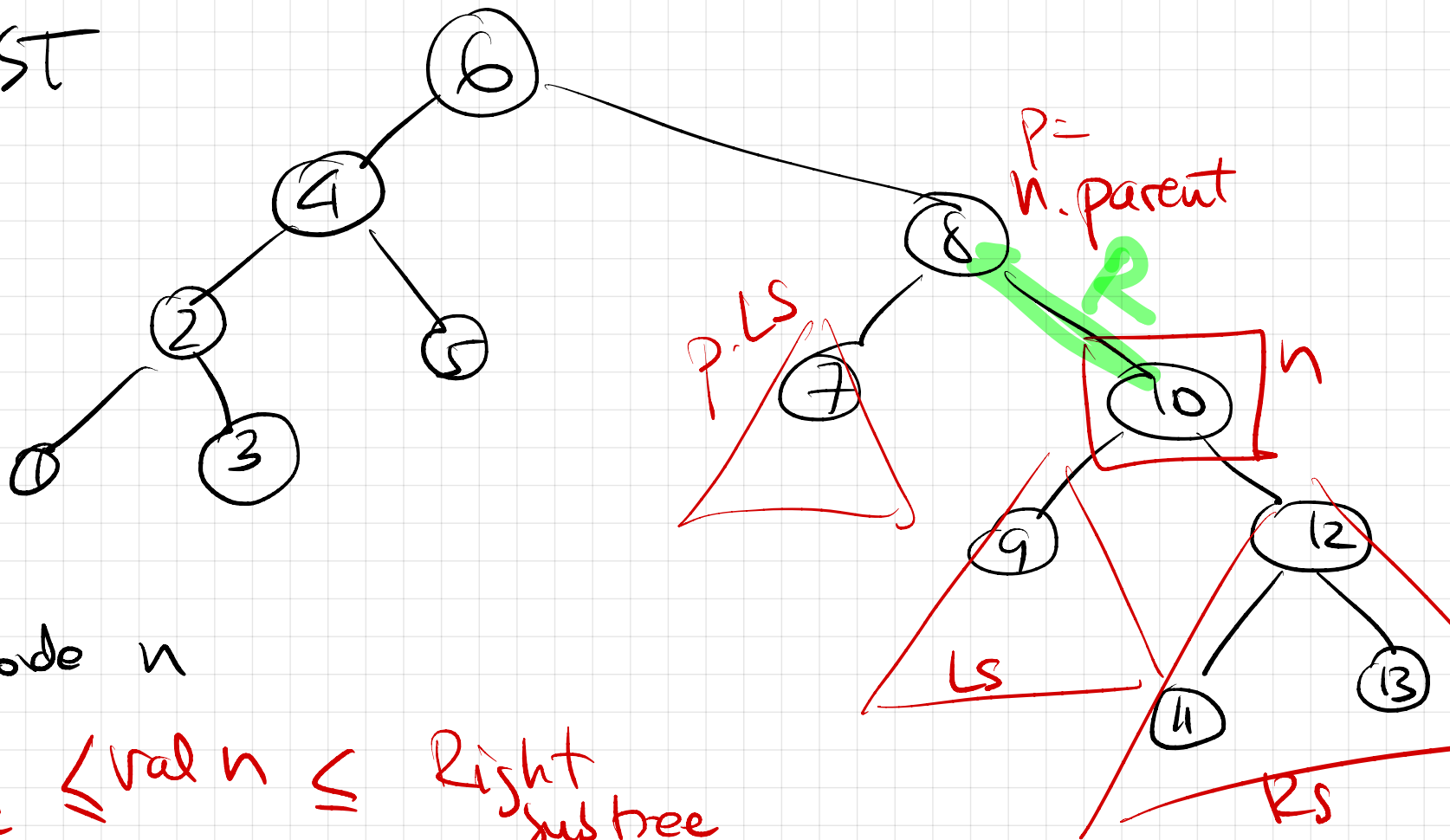


Data structures :

lists	arrays	trees	queues	stacks
- single linked - double linked	1D 2D	binary + BST	FIFO - enqueue - dequeue	LIFO - push - pop



BST



node n

Left subtree \leq val n \leq Right subtree

n = ? n.parent.Left? **NO**

? n.parent.Right? **YES**

P.LS < P < n-subtree

P < n.LS

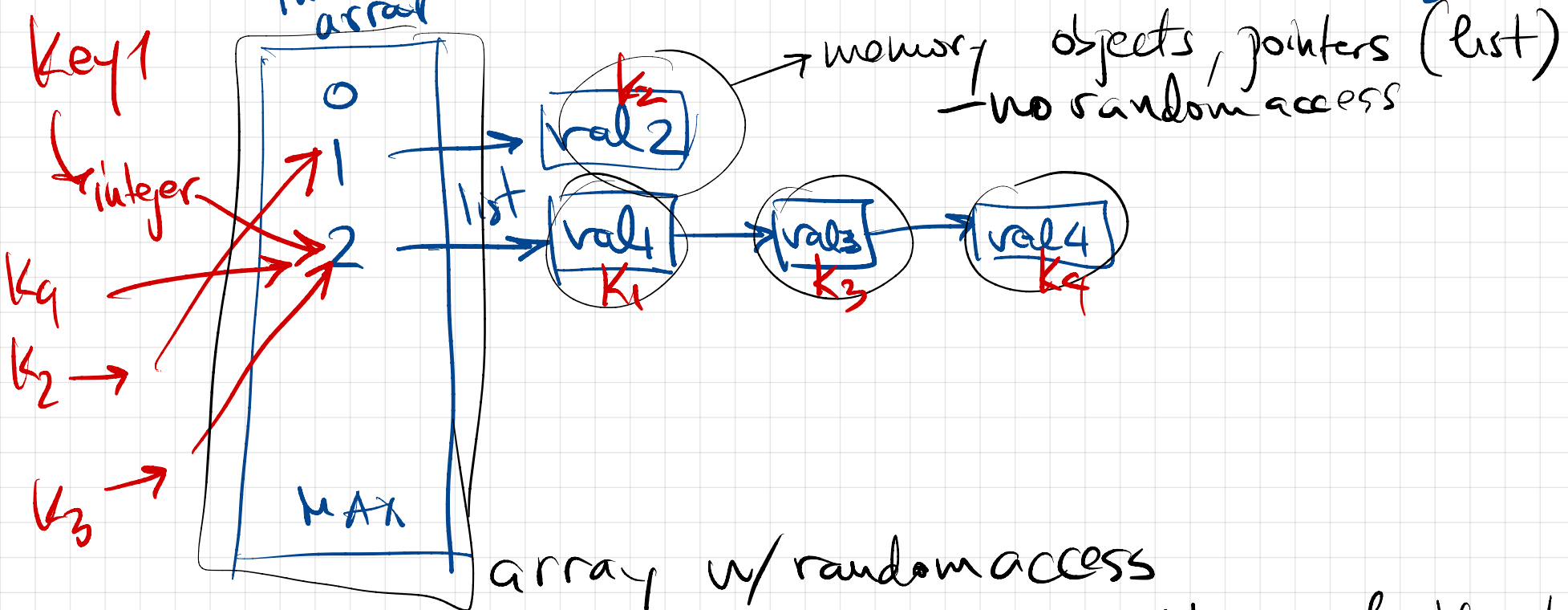
P.LS \leq n
brother, cousins

Adv Data structures: Hash Tables, B trees, Skiplists, Fib heap

Hashes (hash tables)

data = (key, val) pairs $\boxed{\text{val}}$ = val in hashes

key = memory object $\xrightarrow{\text{(large?)}}$ integer number $\xrightarrow{\text{hash function}}$ index \in Range [0: MAX]



array w/ random access
array[index] = memory address of the list of values

- want hash function to be fast

- price = some collisions

n keys
1,000,000

$m = \text{MAX Range size } 100$

want collision list $\approx \frac{n}{m} \approx \frac{1,000,000}{100} \approx 10,000$
avg $\alpha = E[\text{list size}]$

SIMPLE UNIFORM HASHING

likely to be hashed into

any key k equally
any of $0 : \text{MAX}$

$$\text{prob}[\text{hash}(k) = i] = \frac{1}{\text{MAX}} = \frac{1}{m}$$

• unsuccessful search
(key not found)

$$\Theta(1 + \alpha) \approx \Theta(\alpha)$$

usual $\alpha \gg 1$

• Success search
(key found)

$$\Theta(1 + \alpha) \approx \Theta(\alpha)$$

proof
(idea)

• un success (key not found)

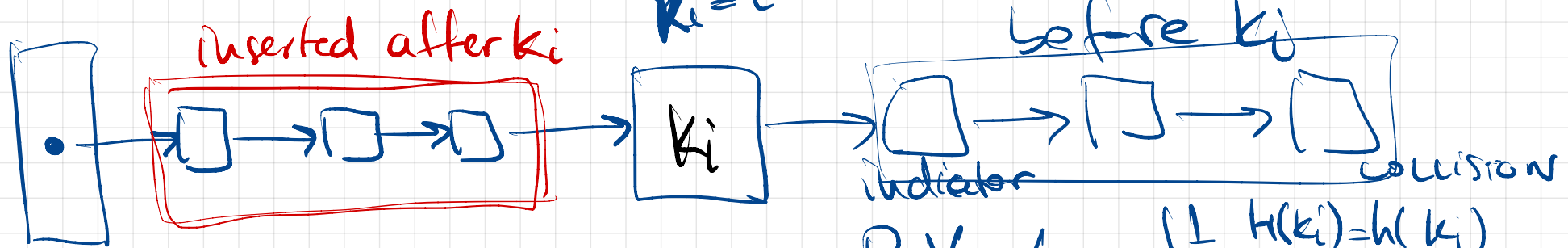
$$E[\text{time}] = E[\text{search in list } \text{hash}(k)=i]$$

$$= E[\text{size of list } i] = \alpha = \frac{n}{m}$$

• success $k \in \text{Hash}$

$k_i = l^{\text{th}}$ inserted key

k_i, k_j keys



$$E[X_{ij}] = \text{prob}(X_{ij} = 1) = \text{prob}$$

$$\text{later key gets hashed in list (first key)} = \frac{1}{m}$$

$$\text{R.V. } X_{ij} = \begin{cases} 1 & h(k_i) = h(k_j) \\ 0 & h(k_i) \neq h(k_j) \end{cases}$$

$$\text{Search time} = E \left[\frac{1}{n} \sum_{i=1}^n \left(1 + \sum_{j=i+1}^n x_{ij} \right) \right]$$

Keys inserted after k_i colliding with k_i

$$= \frac{1}{n} \sum_{i=1}^n \left(1 + \sum_{j=i+1}^n E[x_{ij}] \right) = \frac{1}{n} \sum_{i=1}^n \left(1 + \sum_{j=i+1}^n \frac{1}{m} \right)$$

Search time for k_i

$n-i$ items

$$= 1 + \frac{1}{nm} \sum_{i=1}^n (n-i)$$

$0 + 1 + 2 + \dots + n-1$

$$= 1 + \frac{1}{nm} \frac{(n-1)n}{2} = \Theta \left(1 + \frac{n}{m} \right) = \Theta(1 + \alpha)$$

Hash functions.

$$h(\text{key}) = \text{index} \in [0: \text{MAX}]$$

Key $\xrightarrow{?}$ integer

heuristic

HW8

Key = word

(very large)
integer
*

$h \rightarrow$ index ex 701
MAX = far from 2^p

basic $h(x) = x \bmod \text{MAX} \in [0: \text{MAX}-1]$

remains

MAX

$$h(x) = \lfloor \text{fractional}(x \cdot A) \rfloor$$

$$\text{fractional}(z) = z - \text{integer}(z)$$

power of 2

$$A = \text{fractional of } \frac{S}{2^w}$$

w = bits required by MAX

Hash-function s - universal - set

- adversary: chooses many keys $h(k) = \text{same}$
because $h = \text{fixed}$. \Rightarrow long list of u .

Solution: $S = \{ \text{hash functions} \}$ universal

• every hash created $\Rightarrow h \in S$ picked at random.

$|S| = \text{size of the set of functions}$

every 2 keys k, e

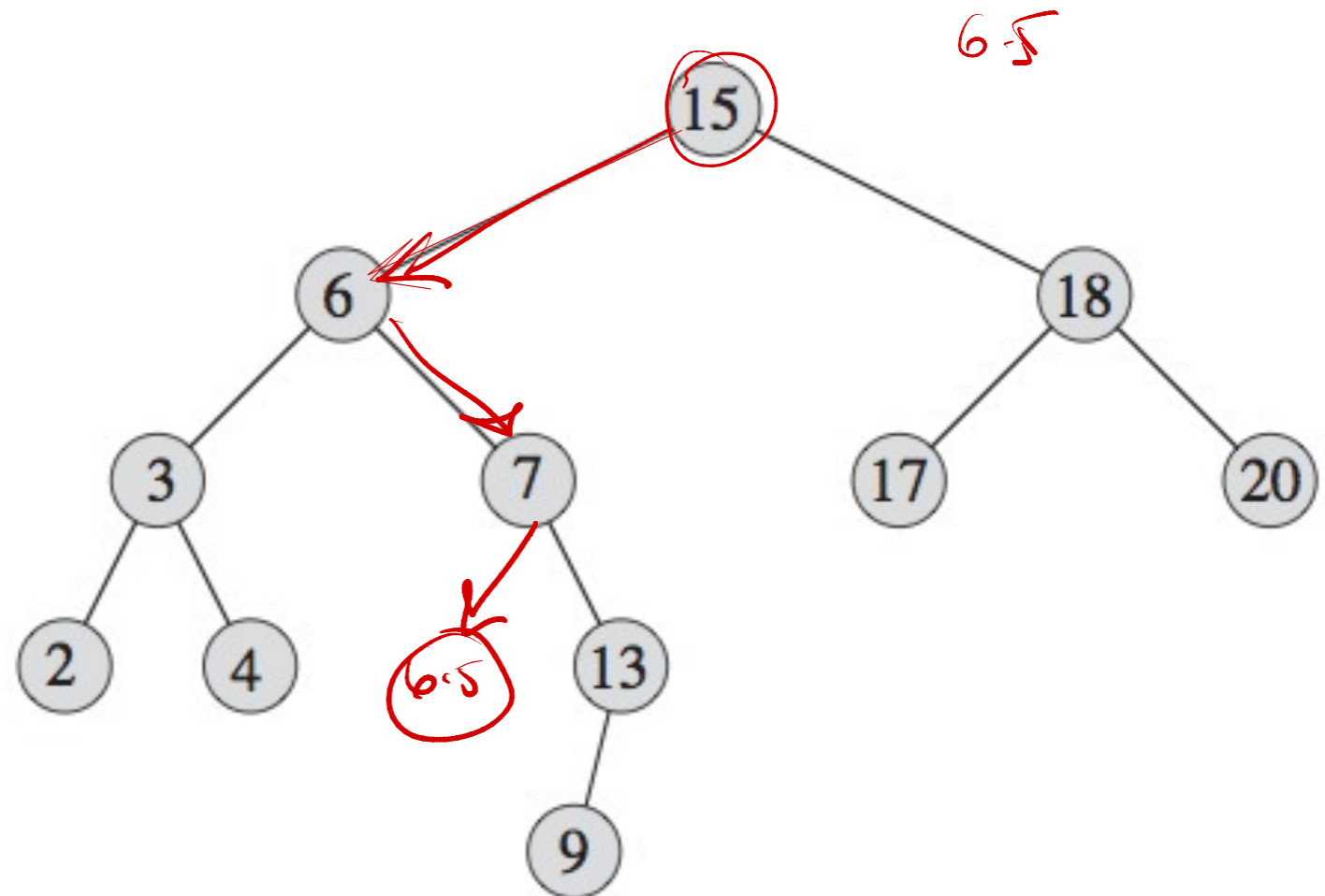
$$\{ h \in S \mid h(k) = h(e) \} \approx \frac{|S|}{\text{MAX}}$$

UNIVERSAL

(f) Adversary cannot create long list of collisions.

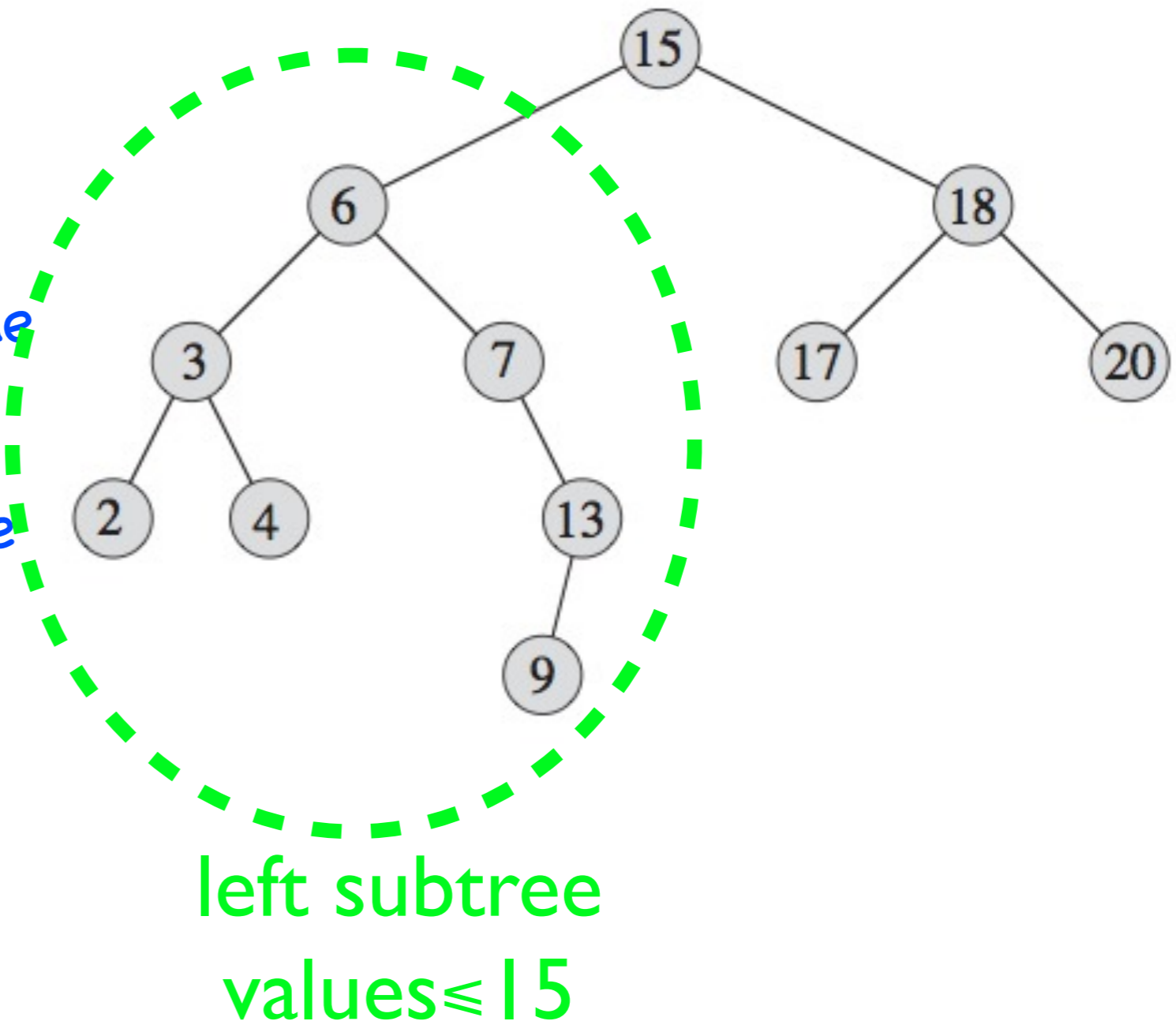
Binary Search Trees - Recap

- each node has at most two children
- any node value is
 - not smaller than any value in the left subtree
 - not larger than any value in the right subtree
 - h = height of tree
- Operations:
 - search, min, max, successor, predecessor, insert, delete
 - runtime $O(h)$



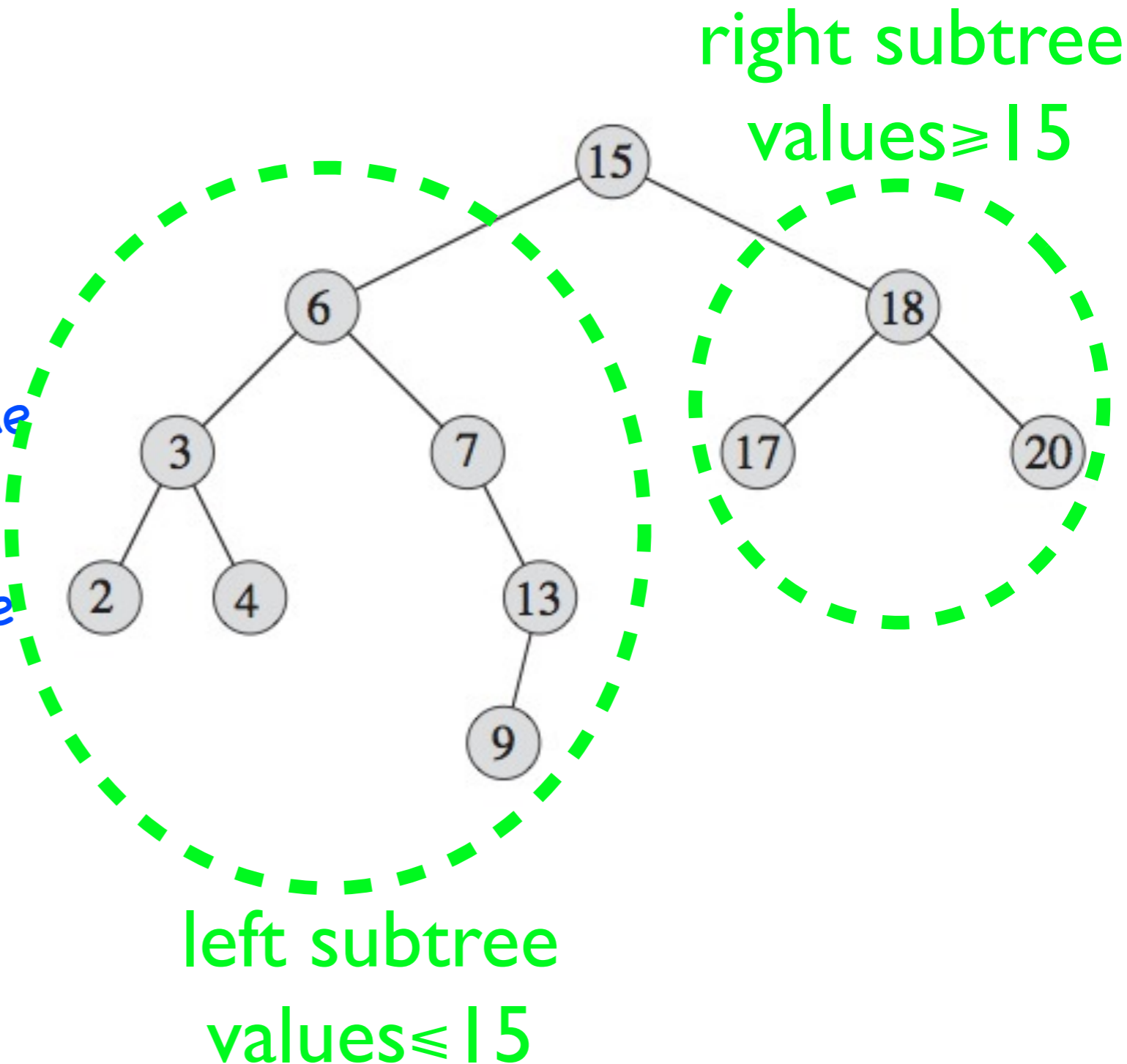
Binary Search Trees - Recap

- each node has at most two children
- any node value is
 - not smaller than any value in the left subtree
 - not larger than any value in the right subtree
 - h = height of tree
- Operations:
 - search, min, max, successor, predecessor, insert, delete
 - runtime $O(h)$

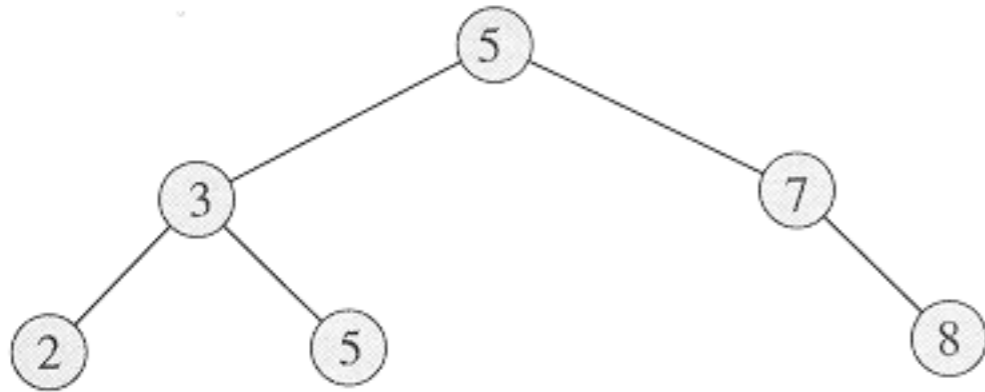


Binary Search Trees - Recap

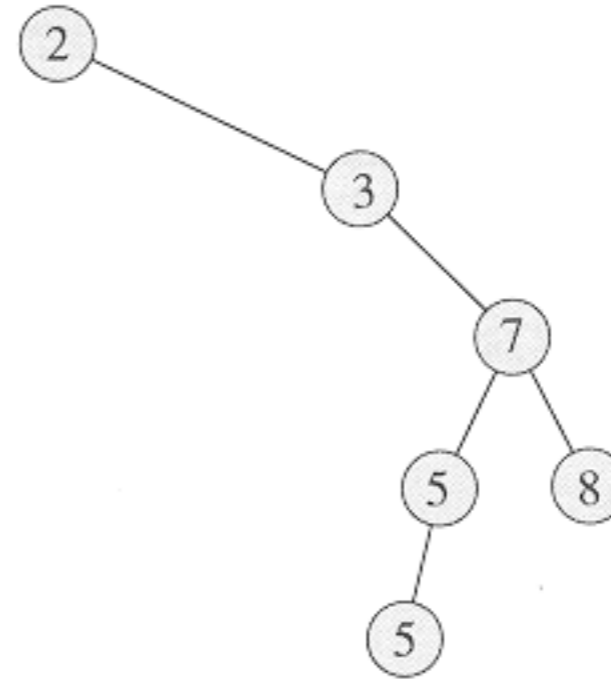
- each node has at most two children
- any node value is
 - not smaller than any value in the left subtree
 - not larger than any value in the right subtree
 - h = height of tree
- Operations:
 - search, min, max, successor, predecessor, insert, delete
 - runtime $O(h)$



Balanced Trees



(a)



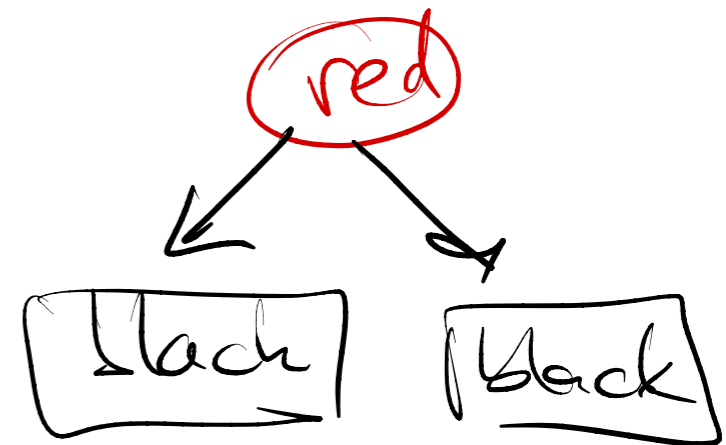
(b)

- a) balanced tree: depth is about $\log(n)$ – logarithmic
- b) unbalanced tree : depth is about n – linear

Red-Black Trees

- binary search tree
- want to enforce **balancing** of the tree
 - height logarithmic in n =number of nodes in the tree
 - height = longest path root→leaf

- extra: each node stores a color
 - color can be either red or black
 - color can change during operations

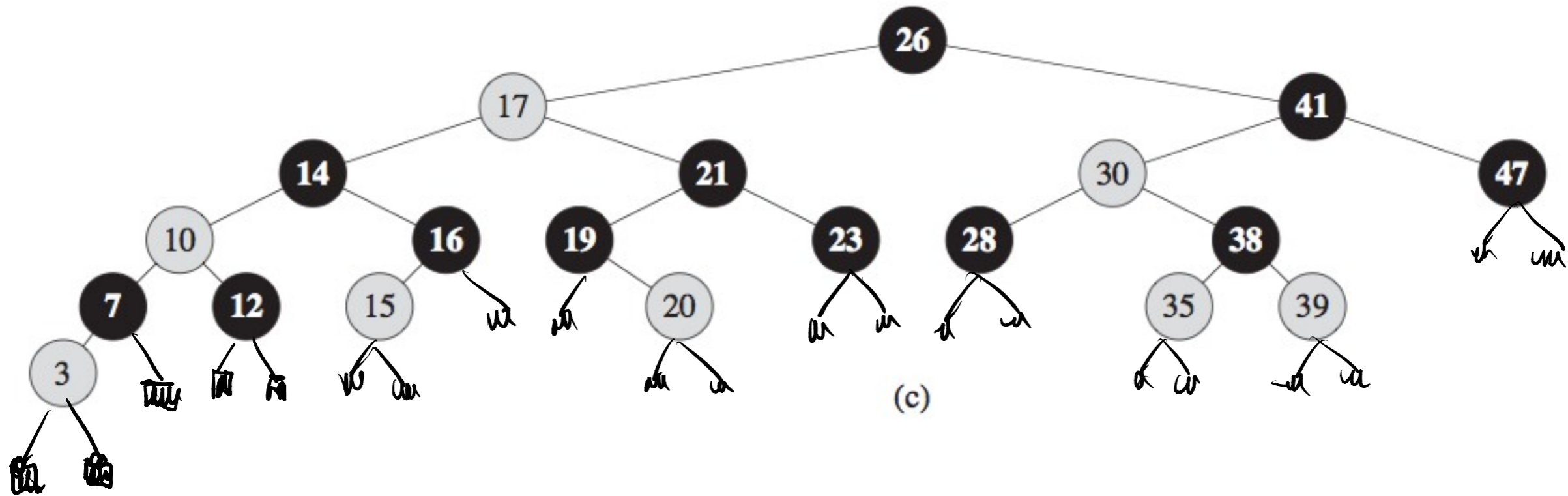


- **red-black properties**

- root is black
- leafs (terminals) are black
- if a node is red, then both children are black
- for any given node, all paths to leaves (node→leaf) have the same number of black nodes

⇒ balanced on black nodes.

Red-Black Trees



- Theorem: a red-black tree with n nodes has height at most $2 \cdot \log(n+1)$
 - or logarithmic height
 - thus enforcing the balancing of the tree
 - and so the all operations can be implemented in $O(\log n)$ time.

Tree operations

- insert, delete - need to account for colors
 - rest of the lecture: insert and delete in red-black trees
- search, min, max, successor, predecessor - same as for regular binary search trees

Red-Black Trees - Rotation

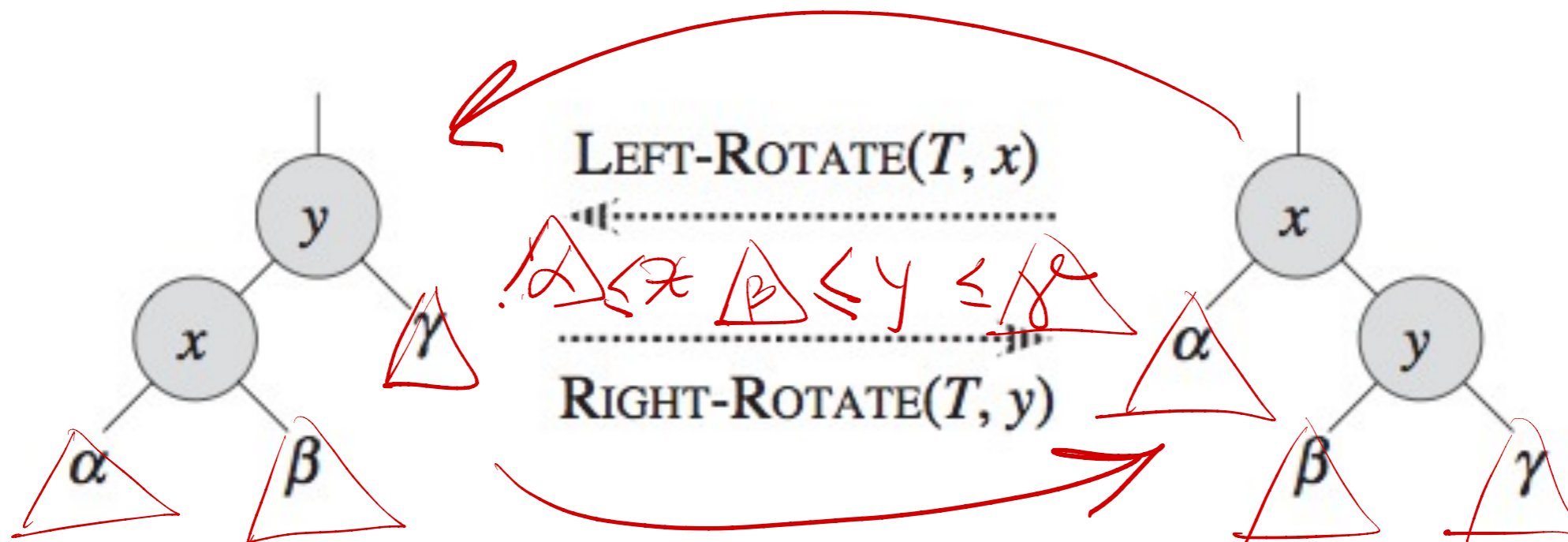
- **Rotation** is a utility operation that facilitates maintenance of red-black properties

- during insert and delete, the tree might temporarily violate the red-black properties
- using rotation we can fix the tree so it satisfies red-black.

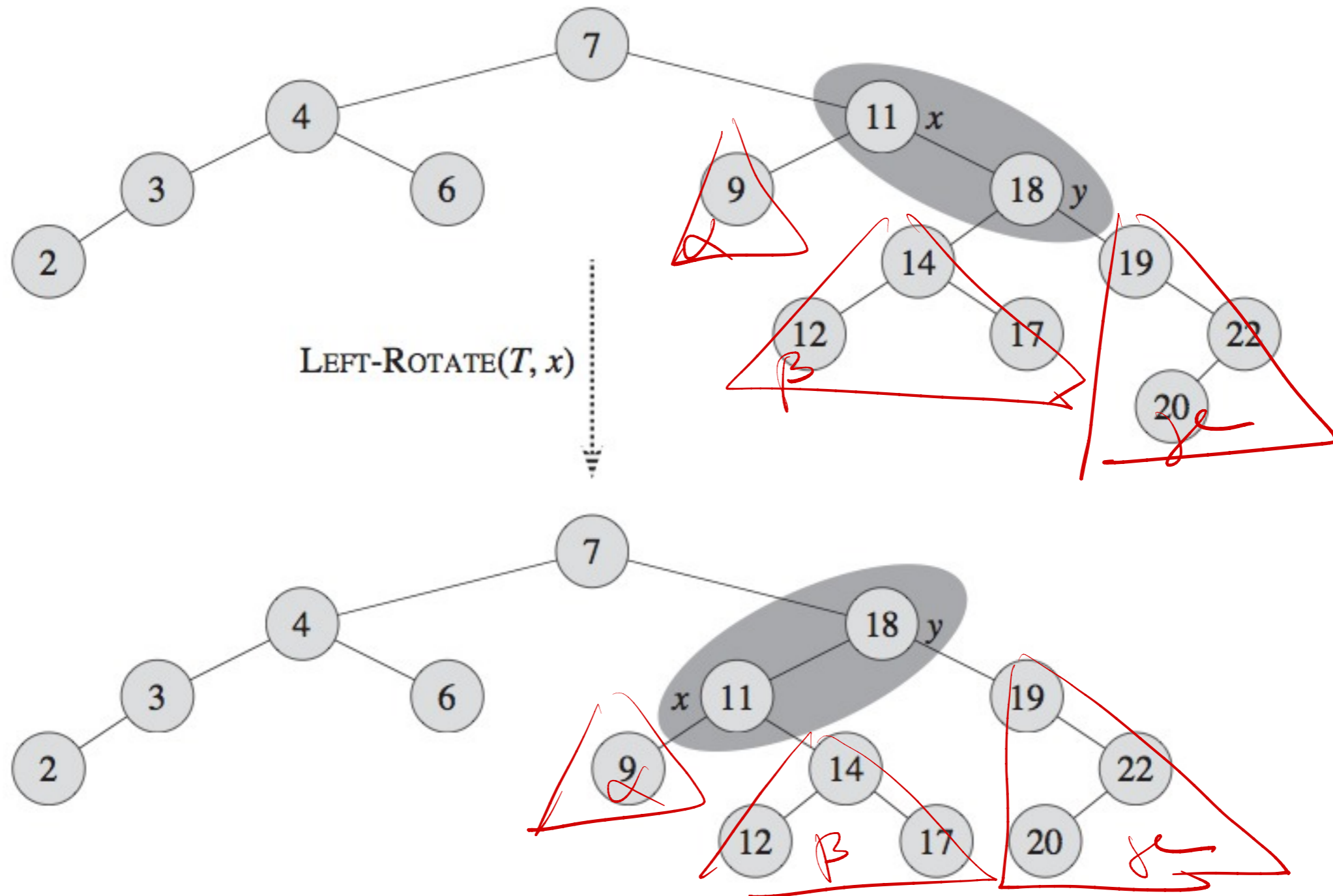
- **Rotate-left at node x**

- x is replaced by its right child y
- β = left subtree of y becomes right subtree of x
- x becomes the left child of y

- **Rotate-right at y symmetric**



Red-Black Trees - Rotation



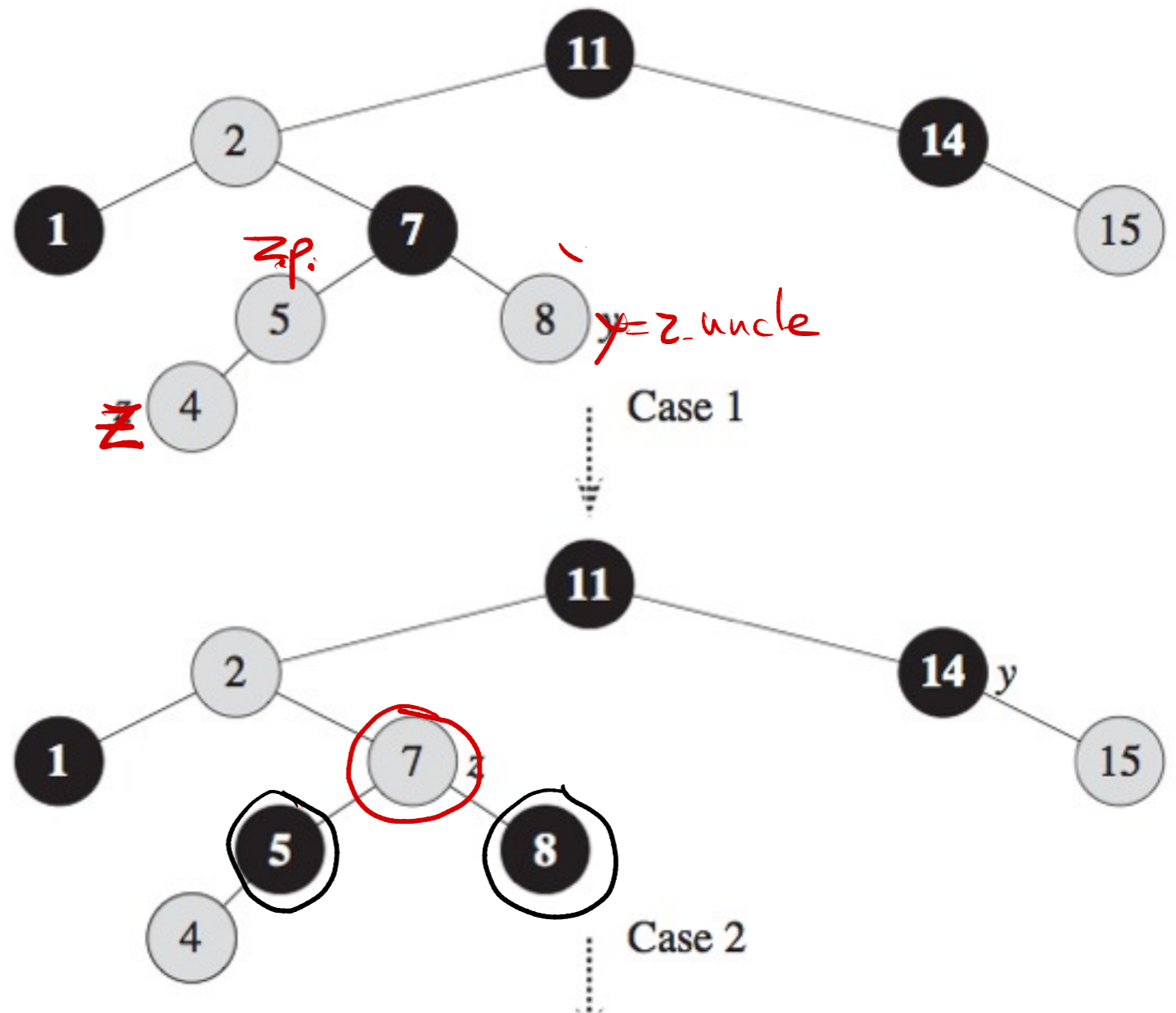
● Example

Red-Black Trees – Insertion

- add node "z" as a leaf
 - like usual in a binary search tree
- color z red, add terminal "NIL" nodes
- check red-black conditions
 - most conditions are still satisfied or easy to fix
 - ✖ the real problem might be the condition that requires children of red nodes to be black.
 - start fixing at the new node z, and as we proceed more fixes might be necessary
 - three "fixing cases"
 - overall still $O(\log n)$ time.
- RB-INSERT-FIXUP procedure in the textbook

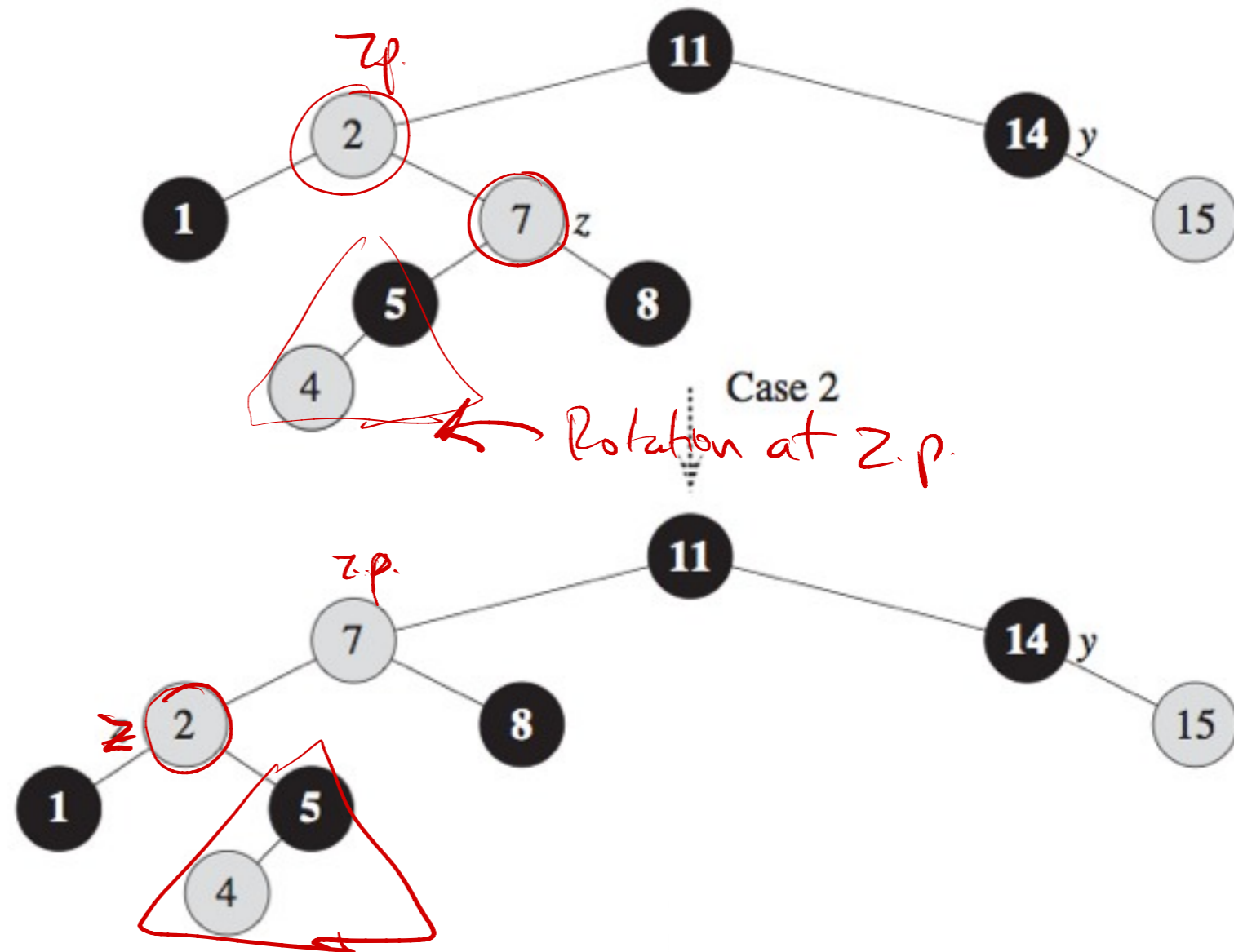
Fixing insertion case 1

- $z.p = z.parent$ and $y = z.uncle$ are red
- fix:
 - make $z.p$ and y black
 - make $z.p.p$ red
 - advance z to $z.p.p$
"fixed locally, move up"



Fixing insertion case 2

- z.p is red, y is black, z is the right child
- fix:
 - rotate left at z.p
 - z advances to its old parent (now his left child)

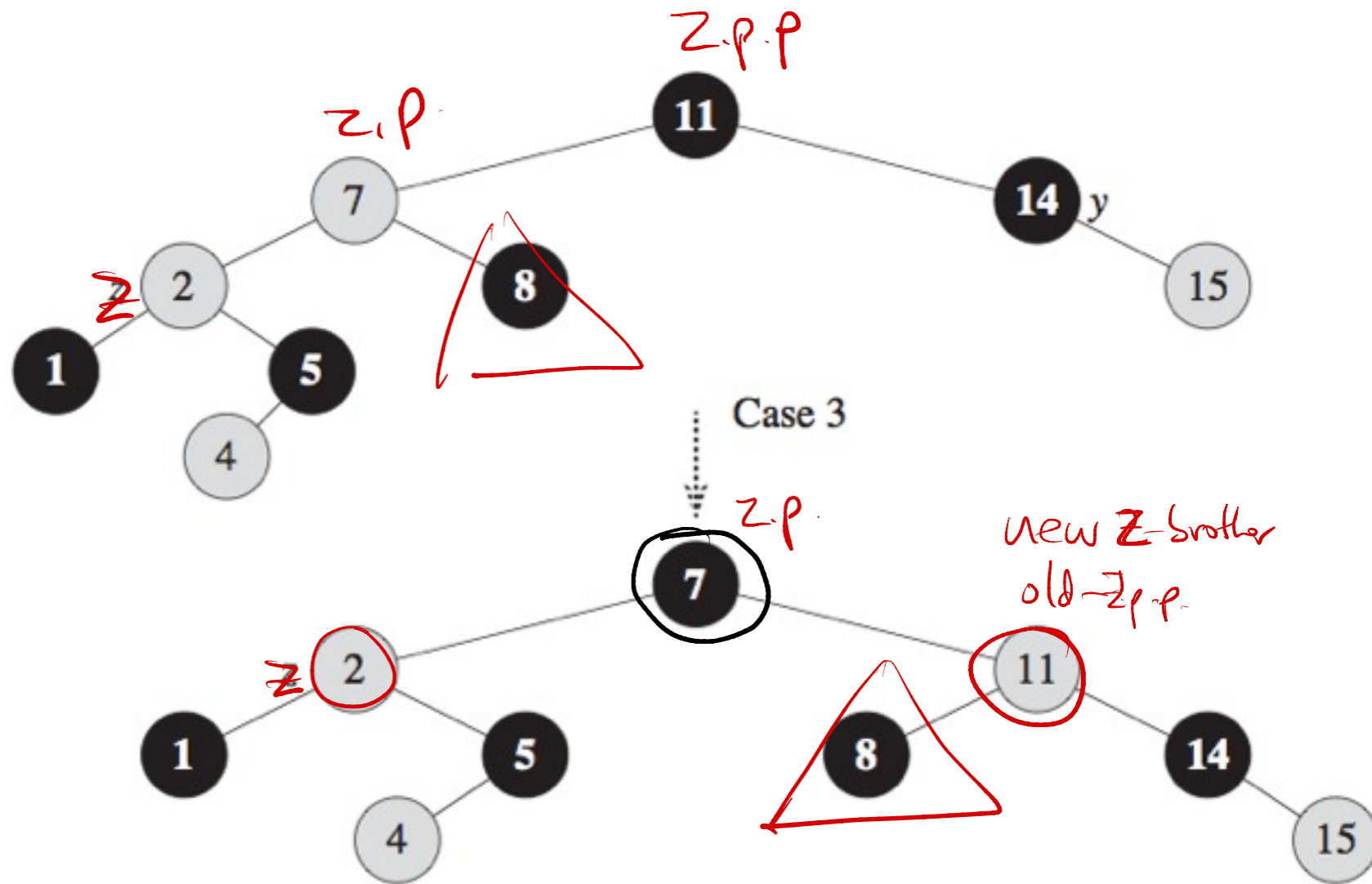


Fixing insertion case 3

- z.p red, y black, z is left child

- fix:

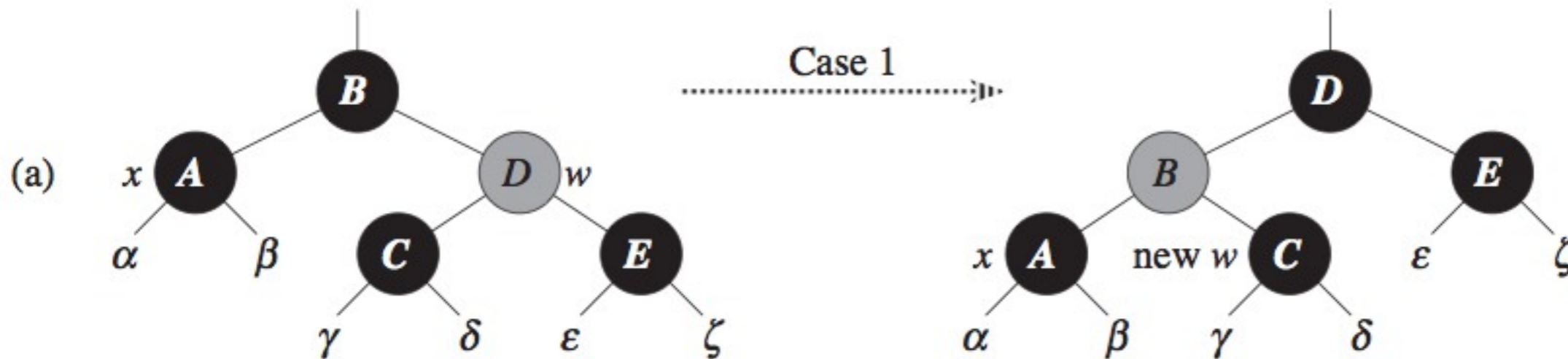
- rotate right at z.p.p
- color z.p black
- color old z.p.p (now z brother) red



Red-Black Trees - Deletion

- delete "z" as we usually delete from a binary search tree
 - maintain search property: left values \leq node value \leq right values
- additionally keep track of
 - y = the node to replace z
 - y original color (its color might change in the process)
- Fix-up the tree red-black properties, if they are violated
 - a procedure with 4 cases
 - RB-DELETE-FIXUP procedure in the textbook

Fixing deletion case 1

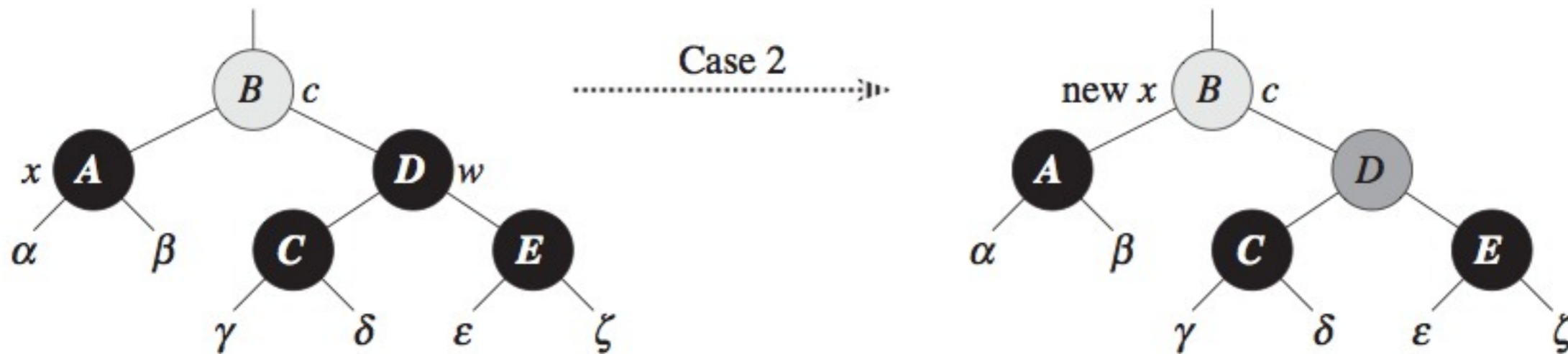


● case 1: x is black, brother w red

● fix :

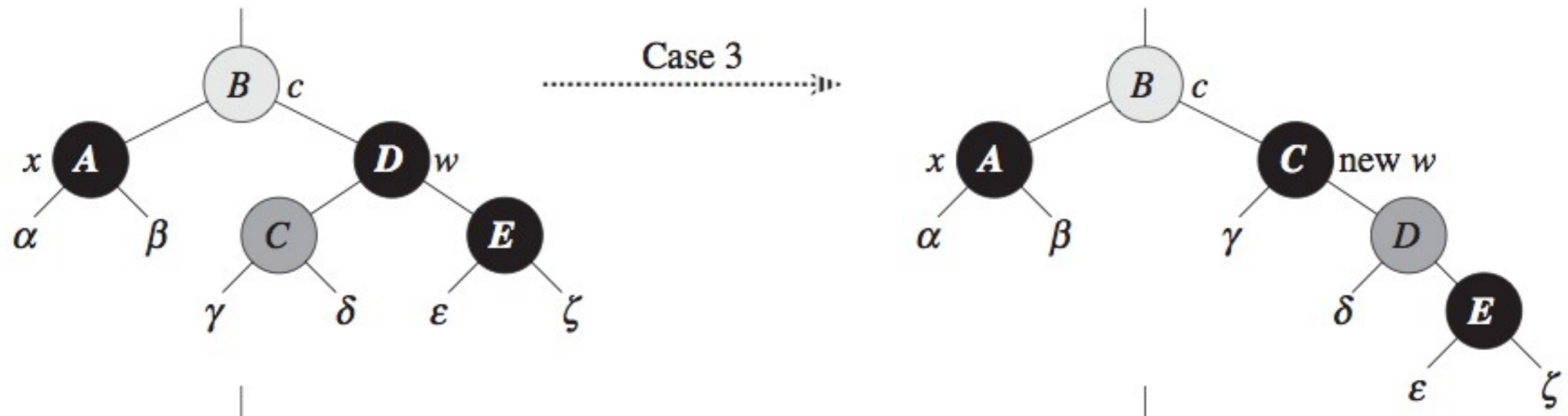
- rotate left at $x.p$;
- color $x.p$ red;
- color w (now $x.p.p$) black

Fixing deletion case 2



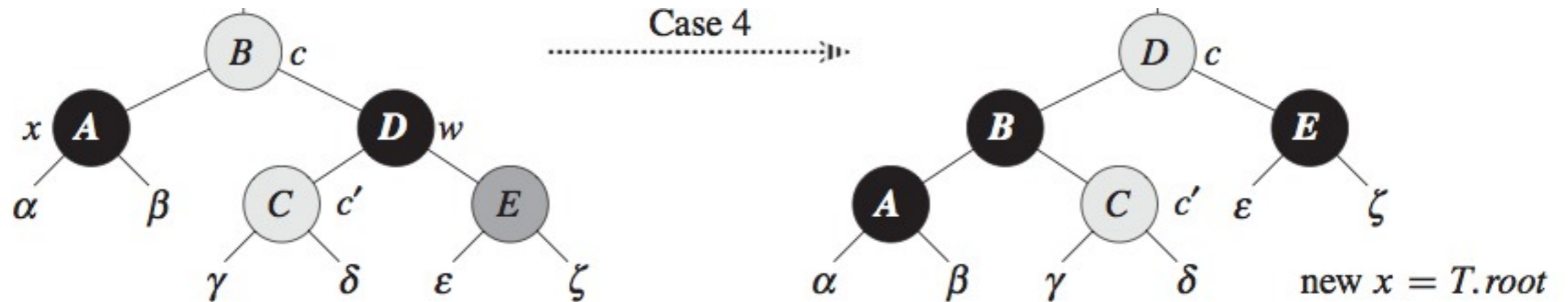
- case2: brother w is black, and w children also black
- fix:
 - color w red
 - advance x to its parent

Fixing deletion case 3



- case3: brother w is black; w 's left child is red; w 's right child is black
- fix:
 - rotate right at w
 - color the new brother from red to black
 - color the old brother from black to red

Fixing deletion case 4



- case4: brother w is black, w 's right child is red
- fix:
 - rotate left at $x.p$
 - color old w 's right child from red to black
 - color $x.p$ from red to black
 - color old w from black to red

Running time

- most BST operations same running time as BST trees
 - search, min, max, successor, predecessor
 - these dont affect RB colors
- Insertion including fixup $O(\log n)$
- Deletion including fixup $O(\log n)$