

CS3000: Algorithms & Data Jonathan Ullman

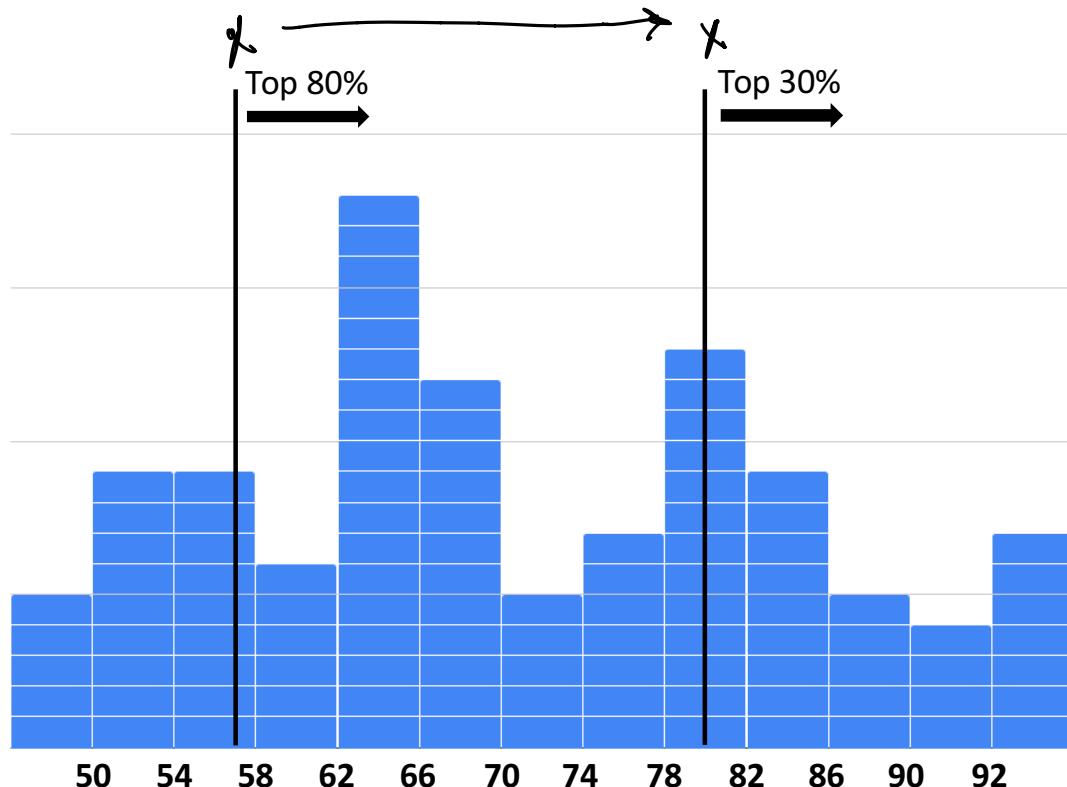
Lecture 13:

- Depth-First Search
- Start Shortest Paths

Oct 23, 2018

Midterm Stats

Midterm Grade Distribution



This midterm is only 15% of your course grade!

Midterm Grade Distribution

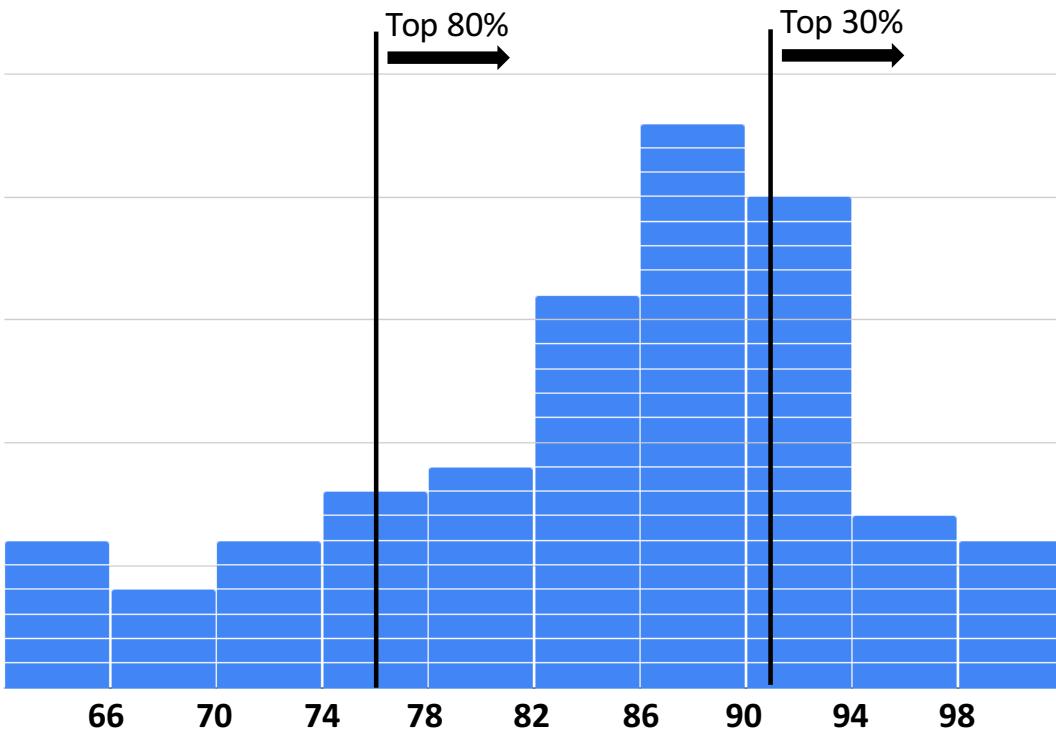
- Lots of points missed for asymptotics, induction:

	Mean
#1 Asymptotics	76%
#2 Recurrences	93%
#3 Induction	65%
#4 Divide-and-Conquer	72%
#5 Stable Matching	90%
#6 Dynamic Programming	63%



- These topics will come up on future exams!

Homework Grade Distribution



**Homework is 45% of your course grade!
I have not dropped your lowest grade yet**

Depth-First Search (DFS)

Exploring a Graph

- **Problem:** Is there a path from s to t ?
- **Idea:** Explore all nodes reachable from s .
- Two different search techniques:
 - **Breadth-First Search:** explore nearby nodes before moving on to farther away nodes
 - **Depth-First Search:** follow a path until you get stuck, then go back

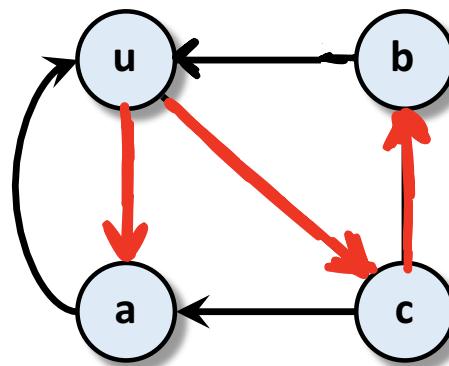
Depth-First Search

```
G = (V,E) is a graph  
explored[u] = 0  $\forall u$ 
```

```
DFS(u) :  
    explored[u] = 1
```

```
for ((u,v) in E):  
    if (explored[v]=0):  
        parent[v] = u  
        DFS(v)
```

start at u

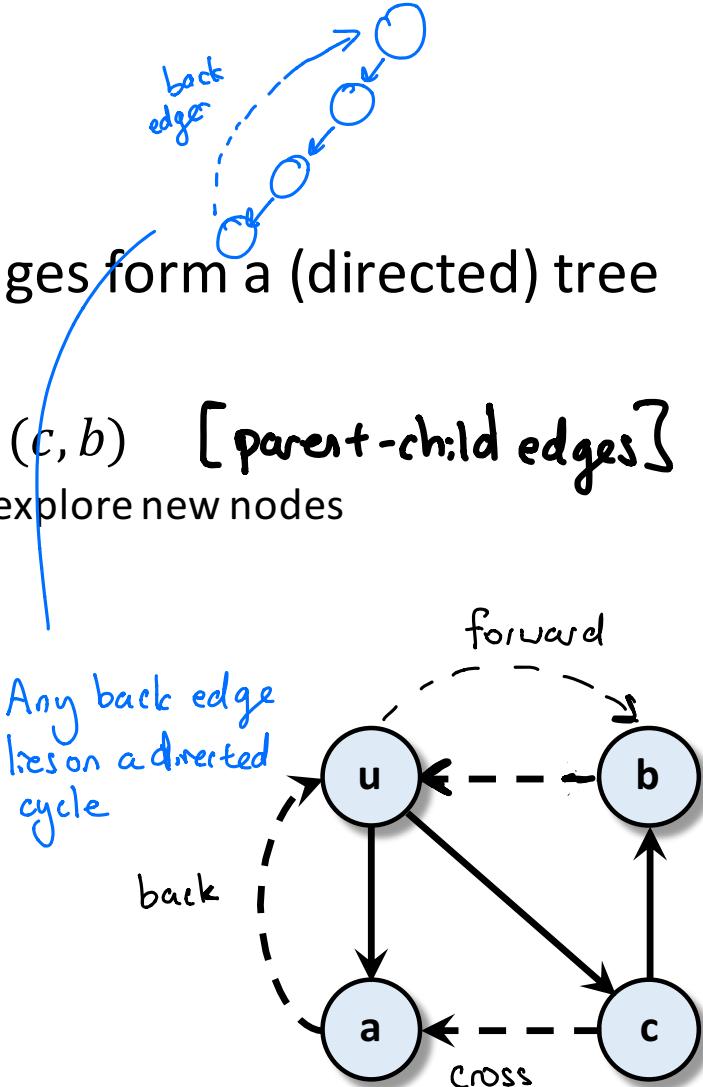
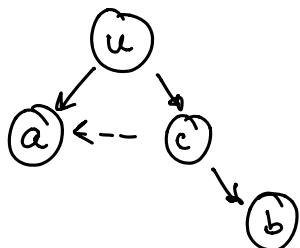


Recursion Stack

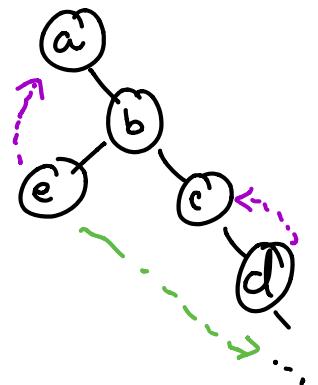
DFS(u) DFS(u) DFS(u) DFS(u) DFS(u) DFS(u)
→ → → → → →
DFS(a) DFS(c) DFS(c) DFS(c) DFS(c) DFS(b)
DFS(c) → DFS(c) → DFS(c) → ...
DFS(b)

Depth-First Search

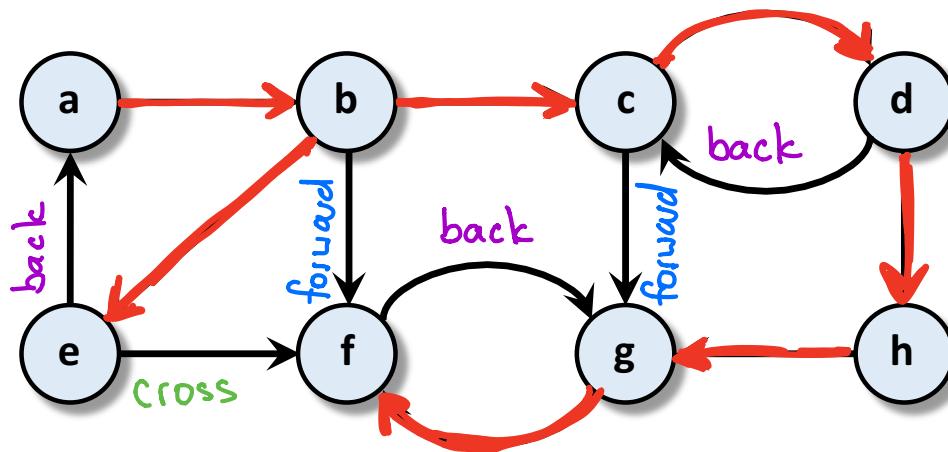
- **Fact:** The parent-child edges form a (directed) tree
- **Each edge has a type:**
 - **Tree edges:** $(u, a), (u, c), (c, b)$ [parent-child edges]
 - These are the edges that explore new nodes
 - **Forward edges:** (u, b)
 - Ancestor to descendant
 - **Backward edges:** (a, u)
 - Descendant to ancestor
 - **Cross edges:** (c, a)
 - No ancestral relation



Ask the Audience



- DFS this graph starting from node *a*
 - Search in alphabetical order
 - Label edges as { tree , forward , backward , cross }



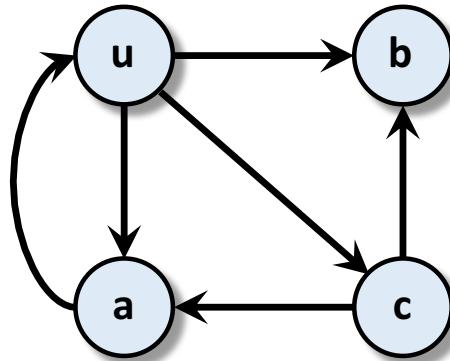
Post-Ordering

```
G = (V,E) is a graph  
explored[u] = 0  $\forall u$ 
```

```
DFS(u) :  
    explored[u] = 1
```

```
        for ((u,v) in E):  
            if (explored[v]=0):  
                parent[v] = u  
                DFS(v)
```

```
post-visit(u)
```



Vertex	Post-Order
u	4
a	1
b	2
c	3

- Maintain a counter **clock**, initially set **clock** = 1
- **post-visit(u)** :
set postorder[u]=clock, clock=clock+1

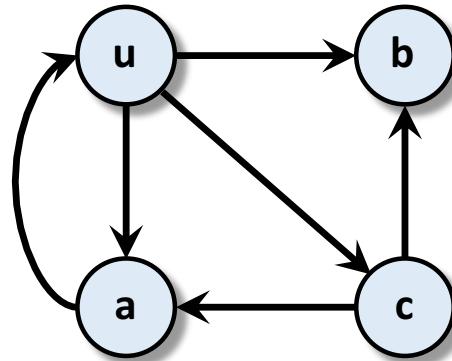
Pre-Ordering

```
G = (V,E) is a graph  
explored[u] = 0  $\forall u$ 
```

```
DFS(u) :  
    explored[u] = 1
```

pre-visit(u)

```
for ((u,v) in E):  
    if (explored[v]=0):  
        parent[v] = u  
        DFS(v)
```

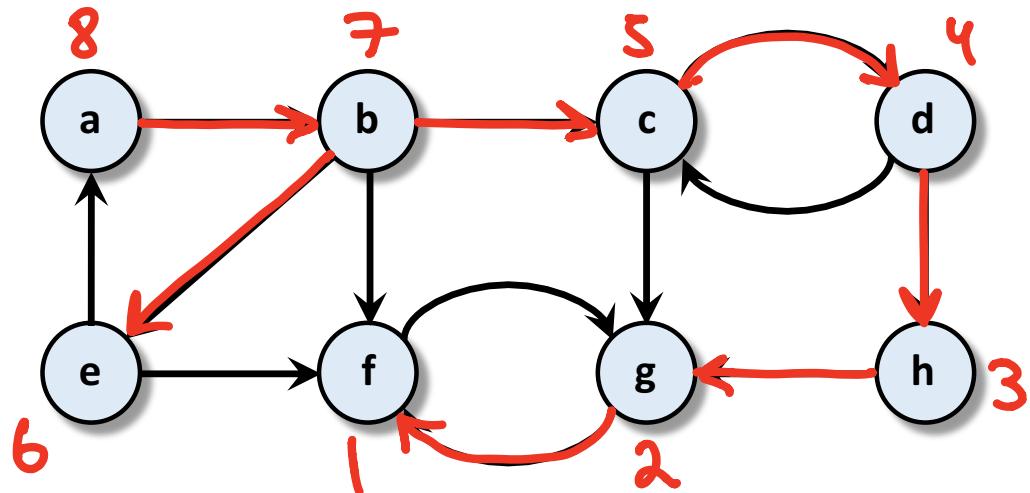


Vertex	Pre-Order
u	1
a	2
b	4
c	3

- Maintain a counter **clock**, initially set **clock** = 1
- **pre-visit(u)** :
set preorder[u]=clock, clock=clock+1

Ask the Audience

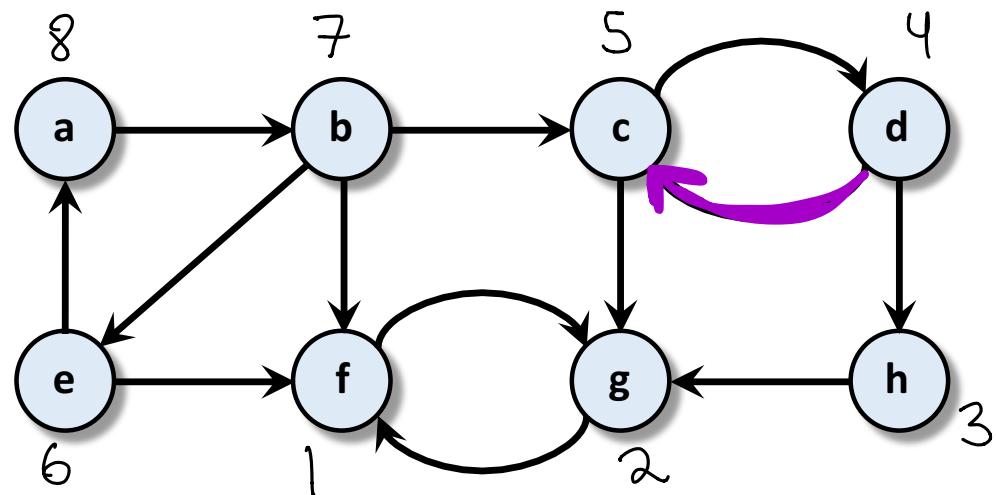
- Compute the **post-order** of this graph
 - DFS from *a*, search in alphabetical order



Vertex	a	b	c	d	e	f	g	h
Post-Order	8	7	5	4	6	1	2	3

Ask the Audience

- **Observation:** if $\text{postorder}[u] < \text{postorder}[v]$ then (u,v) is a backward edge



Vertex	a	b	c	d	e	f	g	h
Post-Order	8	7	5	4	6	1	2	3

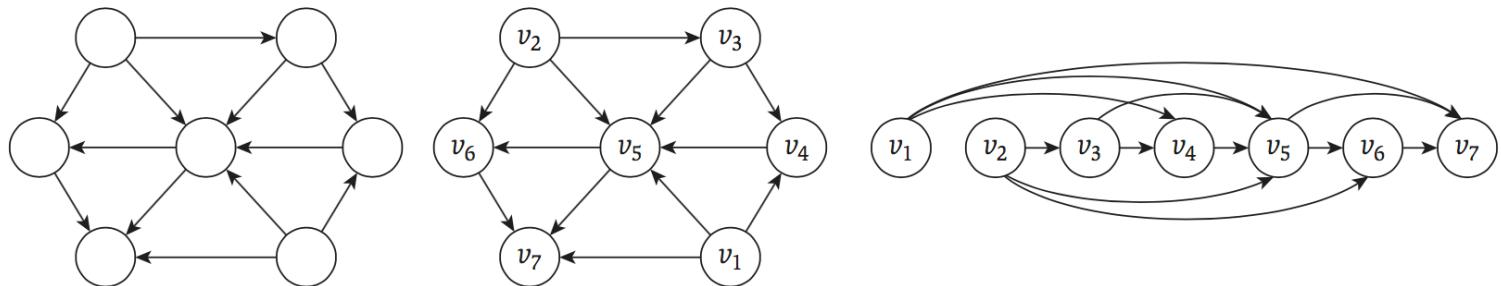
Ask the Audience

- **Observation:** if $\text{postorder}[u] < \text{postorder}[v]$ then (u,v) is a backward edge
 - DFS(u) can't finish until its children are finished
 - If (u,v) is a tree edge, then $\text{postorder}[u] > \text{postorder}[v]$
 - If (u,v) is a forward edge, then $\text{postorder}[u] > \text{postorder}[v]$
 - If $\text{postorder}[u] < \text{postorder}[v]$, then DFS(u) finishes before DFS(v), thus DFS(v) is not called by DFS(u)
 - When we ran DFS(u), we must have had $\text{explored}[v]=1$
 - Thus, DFS(v) started before DFS(u)
 - DFS(v) started before DFS(u) but finished after
 - Can only happen for a backward edge

Fast Topological Ordering

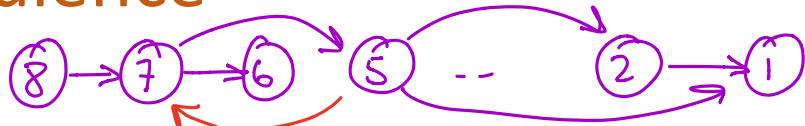
Topological Ordering (TO)

- **DAG**: A directed graph with no directed cycles
- Any DAG can be **topologically ordered**
 - Label nodes v_1, \dots, v_n so that $(v_i, v_j) \in E \Rightarrow j > i$



Ask the Audience

label w)
postorder



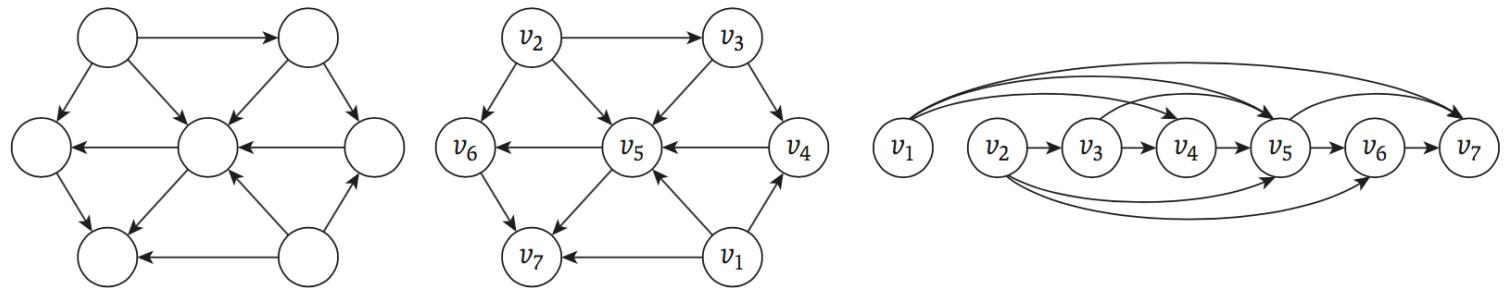
- **Claim:** ordering nodes by decreasing postorder gives a topological ordering

- **Proof:**

- A DAG has no backward edges (back edges \Rightarrow directed cycles)
- Suppose this is **not** a topological ordering
 - That means there exists an edge (u,v) such that $\text{postorder}[u] < \text{postorder}[v]$
 - We showed that any such (u,v) is a backward edge
 - But there are no backward edges, contradiction!

Topological Ordering (TO)

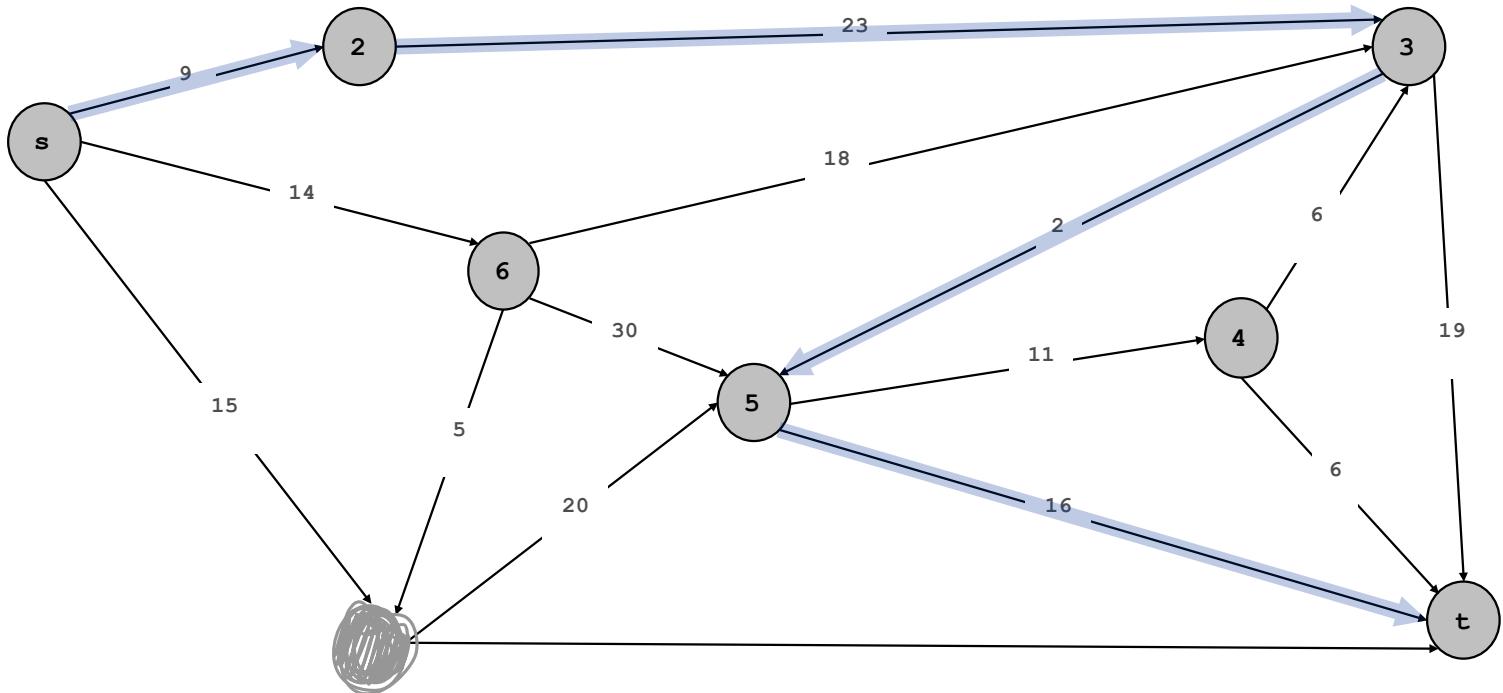
- **DAG**: A directed graph with no directed cycles
- Any DAG can be **topologically ordered**
 - Label nodes v_1, \dots, v_n so that $(v_i, v_j) \in E \Rightarrow j > i$



- Can compute a TO in $O(n + m)$ time using DFS
 - Reverse of post-order is a topological order

Shortest Paths

Navigation



Weighted Graphs

- **Definition:** A weighted graph $G = (V, E, \{w(e)\})$
 - V is the set of vertices
 - $E \subseteq V \times V$ is the set of edges
 - $w_e \in \mathbb{R}$ are edge weights/lengths/capacities
 - Can be directed or undirected
- **Today:**
 - Directed graphs (one-way streets)
 - Strongly connected (there is always some path)
 - Non-negative edge lengths ($\ell(e) \geq 0$)

Shortest Paths

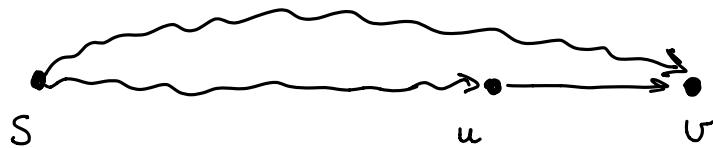
- The length of a path $P = v_1 - v_2 - \dots - v_k$ is the sum of the edge lengths

$$l(P) = \sum_{e \in P} \omega(e)$$

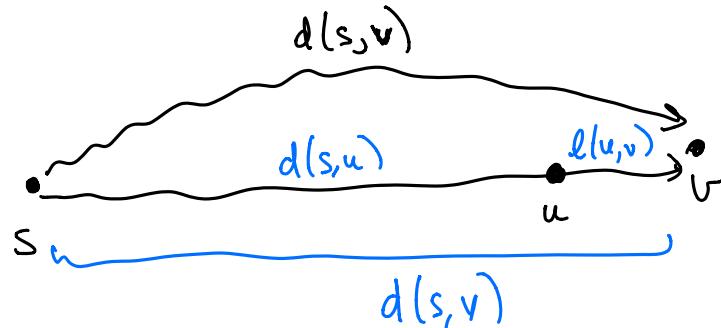
- The distance $d(s, t)$ is the length of the shortest path from s to t
- Shortest Path:** given nodes $s, t \in V$, find the shortest path from s to t
- Single-Source Shortest Paths:** given a node $s \in V$, find the shortest paths from s to **every** $t \in V$

Structure of Shortest Paths

- If $(u, v) \in E$, then $d(s, v) \leq d(s, u) + \ell(u, v)$ for every node $s \in V$

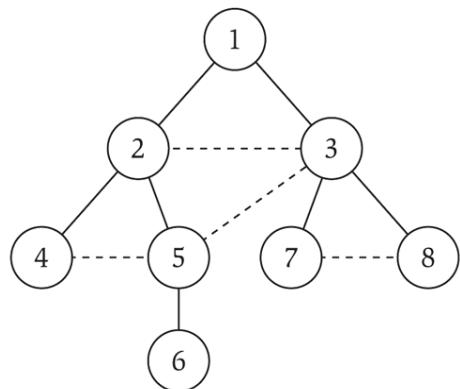
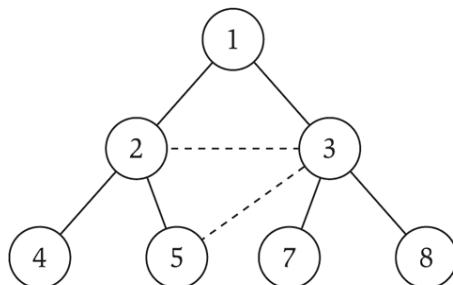
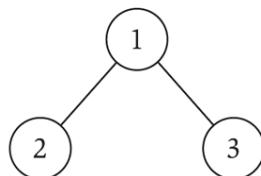


- If $(u, v) \in E$, and $d(s, v) = d(s, u) + \ell(u, v)$ then there is a shortest $s \rightsquigarrow v$ -path ending with (u, v)



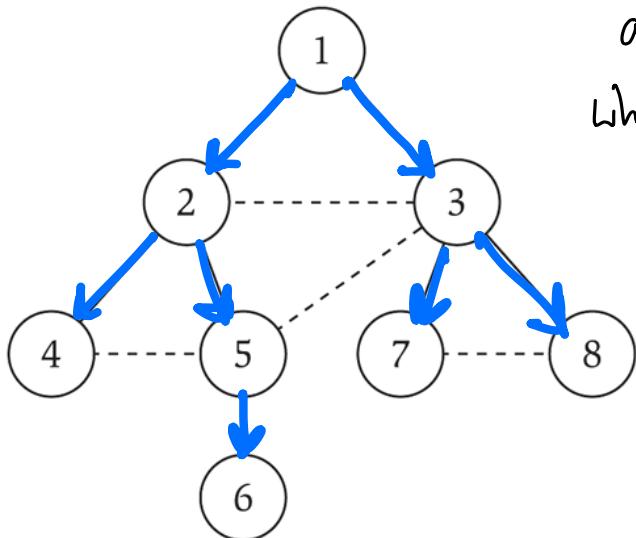
Compare to BFS

- **Thm:** BFS finds distances from s to other nodes
 - L_i contains all nodes at distance i from s
 - Nodes not in any layer are not reachable from s



Compare to BFS

If $\text{parent}[u] = v$ then ?
a shortest s \rightsquigarrow u path
whose last hop is (v, u)

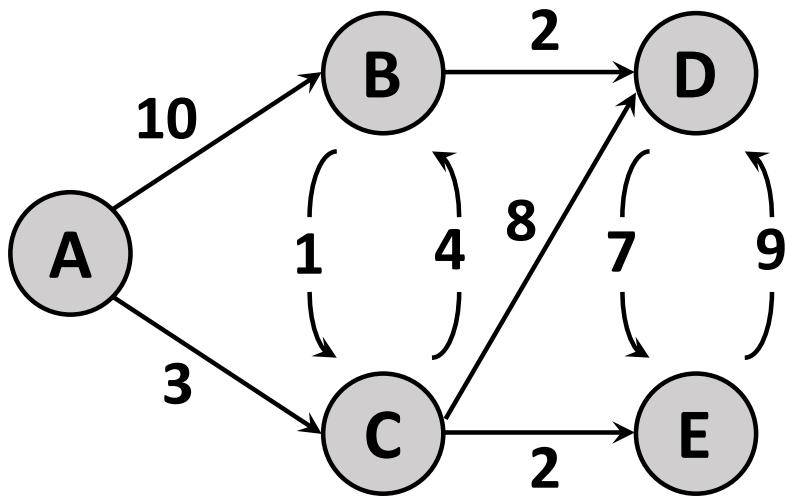


Vertex	1	2	3	4	5	6	7	8
Parent	-	1	1	2	2	5	3	3

Dijkstra's Algorithm

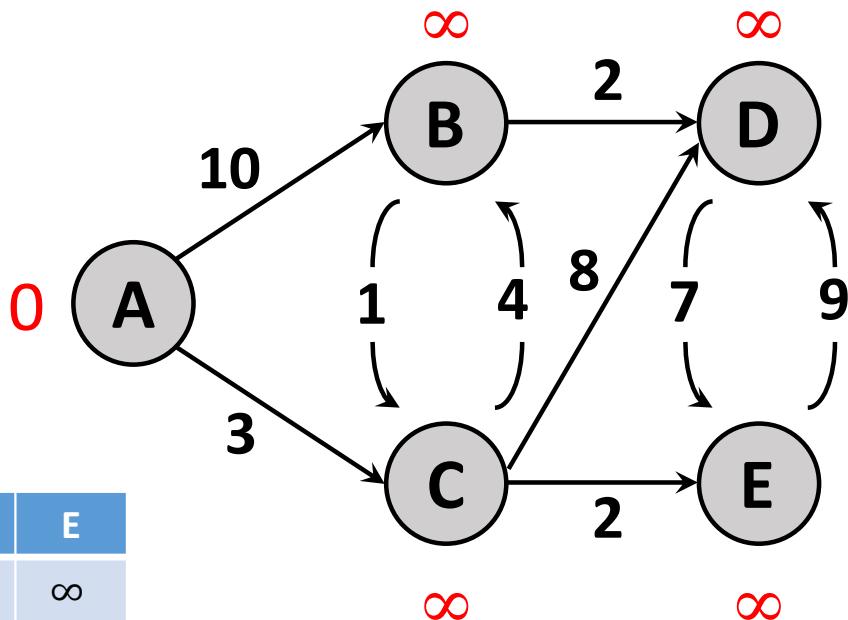
- Dijkstra's Shortest Path Algorithm is a modification of BFS for non-negatively weighted graphs
- Informal Version:
 - Maintain a set S of explored nodes
 - Maintain an upper bound on distance
 - If u is explored, then we know $d(u)$ (Key Invariant)
 - If u is explored, and (u, v) is an edge, then we know $d(v) \leq d(u) + \ell(u, v)$
 - Explore the “closest” unexplored node
 - Repeat until we’re done

Dijkstra's Algorithm: Demo



Dijkstra's Algorithm: Demo

Initialize

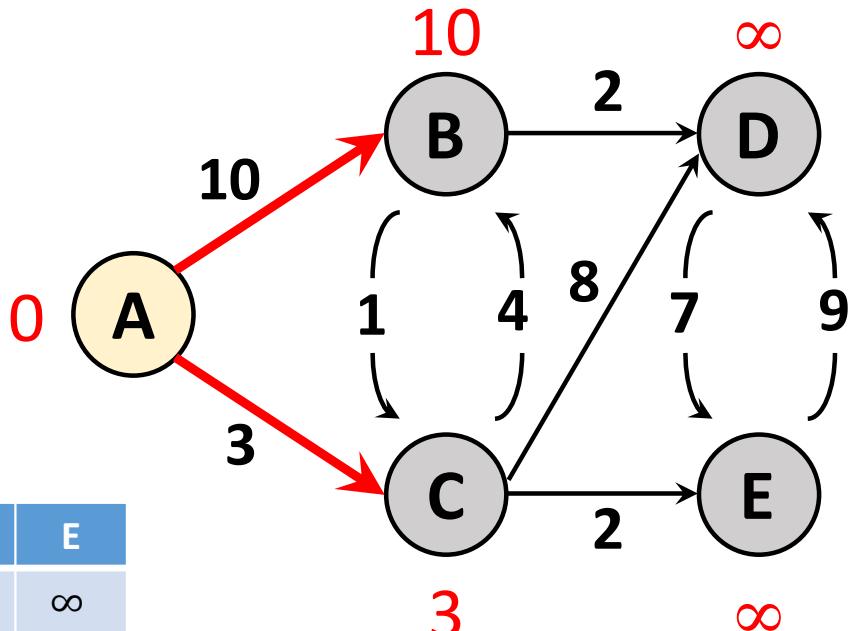


	A	B	C	D	E
$d_0(u)$	0	∞	∞	∞	∞

$$S = \{\}$$

Dijkstra's Algorithm: Demo

Explore A

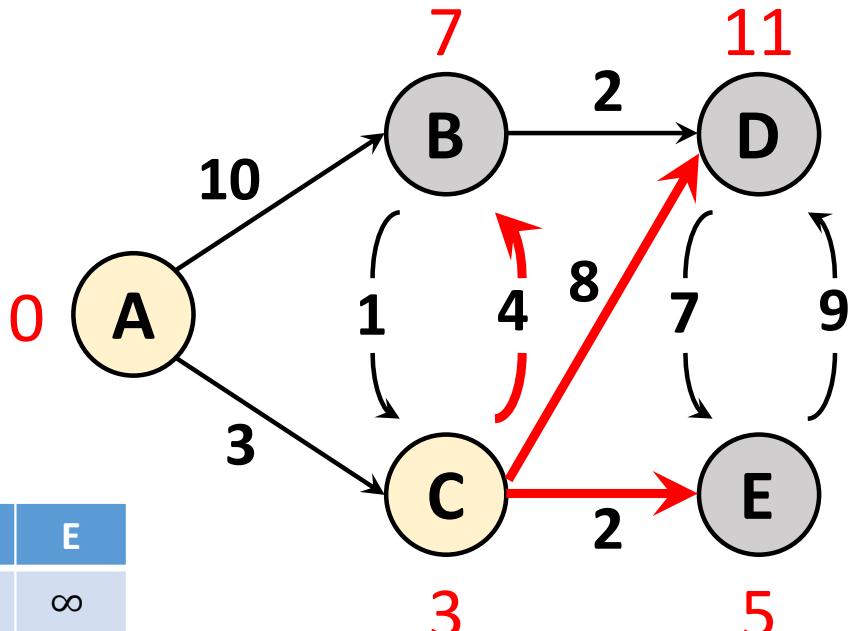


	A	B	C	D	E
$d_0(u)$	0	∞	∞	∞	∞
$d_1(u)$	0	10	3	∞	∞

$$S = \{A\}$$

Dijkstra's Algorithm: Demo

Explore C

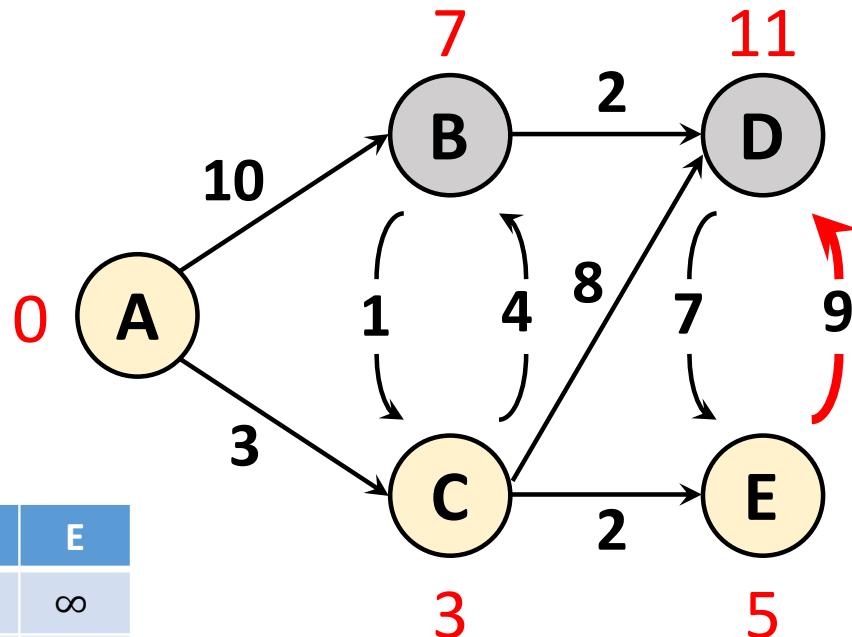


	A	B	C	D	E
$d_0(u)$	0	∞	∞	∞	∞
$d_1(u)$	0	10	3	∞	∞
$d_2(u)$	0	7	3	11	5

$$S = \{A, C\}$$

Dijkstra's Algorithm: Demo

Explore E

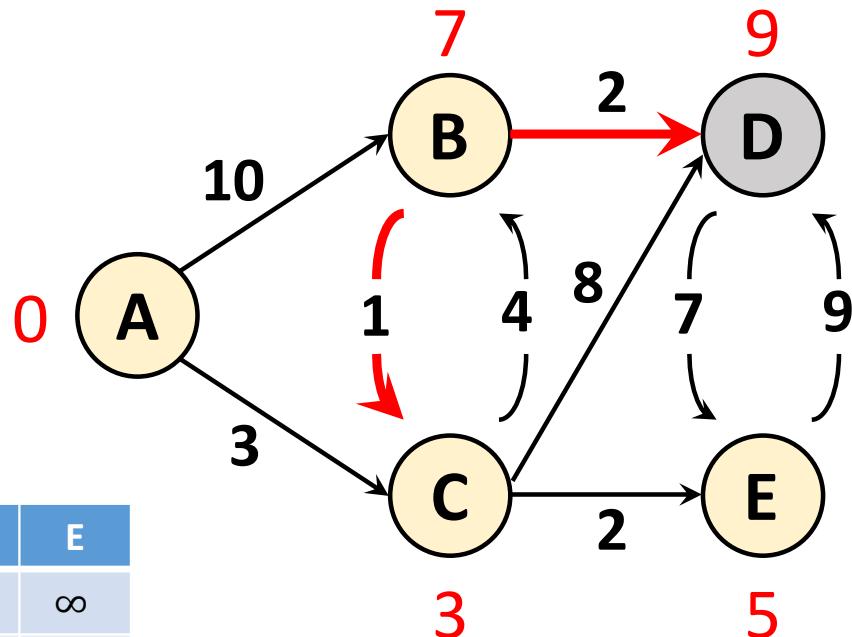


	A	B	C	D	E
$d_0(u)$	0	∞	∞	∞	∞
$d_1(u)$	0	10	3	∞	∞
$d_2(u)$	0	7	3	11	5
$d_3(u)$	0	7	3	11	5

$$S = \{A, C, E\}$$

Dijkstra's Algorithm: Demo

Explore B

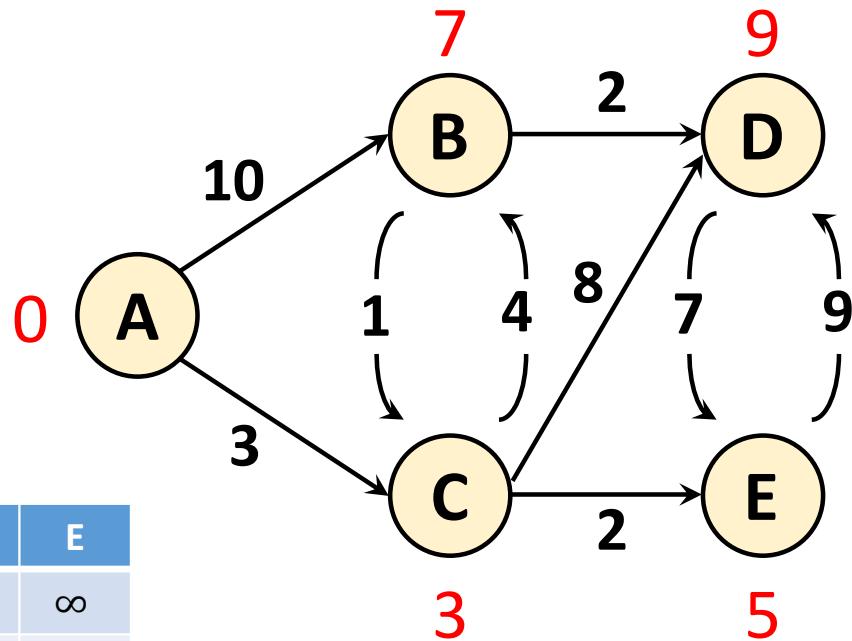


	A	B	C	D	E
$d_0(u)$	0	∞	∞	∞	∞
$d_1(u)$	0	10	3	∞	∞
$d_2(u)$	0	7	3	11	5
$d_3(u)$	0	7	3	11	5
$d_4(u)$	0	7	3	9	5

$$S = \{A, C, E, B\}$$

Dijkstra's Algorithm: Demo

Don't need to explore D

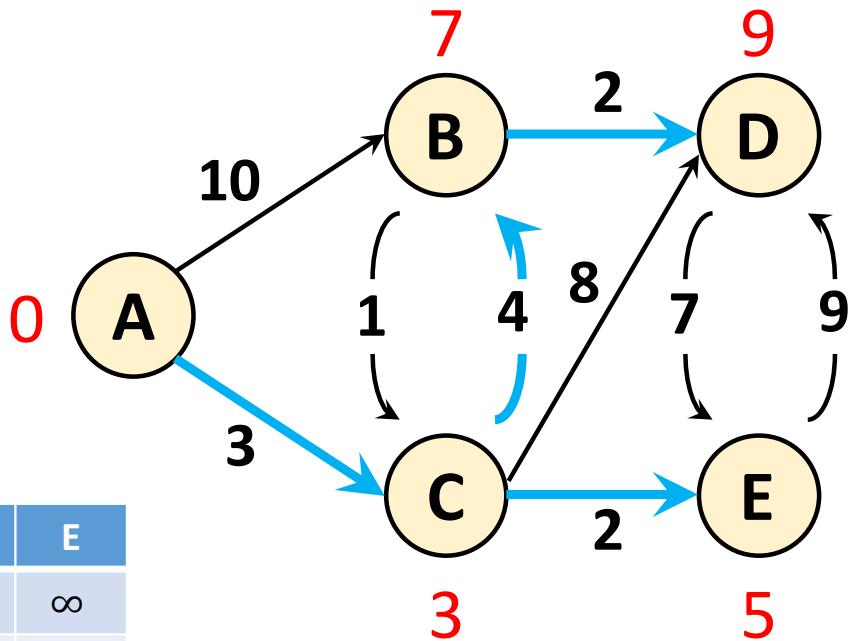


	A	B	C	D	E
$d_0(u)$	0	∞	∞	∞	∞
$d_1(u)$	0	10	3	∞	∞
$d_2(u)$	0	7	3	11	5
$d_3(u)$	0	7	3	11	5
$d_4(u)$	0	7	3	9	5

$$S = \{A, C, E, B, D\}$$

Dijkstra's Algorithm: Demo

Maintain parent pointers so we can find the shortest paths



	A	B	C	D	E
$d_0(u)$	0	∞	∞	∞	∞
$d_1(u)$	0	10	3	∞	∞
$d_2(u)$	0	7	3	11	5
$d_3(u)$	0	7	3	11	5
$d_4(u)$	0	7	3	9	5