

GANs for Compressed Sensing - Theory

CS: Let $x^* \in \mathbb{R}^n$ image observed
 $A \in \mathbb{R}^{m \times n}$ observation matrix, $m < n$
 $\eta \in \mathbb{R}^m$ noise/error
 $y = Ax^* + \eta$ measurements

Given: y, A Find: x^*

As $m < n$, must assume structure to decide which consistent image is most "natural"

Generative model:

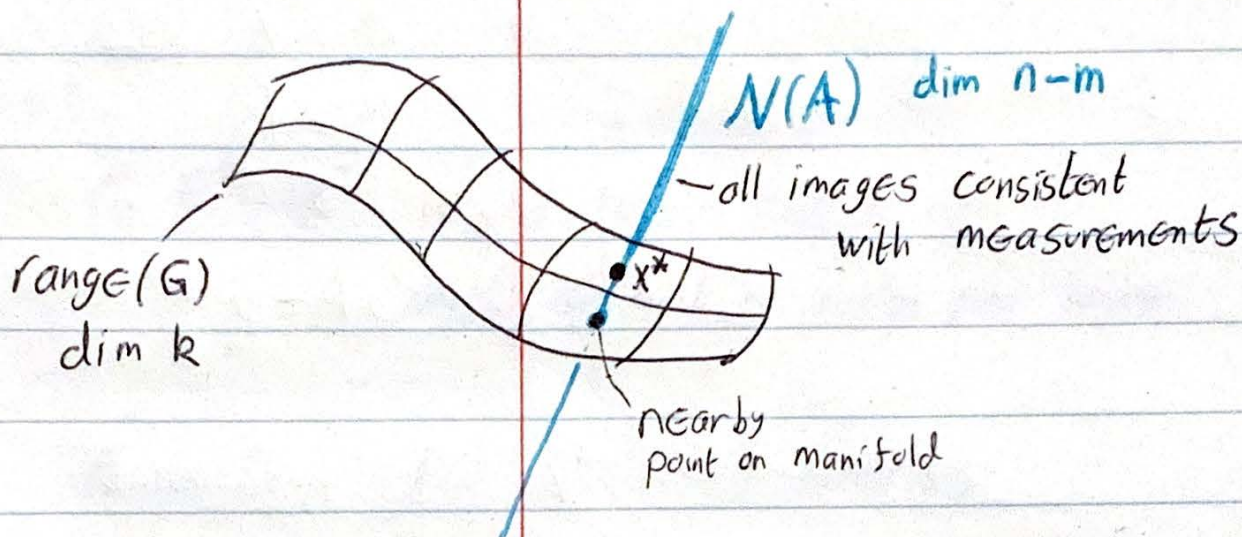
You have trained $G: \mathbb{R}^k \rightarrow \mathbb{R}^n$
 $z \mapsto x$

Such that $G(z)$ for $z \sim \mathcal{N}(0, I_k)$ approximates sampling a natural signal distribution

eg VAEs, GANs

Idea: Use the range of G as a proxy for what images are natural.

Visual Illustration of Geometry of GAN recovery



Recovery Algorithms

$$\min_{z \in \mathbb{R}^k} \|AG(z) - y\| \quad \text{by gradient method}$$

(Bora et al.)

Questions:

How many measurements are needed?

Is this the right problem to solve?

Can this problem be solved?

Theory for CS w/ GAN priors

(Bora et al.)

Setup:

$G: \mathbb{R}^k \rightarrow \mathbb{R}^n$ is a d -layer ReLU net
with at most n nodes per layer

$A \in \mathbb{R}^{m \times n}$ iid $\mathcal{N}(0, 1/m)$ entries

Theorem:

Fix $x^* \in \mathbb{R}^n$. Let $y = Ax^* + \eta$. Let $m = \Omega(kd \log n)$.

Suppose $\|AG(\hat{z}) - y\| \leq \epsilon + \min_z \|AG(z) - y\|$

Then with probability $1 - e^{-\Omega(m)}$

$$\|G(\hat{z}) - x^*\| \leq 6 \min_{z^* \in \mathbb{R}^k} \|G(z^*) - x^*\| + 3\|\eta\| + 2\epsilon$$

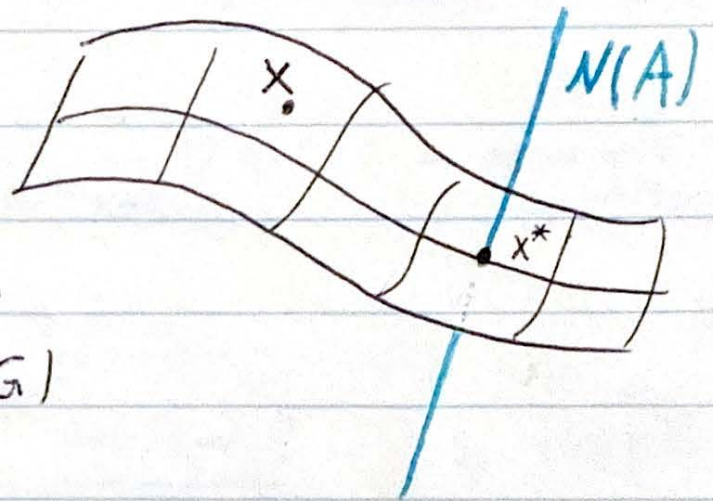
|
representation
error

|
noise

|
Error
from
optimiz.

Recovery based on Set-Restricted Eigenvalue Condition

To guarantee injectivity,
want $N(A)$ to be
away from directions between
pairs of points in $\text{range}(G)$



Defn:

$A \in \mathbb{R}^{m \times n}$ satisfies $S\text{-REC}(S, \gamma)$ if
 $\forall x_1, x_2 \in S$

$$\|A(x_1 - x_2)\| \geq \gamma \|x_1 - x_2\|$$

i.e. $N(A)$ is away from secant lines within S

Lemma: Let $y = Ax^* + \eta$.

Suppose A satisfies $S\text{-REC}(S, \gamma)$ w/ prob $1-p$

and for fixed $x \in \mathbb{R}^n$, $\|Ax\| \leq 2\|x\|$ w/ prob $1-p$

and $\|A\hat{x} - y\| \leq \min_{x \in S} \|y - Ax\| + \epsilon$ for $\hat{x} \in S$

then w/ prob $1-2p$

$$\|\hat{x} - x^*\| \leq \left(\frac{4}{\gamma} + 1\right) \min_{x \in S} \|x^* - x\| + \frac{2\|\eta\| + \epsilon}{\gamma}$$

Proof :

Fix x^* - true image

$$\bar{x} = \operatorname{argmin}_{x \in S} \|x^* - x\| \quad \text{- closest img in } S$$

$$\hat{x} \text{ st } \|A\hat{x} - y\| \leq \min_{x \in S} \|y - Ax\| + \varepsilon \quad \text{- approximate optimizer}$$

$$\|\hat{x} - x^*\| \leq \|x^* - \bar{x}\| + \|\bar{x} - \hat{x}\|$$

$$\leq \dots + \frac{\|A(\bar{x} - \hat{x})\|}{\gamma} \quad \text{by } S\text{-REC}$$

$$\leq \dots + \frac{\|A\bar{x} - y\| + \|A\hat{x} - y\|}{\gamma}$$

$$\leq \dots + \frac{2\|A\bar{x} - y\| + \varepsilon}{\gamma} \quad \text{by approx minimization by } \hat{x}$$

$$\leq \dots + \frac{2\|A\bar{x} - Ax^*\| + 2\|Ax^* - y\| + \varepsilon}{\gamma}$$

$$\leq \dots + \frac{2\|A(\bar{x} - x^*)\| + 2\|y\| + \varepsilon}{\gamma}$$

$$\leq \dots + \frac{4\|\bar{x} - x^*\| + 2\|y\| + \varepsilon}{\gamma} \quad \text{by assump on } A$$

$$\leq \left(1 + \frac{4}{\gamma}\right) \|x^* - \bar{x}\| + \frac{2\|y\| + \varepsilon}{\gamma}$$

□

Random matrices satisfy S-REC

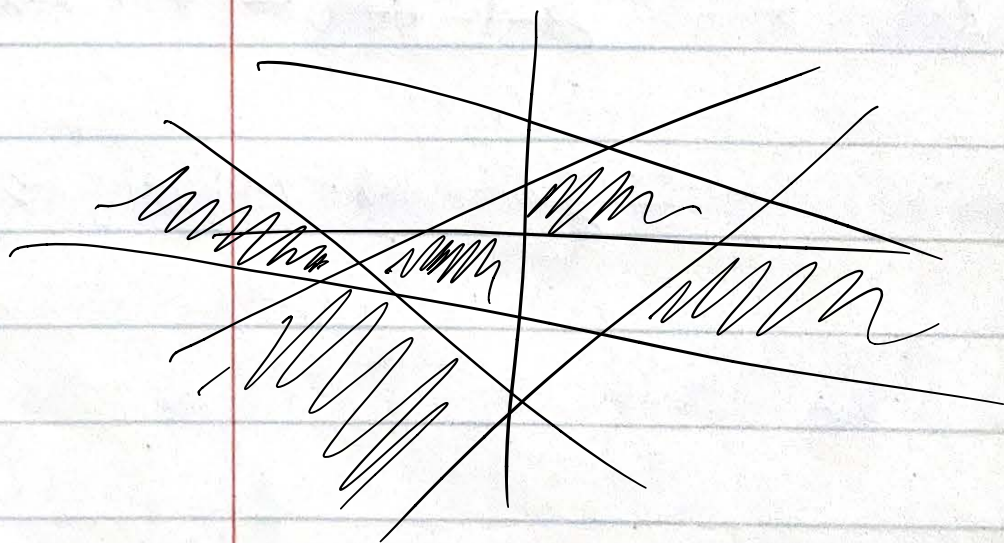
To show A w/ $N(0, 1/m)$ entries satisfies S-REC for G given by ReLU nets, we need two technical results

Theorem: Let $A \in \mathbb{R}^{m \times k}$ have iid $N(0, 1)$ entries.
 $\forall t \geq 0$, with prob at least $1 - 2e^{-t^2/2}$,
 $\sqrt{m} - \sqrt{k} - t \leq \sigma_{\min}(A) \leq \sigma_{\max}(A) \leq \sqrt{m} + \sqrt{k} + t$

See Vershynin "Introduction to the non-asymptotic analysis of random matrices"

States: tall random Gaussian matrices are approximate isometries

Theorem: If \mathbb{R}^k is partitioned by c hyperplanes, the number of partition pieces is $O(c^k)$



Lemma: Let $G: \mathbb{R}^k \rightarrow \mathbb{R}^n$ be a d -layer NN
 w/ each layer a linear transformation
 followed by a ReLU. Suppose G
 has at most n nodes per layer.

If $m = \Omega\left(\frac{1}{\alpha^2} kd \log n\right)$ then

$A \in \mathbb{R}^{m \times n}$ w/ i.i.d $N(0, \frac{1}{m})$ entries satisfies
 $S\text{-REC}(G(\mathbb{R}^k), 1-\alpha)$ w/ prob $1 - e^{-\Omega(\alpha^2 m)}$

Proof: First layer has at most n^k diff. linear pieces
 Applying to d layers, at most n^{kd} linear pieces

So $G(\mathbb{R}^k)$ lives in union of n^{kd} subspaces

of dim k . Thus $\{x_1, x_2 \mid x_{1,2} \in G(\mathbb{R}^k)\}$

lives in union of n^{2kd} subspaces of dim $2k$.

On each subspace A satisfies $S\text{-REC}$

w/ param $1-\alpha$ w/ prob $1 - e^{-\Omega(\alpha^2 m)}$ if $m = \Omega(k/\alpha^2)$

Prob that $S\text{-REC}$ holds on all subspaces is at least

$$1 - n^{2kd} e^{-\Omega(\alpha^2 m)}$$

which is $1 - e^{-\Omega(\alpha^2 m)}$ if $m = \Omega\left(\frac{kd \log n}{\alpha^2}\right)$.

When can one solve the optimization?

$$\min_{Z \in \mathbb{R}^k} \|AG(Z) - y\|$$

Finding minimizer for nonconvex problems is NP-hard in general.

provably
Can solve this problem under a random model for G .

Let $G: \mathbb{R}^k \rightarrow \mathbb{R}^n$ be given by

$$G(Z) = W_d \cdots \text{relu}(W_2 \text{relu}(W_1 Z)) \quad W_i \in \mathbb{R}^{n_i \times n_{i-1}}$$

fully connected / no bias terms

- Assume:
- $n_i > C n_{i-1} \log n_{i-1}$ expansivity
 - W_i has iid $\mathcal{N}(0,1)$ entries Gaussian
 - $m > C k d \log(n_1 n_2 \cdots n_d)$ $\Omega(k)$ measurements.

Then w/ high prob a gradient algorithm will converge to Z^* if $y = AG(Z^*)$.

(Hend + Voroninski, Huang et al.)