

# CS3000: Algorithms & Data

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### Lecture 15:

- Bellman-Ford

Oct 30, 2018

### Schedule

- Midterm II Nov 16
- No class Thanksgiving week

# Bellman-Ford

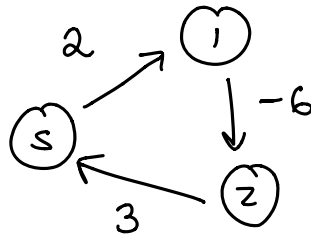
# Dijkstra Recap

- **Input:** Directed, weighted graph  $G = (V, E, \{\ell_e\})$ , source node  $s$ 
  - Non-negative edge lengths  $\ell_e \geq 0$
- **Output:** Two arrays  $d, p$  (Single-source shortest paths)
  - $d[u]$  is the length of the shortest  $s \rightsquigarrow u$  path
  - $p[u]$  is the final hop on shortest  $s \rightsquigarrow u$  path
    - ↳ edges in the shortest tree
- **Running time:**  $O(m \log n)$ 
  - Implement using **binary heaps**

# Ask the Audience

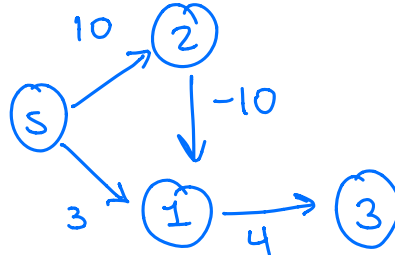
- Show that Dijkstra's Algorithm can fail in graphs with negative edge lengths, but no neg. length cycles.

① Negative-length cycles — shortest path is undefined



distances can be  $-\infty$

②



Running Dijkstra gives

	s	1	2	3
d	0	$\infty$	$\infty$	$\infty$
0		3	10	$\infty$
0		3	10	7
0		3	10	7

Wrong distances →

0	0	10	7
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# Why Care About Negative Lengths?

- Models various phenomena
  - Transactions (credits and debits)
  - Currency exchange ( $\log(\text{exchange rate})$  can be + or -)
  - Chemical reactions (can be exo or endothermic)
- Leads to interesting algorithms
  - Variants of Bellman-Ford are used in internet routing

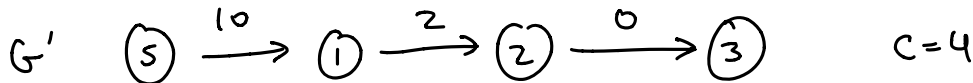
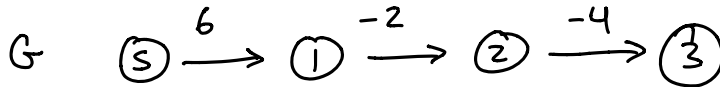
# Bellman-Ford

- **Input:** Directed, weighted graph  $G = (V, E, \{\ell_e\})$ , source node  $s$ 
  - Possibly negative edge lengths  $\ell_e \in \mathbb{R}$
  - No negative-length cycles!
- **Output:** Two arrays  $d, p$ 
  - $d[u]$  is the length of the shortest  $s \rightsquigarrow u$  path
  - $p[u]$  is the final hop on shortest  $s \rightsquigarrow u$  path

# Ask the Audience

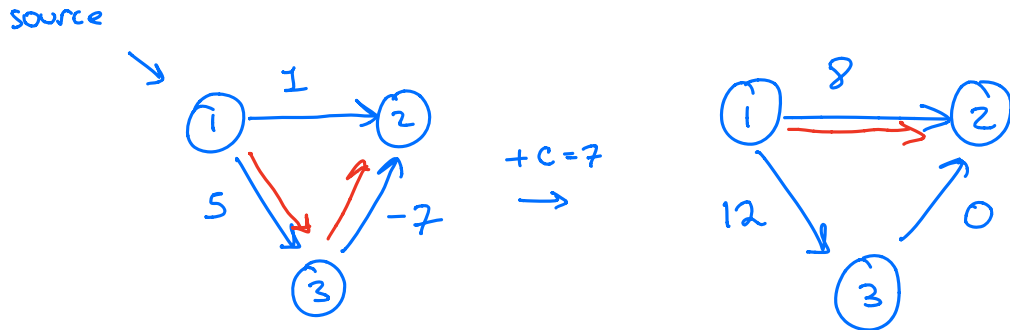
$$C = -\min_{e \in E} \ell(e)$$

- Suppose we try the following algorithm
  - Take a graph  $G = (V, E, \{\ell(e)\})$  with negative lengths
  - Add  $C$  to all lengths to make them non-negative
  - Run Dijkstra on the new graph
- Why wont this work?



# Ask the Audience

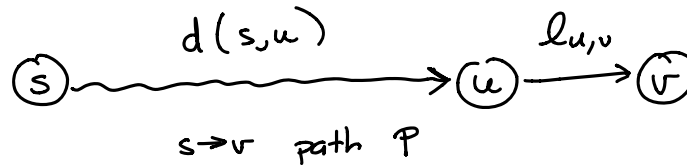
- Suppose we try the following algorithm
  - Take a graph  $G = (V, E, \{\ell(e)\})$  with negative lengths
  - Add  $C$  to all lengths to make them non-negative
  - Run Dijkstra on the new graph
- Why won't this work?





# Structure of Shortest Paths

- If  $(u, v) \in E$ , then  $d(s, v) \leq d(s, u) + \ell(u, v)$  for every node  $s \in V$



- For every  $v$ , there exists an edge  $(u, v) \in E$  such that  $d(s, v) = d(s, u) + \ell(u, v)$



- If  $(u, v) \in E$ , and  $d(s, v) = d(s, u) + \ell(u, v)$  then there is a shortest  $s \rightsquigarrow v$ -path ending with  $(u, v)$

# Dynamic Programming

- **Subproblems:** Let  $\text{OPT}(v)$  be the length of the shortest path from  $s$  to  $v$

- For every  $v$ , the shortest path makes some final hop  $(u, v)$

- Case  $u$  (the final hop is  $(u, v) \in E$ )

$$\hookrightarrow \text{OPT}(v) = \text{OPT}(u) + l(u, v)$$

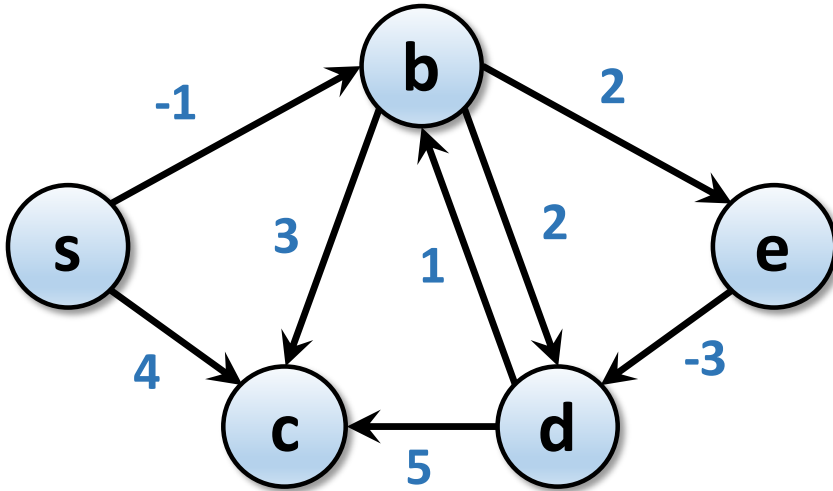
- Recurrence :

$$\text{OPT}(v) = \min_{(u, v) \in E} \text{OPT}(u) + l(u, v)$$

$$\text{OPT}(s) = 0$$

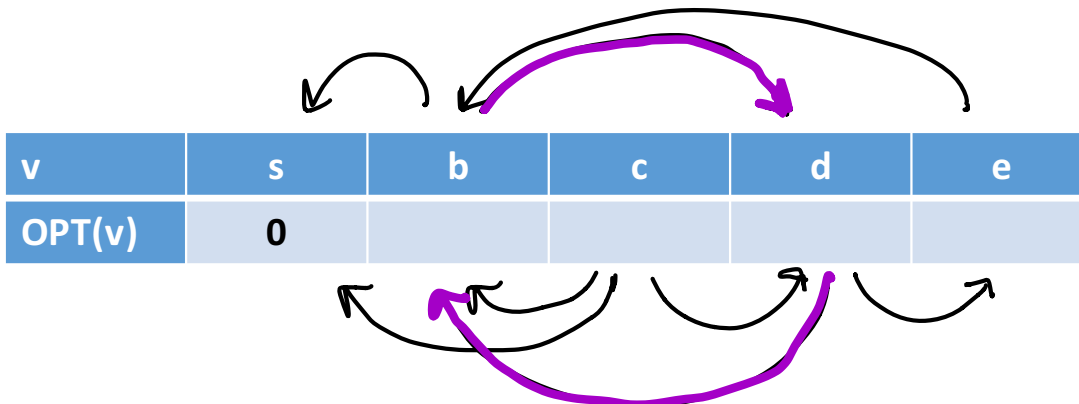
# Bottom-Up Implementation?

$$OPT(v) = \min_{(u,v) \in E} OPT(u) + l(u,v)$$



Need to fill the DP table in some order.

Cannot put the DP table "in order"



# Dynamic Programming Take II

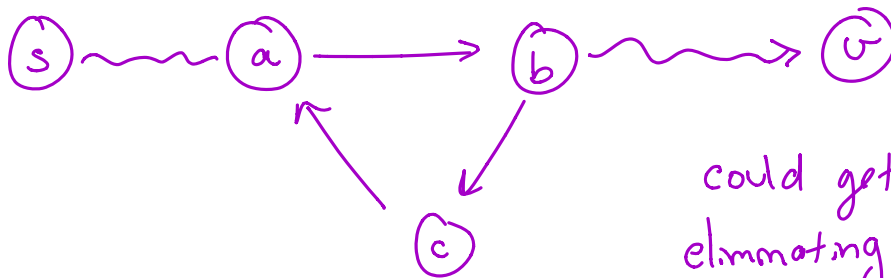
$\exists$  a shortest path w/  $\leq n-1$  hops

- **Subproblems:** Let  $\text{OPT}(v, j)$  be the length of the shortest path from  $s$  to  $v$  with at most  $j$  hops

- $0 \leq j \leq n-1$

- Any path with  $\geq n$  hops has a cycle, any cycle has  $\geq 0$  length

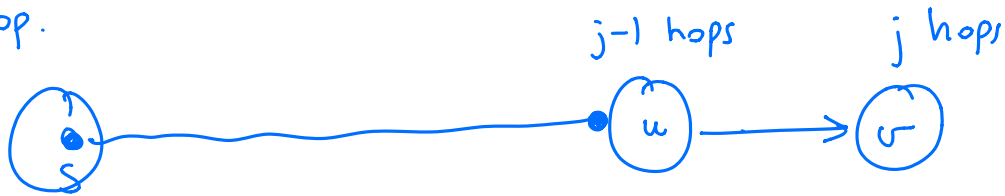
$\therefore$  shortest path has  $\leq n-1$  hops



could get a shorter path by eliminating the cycle

# Dynamic Programming Take II

- **Subproblems:** Let  $\text{OPT}(v, j)$  be the length of the shortest path from  $s$  to  $v$  with at most  $j$  hops
- Shortest path using  $j$  hops uses some  $(u, v)$  as the final hop.



$$\text{OPT}(v, j) = \min \left\{ \text{OPT}(v, j-1), \min_{(u,v) \in E} \text{OPT}(u, j-1) + l(u,v) \right\}$$

$$\text{OPT}(s, 0) = 0$$

$$\text{OPT}(v, 0) = \infty \quad \forall v \neq s$$

# Recurrence

- **Subproblems:** Let  $\text{OPT}(v, j)$  be the length of the shortest path from  $s$  to  $v$  with at most  $j$  hops
- **Case  $u$ :**  $(u, v)$  is final edge on the shortest  $j$ -hop  $s \rightsquigarrow v$  path

**Recurrence:**

$$\text{OPT}(v, j) = \min \left\{ \text{OPT}(v, j-1), \min_{(u,v) \in E} \{ \text{OPT}(u, j-1) + \ell_{u,v} \} \right\}$$

$$\text{OPT}(s, j) = 0 \text{ for every } j$$

$$\text{OPT}(v, 0) = \infty \text{ for every } v$$

# Finding the paths

- $\text{OPT}(v, j)$  is the length of the shortest  $s \rightsquigarrow v$  path with at most  $j$  hops
  - $P(v, j)$  is the last hop on some shortest  $s \rightsquigarrow v$  path with at most  $j$  hops
- (Edges in the shortest path tree only allowing  $\leq j$  hop paths)

**Recurrence:**

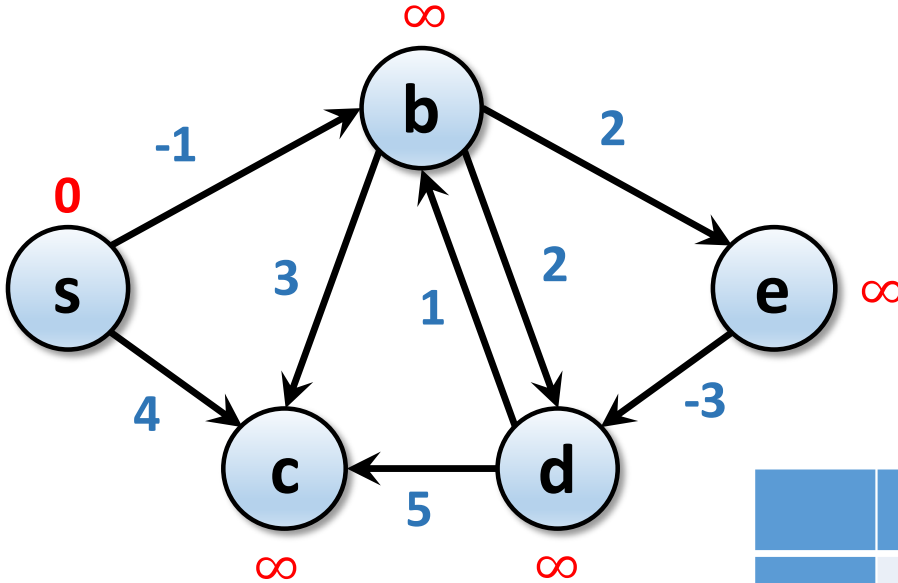
$$\text{OPT}(v, j) = \min \left\{ \text{OPT}(v, j-1), \min_{(u,v) \in E} \{ \text{OPT}(u, j-1) + \ell_{u,v} \} \right\}$$

If  $\text{OPT}(v, j) = \text{OPT}(u, j-1) + \ell(u, v)$  then there  $\exists$  a shortest  $s \rightsquigarrow v$  path  $v/\leq j$  hops whose last hop is  $(u, v)$

$$\Rightarrow P(v, j) = u$$

# Example

$$OPT(v, j) = \min \left\{ OPT(v, j-1), \min_{(u,v) \in E} OPT(u, j-1) + l_{u,v} \right\}$$

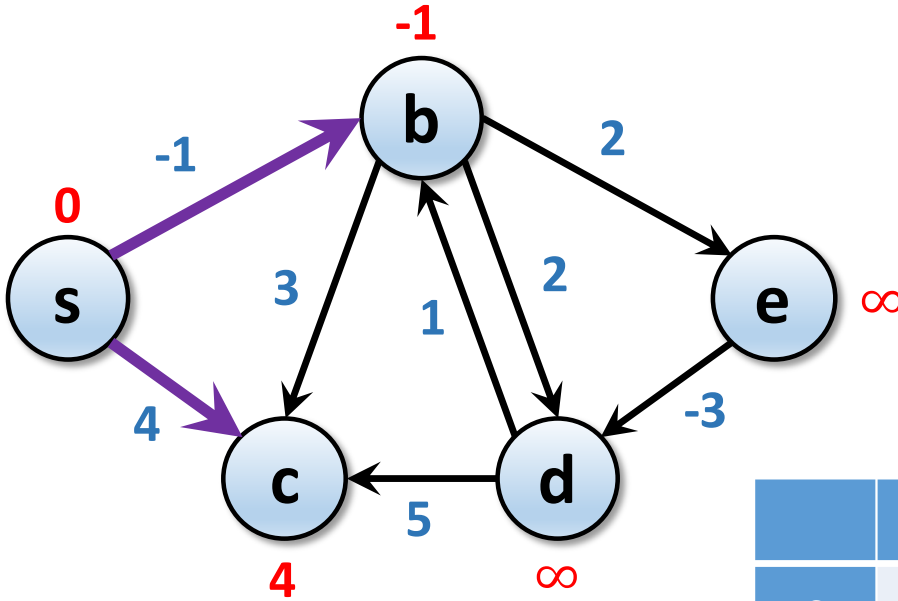


	0	1	2	3	4
s	0	0	0	0	0
b	∞				
c	∞				
d	∞				
e	∞				



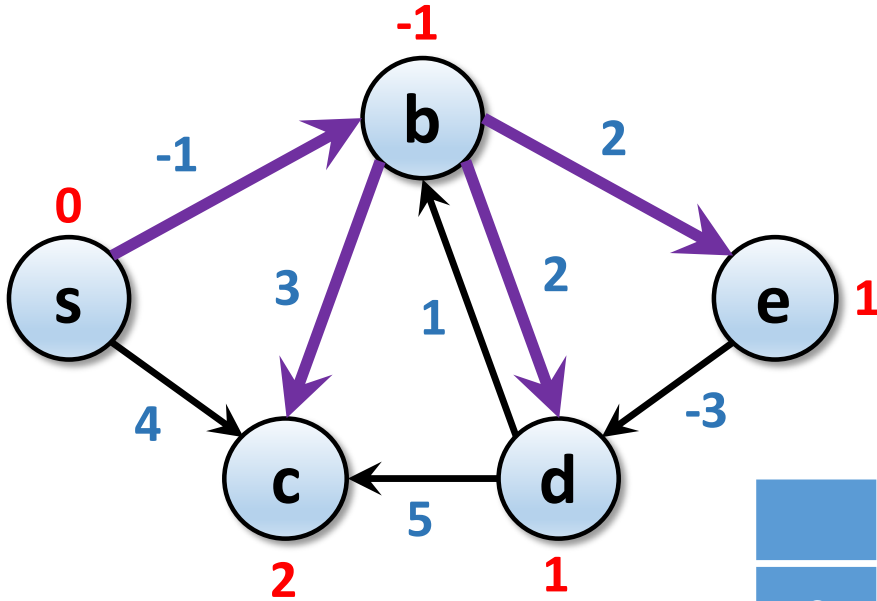
# Example

$$OPT(v, j) = \min \left\{ \begin{array}{l} OPT(v, j-1), \\ \min_{(u,v) \in E} \{ OPT(u, j-1) + l_{u,v} \} \end{array} \right.$$



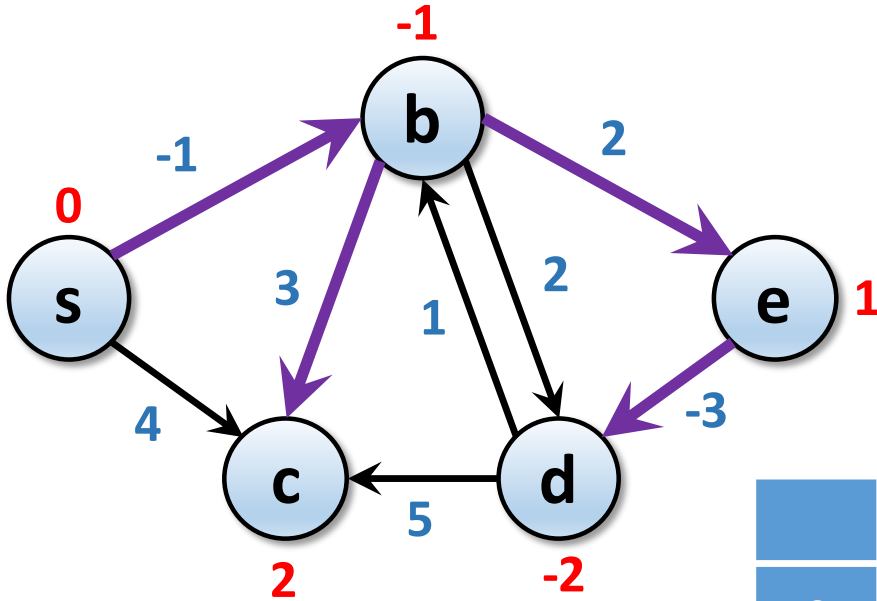
	0	1	2	3	4
s	0	0	0	0	0
b	∞	-1			
c	∞	4			
d	∞	∞			
e	∞	∞			

# Example



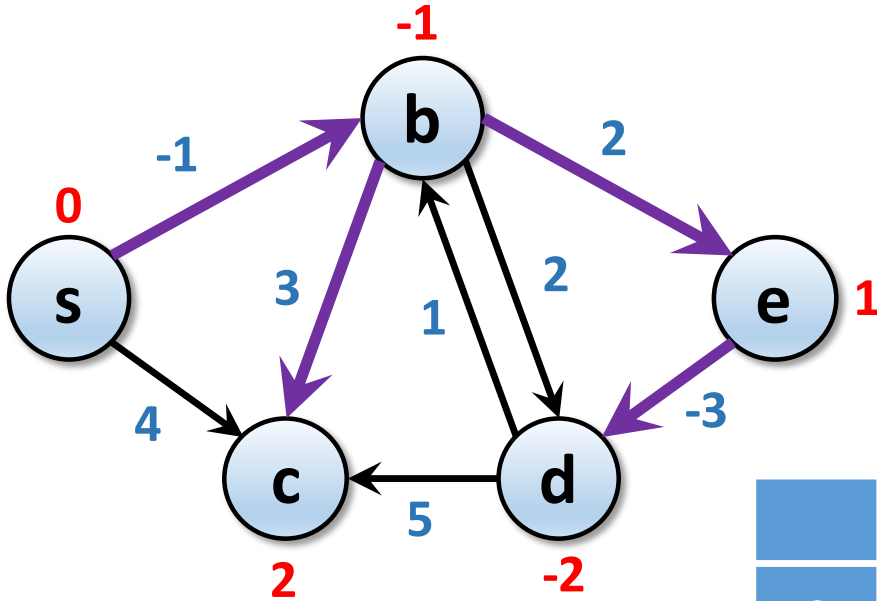
	0	1	2	3	4
s	0	0	0	0	0
b	$\infty$	-1	-1		
c	$\infty$	4	2		
d	$\infty$	$\infty$	1		
e	$\infty$	$\infty$	1		

# Example



	0	1	2	3	4
s	0	0	0	0	0
b	$\infty$	-1	-1	-1	
c	$\infty$	4	2	2	
d	$\infty$	$\infty$	1	-2	
e	$\infty$	$\infty$	1	1	

# Example



*nothing changed*



	0	1	2	3	4
s	0	0	0	0	0
b	$\infty$	-1	-1	-1	-1
c	$\infty$	4	2	2	2
d	$\infty$	$\infty$	1	-2	-2
e	$\infty$	$\infty$	1	1	1

# Implementation (Bottom Up DP)

$$D[v, j] = \text{OPT}(v, j)$$

Running Time

Shortest-Path( $G, s$ )

**foreach** node  $v \in V$

$D[v, 0] \leftarrow \infty$

$P[v, 0] \leftarrow \perp$

$D[s, 0] \leftarrow 0$

$O(n)$  time

**for**  $i = 1$  to  $n-1$   $\longrightarrow \leq n-1$  iterations

**foreach** node  $v \in V$

$D[v, i] \leftarrow D[v, i-1]$

$P[v, i] \leftarrow P[v, i-1]$

**foreach** edge  $(u, v) \in E$

**if**  $(D[u, i-1] + l_{uv} < D[v, i])$

$D[v, i] \leftarrow D[u, i-1] + l_{uv}$

$P[v, i] \leftarrow u$

implements  
the recurrence

$O(1)$

$O(\text{indeg}(v))$

$$\text{Total Time} = O(nm)$$

$$\text{Total Space} = O(n^2)$$

$$\begin{aligned} & \sum_{v \in V} O(\text{indeg}(v)) \\ &= O(m) \end{aligned}$$

# Optimizations

Once I find  $OPT(\cdot, j)$ ,  
don't care about  
 $OPT(\cdot, j-1)$

- One array  $d[v]$  containing shortest path found so far
- No need to check edges  $(u, v)$  unless  $d[u]$  has changed
- Stop if no  $d[v]$  has changed for a full pass through  $V$
- **Theorem:**
  - Throughout the algorithm  $M[v]$  is the length of some  $s - v$  path
  - After  $i$  passes through the nodes,  $M[v] \leq OPT(v, i)$

# Implementation II

```
Efficient-Shortest-Path(G, s)
  foreach node v ∈ V
    D[v] ← ∞
    P[v] ← ⊥ (NULL)
  D[s] ← 0

  for i = 1 to n
    foreach node u ∈ V
      if (D[u] changed in the last iteration)
        foreach edge (u,v) ∈ E
          if (D[u] + luv < D[v])
            D[v] ← D[u] + luv
            P[v] ← u
        if (no D[u] changed): return (D,P)
```

Running Time  $O(mn)$ , but  $O(m)$  in practice

Space  $O(n)$

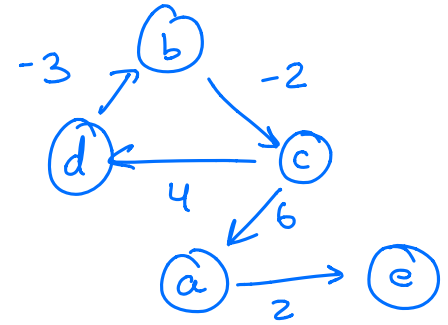
# Negative Cycle Detection

- **Claim 1:** if  $OPT(v, n) = OPT(v, n - 1)$  then there are no negative cycles reachable from  $s$
- **Claim 2:** if  $OPT(v, n) < OPT(v, n - 1)$  then any shortest  $s - v$  path contains a negative cycle

↳ shortest  $s \rightsquigarrow v$  path w/ at most  $n$  hops,  
uses exactly  $n$  hops, and thus contains a cycle  
this cycle must have negative length!

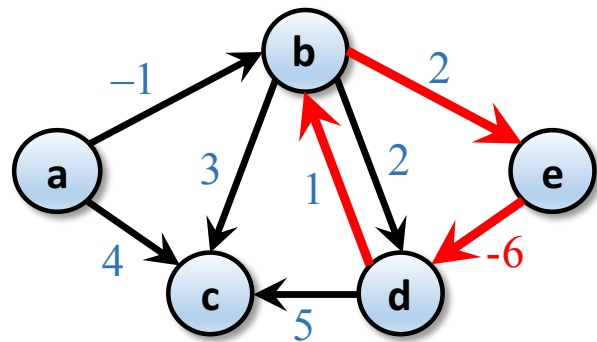


# Negative Cycle Detection



- **Algorithm:**

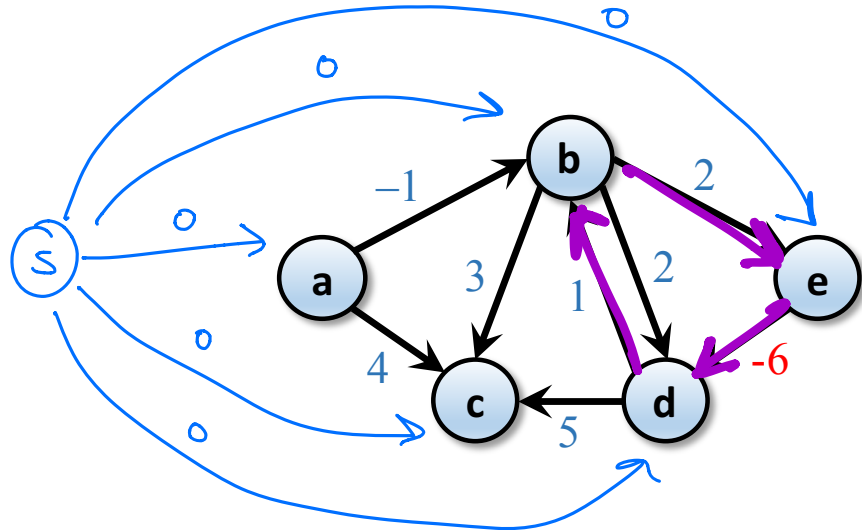
- Pick a node  $a \in V$
- Run Bellman-Ford for  $n$  iterations
- Check if  $OPT(v, n) \neq OPT(v, n - 1)$  for some  $v \in V$ 
  - If no, then there are no negative cycles
  - If yes, the shortest  $a - v$  path contains a negative cycle



# Negative Cycle Detection

- **Algorithm:**

- Add a new node  $s \in V$ , add edges  $(s, v)$  for every  $v \in V$
- Run Bellman-Ford for  $n$  iterations
- Check if  $OPT(v, n) \neq OPT(v, n - 1)$  for some  $v \in V$ 
  - If no, then there are no negative cycles
  - If yes, the shortest  $s - v$  path contains a negative cycle



# Shortest Paths Summary

- **Input:** Directed, weighted graph  $G = (V, E, \{\ell_e\})$ , source node  $s$
- **Output:** Two arrays  $d, p$ 
  - $d[u]$  is the length of the shortest  $s \rightsquigarrow u$  path
  - $p[u]$  is the final hop on shortest  $s \rightsquigarrow u$  path
- **Non-negative lengths:** Dijkstra's Algorithm solves in  $O(m \log n)$  time
- **Negative lengths:** Bellman-Ford solves in  $O(nm)$  time  $O(n + m)$  space, or finds a negative cycle