College of Computer & Information Science Northeastern University CS7800: Advanced Algorithms

## Fall 2010 Handout 20 15 December 2010

#### Take-Home Final Exam

# Due by 5:30 PM, Thursday, December 16

- **Honor code:** This exam is open-notes, open-library, and open-web. However, *no collabo-* ration of any kind is allowed. ("Collaboration" includes, for example, discussion or exchange of material related to the problems on the exam with anyone other than the instructor.) If you have any questions or clarifications, please ask me.
- Policy on Cheating: Students who violate the above rules on scholastic honesty are subject to disciplinary penalties. Any student caught cheating will receive an **F** (failing grade) for the course, and the case will be forwarded to the Office of Student Conduct and Conflict Resolution.
- **Presentation of solutions:** While describing an algorithm, you may use any of the algorithms covered in class or in the text as a subroutine, without elaboration.
- A note on grading: Your grade on any problem that asks you to design an algorithm will be determined on the basis of its correctness and the clarity of the description. In case you are not able to present an algorithm that has the desired properties, give the best algorithm you have designed. Show your work, as partial credit may be given.
- Good Luck!

# Problem 1. (4 + 5 + 6 = 15 points) Proofs and counterexamples

- (a) Prove or disprove: Let G be a connected graph with a weight function w on edges. Let T be a minimum spanning tree of G, with respect to w. Let C be any cut of G, and let e and e' be two edges crossing the cut C such that e is in T and e' is not in T. Then  $w(e) \leq w(e')$ .
- (b) We know that a sequence of n splay operations on any n-node tree incurs  $O(n \log n)$  time. Recall that each splay operation is a sequence of zig, zig-zig, or zig-zag steps. Suppose we replace the zig-zig and zig-zag steps on a node x by the following step: if x has a parent y and a grandparent, first rotate(y) and then rotate(x). Give an n-node tree and a sequence of n splay operations applied on the tree for which this modified splay implementation will cost  $\Omega(n^2)$  time.
  - You need not give a detailed proof. A precise definition of the tree, the sequence, and a brief argument for the time would suffice.
- (c) Consider a network flow (directed) graph G with a capacity on each edge, a source s, and a sink t. We say that an edge e is crucial if decreasing its capacity will decrease the maximum flow from s to t. We say that an edge e is a bottleneck if increasing its capacity will increase the maximum flow from s to t. Prove or disprove each of the following two statements: (i) if an edge is crucial, then it is also a bottleneck; (ii) if an edge is a bottleneck, then it is also crucial.

#### Problem 2 (10 + 2 = 12 points) Cheapest short paths

Let G = (V, E) be a directed graph, and  $\ell : E \to N$  and  $c : E \to N$  be two functions, where N is the set of positive integers. We call  $\ell(e)$  to be the length of edge e and c(e) to be the cost of edge e. Given G,  $\ell$ , c, a source  $s \in V$ , a destination  $t \in V$ , and an integer L, design an algorithm for finding a path from s to t with length at most L and whose cost is smallest among all paths from s to t of length at most L. (If not such path exists, then your algorithm should indicate so.) The worst-case running time of your algorithm must be polynomial in |V|, |E|, L, and the sizes of  $\ell$  and c.

You need not prove the correctness of your algorithm; nor do you need to optimize the running time of your algorithm.

Given G,  $\ell$ , c, and L, as above, the problem of finding the minimum-cost path with length at most L is known to be NP-complete. Explain why we cannot infer from the preceding fact and your algorithm that P = NP.

### Problem 3. (8 points) Finding a fitting line

Design a polynomial-time algorithm for the following problem. Given a set of n points  $(x_i, y_i)$ ,  $1 \le i \le n$ , find a line ax + by = c (i.e., find a, b, c) that best fits the n points in the following sense: the line minimizes

$$\max_{i} |ax_i + by_i - c|.$$

Assume that  $x_i$ 's and  $y_i$ 's are all integers.

You need not prove the correctness of your algorithm; nor do you need to optimize the running time of your algorithm.