

Modularization of crosscutting concerns

```

interface ShapeI extends Remote {
    double get_x() throws RemoteException ;
    void set_x(int x) throws RemoteException ;
    double get_y() throws RemoteException ;
    void set_y(int y) throws RemoteException ;
    double get_width() throws RemoteException ;
    void set_width(int w) throws RemoteException ;
    double get_height() throws RemoteException ;
    void set_height(int h) throws RemoteException ;
    void adjustLocation() throws RemoteException ;
    void adjustDimensions() throws RemoteException ;
}
public class Shape
    implements ShapeI {
    protected AdjustableLocation loc;
    protected AdjustableDimension dim;
    public Shape() {
        loc = new AdjustableLocation(0, 0);
        dim = new AdjustableDimension(0, 0);
    }
    double get_x() throws RemoteException {
        return loc.x();
    }
    void set_x(int x) throws RemoteException {
        loc.set_x(x);
    }
    double get_y() throws RemoteException {
        return loc.y();
    }
    void set_y(int y) throws RemoteException {
        loc.set_y(y);
    }
    double get_width() throws RemoteException {
        return dim.width();
    }
    void set_width(int w) throws RemoteException {
        dim.set_w(w);
    }
    double get_height() throws RemoteException {
        return dim.height();
    }
    void set_height(int h) throws RemoteException {
        dim.set_h(h);
    }
    void adjustLocation() throws RemoteException {
        loc.adjust();
    }
    void adjustDimensions() throws RemoteException {
        dim.adjust();
    }
}
class AdjustableLocation {
    protected double x_, y_;
    public AdjustableLocation(double x, double y) {
        x_ = x; y_ = y;
    }
    synchronized double get_x() { return x_; }
    synchronized void set_x(int x) { x_ = x; }
    synchronized double get_y() { return y_; }
    synchronized void set_y(int y) { y_ = y; }
    synchronized void adjust() {
        x_ = longCalculation1();
        y_ = longCalculation2();
    }
}
class AdjustableDimension {
    protected double width_=0.0, height_=0.0;
    public AdjustableDimension(double h, double w) {
        height_ = h; width_ = w;
    }
    synchronized double get_width() { return width_; }
    synchronized void set_w(int w) { width_ = w; }
    synchronized double get_height() { return height_; }
    synchronized void set_h(int h) { height_ = h; }
    synchronized void adjust() {
        width_ = longCalculation3();
        height_ = longCalculation4();
    }
}

```

Instead of writing this

Write this

```

public class Shape {
    protected double x_= 0.0, y_= 0.0;
    protected double width_=0.0, height_=0.0;

    double get_x() { return x_; }
    void set_x(int x) { x_ = x; }
    double get_y() { return y_; }
    void set_y(int y) { y_ = y; }
    double get_width() { return width_; }
    void set_width(int w) { width_ = w; }
    double get_height(){ return height_; }
    void set_height(int h) { height_ = h; }
    void adjustLocation() {
        x_ = longCalculation1();
        y_ = longCalculation2();
    }
    void adjustDimensions() {
        width_ = longCalculation3();
        height_ = longCalculation4();
    }
}

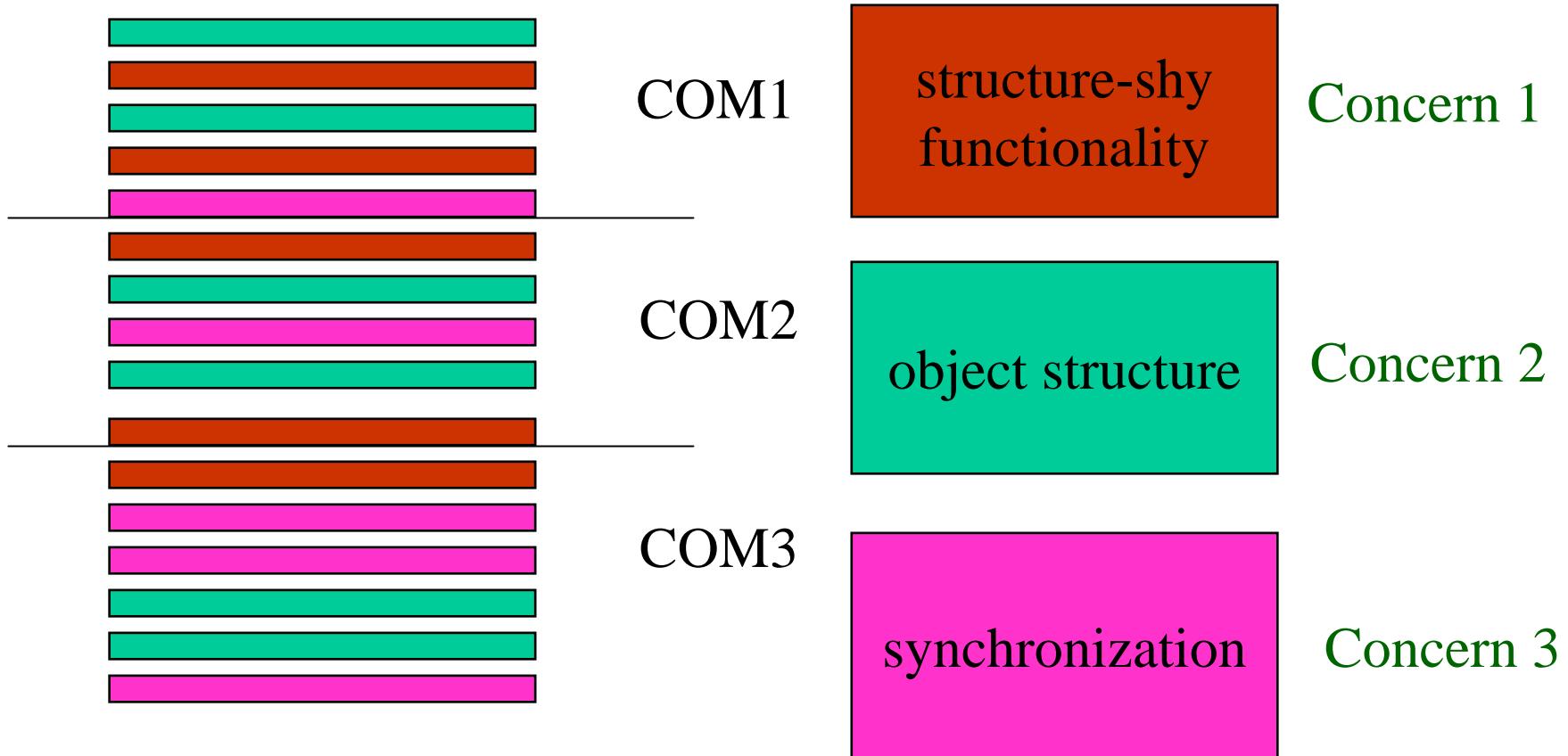
coordinator Shape {
    selfex adjustLocation, adjustDimensions;
    mutex {adjustLocation, get_x, set_x,
            get_y, set_y};
    mutex {adjustDimensions, get_width, get_height,
            set_width, set_height};
}

portal Shape {
    double get_x() {};
    void set_x(int x) {};
    double get_y() {};
    void set_y(int y) {};
    double get_width() {};
    void set_width(int w) {};
    double get_height() {};
    void set_height(int h) {};
    void adjustLocation() {};
    void adjustDimensions() {};
}

```

Scattering: count number of components to which color goes

ordinary program aspect-oriented prog.



AspectJ

- Xerox PARC: Gregor Kiczales et al.: lingua franca of AOP.
- First version: Crista Lopes (member of Demeter group): implementing both COOL and RIDL in a general purpose AO language (early AspectJ version).
- Model: join points, pointcuts, advice.

From Demeter to AspectJ

Demeter (for Scheme or
C++ or Java or Flavors)

- Visitor method sig.
 - set of execution points of traversals
 - specialized for traversals (nodes, edges)
 - where to enhance
- Visitor method bodies
 - how to enhance

AspectJ

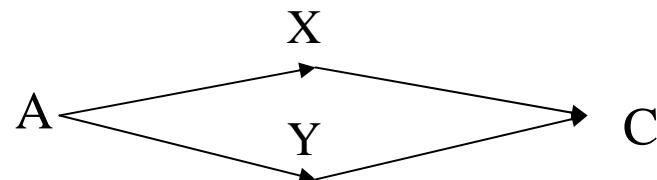
- Pointcut
 - set of execution points of any method, ...
 - rich set of primitive pointcuts: this, target, call, ... + set operations
 - where to enhance
- Advice
 - how to enhance

Flow Expressions

- $D ::= [A,B] \mid \text{join}(D_1, D_2) \mid \text{merge}(D_1, D_2)$
- We can use them in three different graphs relevant to programming:
 - call trees: subset of nodes
 - class graphs: subset of nodes
 - object trees: subgraph

Flow Expressions and AOP

- They are a basic cross-cutting construct for defining subgraphs.



- `merge(join([A,X],[X,C]), join([A,Y],[Y,C]))` defines a subgraph of a larger graph whose ad-hoc description cuts across many nodes or edges.
- succinct encapsulations of subgraphs related to some aspect.

Flow expressions

- are abstractions of some aspect whose ad-hoc description would cut across many nodes or edges of a graph.
- define sets of join points based on connectivity in graph.
- offer pointcut designator reduction (high-level pointcut designator): free programmer from details of some graph representing some aspect.

Definitions for Flow Expressions

- $D ::= [A,B] \mid \text{join}(D_1, D_2) \mid \text{merge}(D_1, D_2)$
- $\text{Source}([A,B]) = A$
- $\text{Target}([A,B]) = B$
- $\text{Source}(\text{join}(D_1, D_2)) = \text{Source}(D_1)$
- $\text{Target}(\text{join}(D_1, D_2)) = \text{Target}(D_2)$
- $\text{Source}(\text{merge}(D_1, D_2)) = \text{Source}(D_1)$
- $\text{Target}(\text{merge}(D_1, D_2)) = \text{Target}(D_1)$

Well-formed Flow Expressions

- $D ::= [A,B] \mid \text{join}(D_1, D_2) \mid \text{merge}(D_1, D_2)$
- $\text{WF}([A,B]) = \text{true}$ // well-formed
- $\text{WF}(\text{join}(D_1, D_2)) = \text{WF}(D_1) \And \text{WF}(D_2) \And \text{Target}(D_1) = \text{Source}(D_2)$
- $\text{WF}(\text{merge}(D_1, D_2)) = \text{WF}(D_1) \And \text{WF}(D_2) \And \text{Source}(D_1) = \text{Source}(D_2) \And \text{Target}(D_1) = \text{Target}(D_2)$

Interpretation of traversal strategies

- $D ::= [A,B] \mid \text{join}(D_1,D_2) \mid \text{merge}(D_1,D_2)$
- A and B are pointcut designators.
- $[A,B]$: the set of B-nodes reachable from A-nodes.
- $\text{join}(D_1,D_2)$: the set of Target(D_2)-nodes reachable from Source(D_1)-nodes following D_1 and then following D_2 .

Interpretation of traversal strategies

- $\text{merge}(D_1, D_2)$: the union of the set of $\text{Target}(D_1)$ -nodes reachable from $\text{Source}(D_1)$ -nodes following D_1 and the set of $\text{Target}(D_2)$ -nodes reachable from $\text{Source}(D_2)$ -nodes following D_2 .

Meaning in Class graph

- D
- [A,B]
- join(D1,D2)
- merge(D1,D2)
- PathSet(D)
- Paths(A,B)
- PathSet(D1).PathSet(D2)
- PathSet(D1) || PathSet(D2)

flow expressions are called traversal strategies

Demeter/C++

DemeterJ

DJ

Object tree

- D
- [A,B]
 - subgraph of O
 - subgraph of O consisting of all paths from an A-node to a B-node, including prematurely terminated paths.

Object tree

- D
- $\text{join}(D_1, D_2)$
 - subgraph of O
 - subgraph of O consisting of all paths following D_1 and those reaching $\text{Target}(D_1)$ concatenated with all paths following D_2 .

Object tree

- D
 - subgraph of O
- merge(D1,D2)
 - subgraph of O
 - consisting of all paths following D1 or following D2.

Purposes of strategies

- DJ
- Traversal
 - strategy graph
 - class graph
 - object graph
- Purposes
 - select og with sg
 - extract node labels
 - select cg with sg
- AspectJ
- General computation
 - strategy call graph
 - static call graph
 - dynamic call graph
- Purposes
 - select dcg with sycg
 - extract node labels
 - select scg with sycg

Purposes of strategies

- DJ + method edges
- Traversal
 - strategy graph
 - class graph
 - object graph
 - argument map
- Purposes
 - select **dcg** with sg + am
 - extract node labels

Correspondences

- | | |
|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <ul style="list-style-type: none">• D1• from A to B• from A to *• from A via B to C• from A via B via C to E• merge(from A via B1 to C,
from A via B2 to C)• merge(D1,D2)• join(D1,D2)• join (from A to B, from B to C) | <ul style="list-style-type: none">• $t(D1)$• $\text{flow}(A) \&\& B$• $\text{flow}(A)$• $\text{flow}(\text{flow}(A) \&\& B) \&\& C$• $\text{flow}(\text{flow}(\text{flow}(A) \&\& B) \&\& C) \&\& E$• $(\text{flow}(\text{flow}(A) \&\& B1) \&\& C) \parallel (\text{flow}(\text{flow}(A) \&\& B2) \&\& C)$• $t(D1) \parallel t(D2)$• $\text{flow}(t(D1)) \&\& t(D2)$• $\text{flow}(\text{flow}(A) \&\& B) \&\& (\text{flow}(B) \&\& C)$• = flow(flow(A) && B) && C |
|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|

$$\text{subset}(\text{flow}(B)) \&\& \text{flow}(B) = \text{subset}(\text{flow}(B))$$

Theme

- Defining high-level artifact in terms of a low-level artifact without committing to details of low-level artifact in definition of high-level artifact. Low-level artifact is parameter to definition of high-level artifact.
- Exploit structure of low-level artifact.

AspectJ adds

- Generalizes from join points of specialized methods to join points of any method, field access, field modification, etc.
- Uses set operations `&&` and `!` combined with a rich set of primitive pointcuts.
- Generalizes from a flow construct for traversals to a flow construct for arbitrary join points.