

CS3000: Algorithms & Data — Spring 2019 — Paul Hand

Homework 7

Due Wednesday 4/10/2019 at 2:50pm via [Gradescope](#)

Name:

Collaborators:

- Make sure to put your name on the first page. If you are using the \LaTeX template we provided, then you can make sure it appears by filling in the `yourname` command.
- This assignment is due Wednesday 4/10/2019 at 2:50pm via [Gradescope](#). No late assignments will be accepted. Make sure to submit something before the deadline.
- Solutions must be typeset in \LaTeX . If you need to draw any diagrams, you may draw them by hand as long as they are embedded in the PDF. I recommend using the source file for this assignment to get started.
- I encourage you to work with your classmates on the homework problems. *If you do collaborate, you must write all solutions by yourself, in your own words.* Do not submit anything you cannot explain. Please list all your collaborators in your solution for each problem by filling in the `yourcollaborators` command.
- Finding solutions to homework problems on the web, or by asking students not enrolled in the class is strictly forbidden.

Problem 1. All-Pairs Shortest Paths

In the *all-pairs shortest paths* problem, you are given a directed, weighted graph with edge lengths $G = (V, E, \{\ell_e\})$, and have to find the length of the shortest path from s to t for *every pair* $s, t \in V$. For this HW we only want the *length* of the shortest path and not the path itself.

If all edge lengths are non-negative ($\ell_e \geq 0$), then we can solve this problem by running Dijkstra's algorithm from every source node $s \in V$, incurring running time $O(nm \log n)$. However, if lengths can be negative, then running Bellman-Ford from each source node $s \in V$ incurs running time $O(n^2m)$. In this question we will study the following algorithm for solving all-pairs shortest paths in graphs with negative-length edges, but no negative-length cycles.

- Modify the input graph by adding an additional node z connected to every other node v by a zero-length edge (z, v) .
- Run the Bellman-Ford algorithm on the modified graph with source z to find the length $f(v)$ of the shortest $z \rightarrow v$ path in the modified graph.
- Define new edge lengths $\ell'_{u,v} = \ell_{u,v} + f(u) - f(v)$ and let $G' = (V, E, \{\ell'_e\})$ be the input graph with these modified edge weights.
- For each source $s \in V$, run Dijkstra's algorithm on the graph G' with source s to find the length $d'(s, v)$ of the shortest $s \rightarrow v$ path in G' for every node v .
- For every $u, v \in V$, let $d(u, v) = d'(u, v) - f(u) + f(v)$. Output the values $\{d(u, v)\}$.

In this problem, we will show correctness and analyze the running time of this algorithm. The final three steps of the problem form the proof of correctness.

- (a) What is the running time of this algorithm? Briefly explain your answer.

Solution:

- (b) Prove that every edge in G' has non-negative length. That is, $\forall u, v \in V, \ell'_{u,v} \geq 0$. (Thus, Dijkstra's algorithm will correctly find the length $d'(u, v)$ of the shortest $u \rightarrow v$ path in G' .)

Solution:

- (c) Prove that for every $u \rightarrow v$ path $P = u \rightarrow w_1 \rightarrow \dots \rightarrow w_{k-1} \rightarrow v$, we have $\ell'_P = \ell_P + f(u) - f(v)$ where ℓ'_P, ℓ_P are the length of the path in G' and G , respectively.

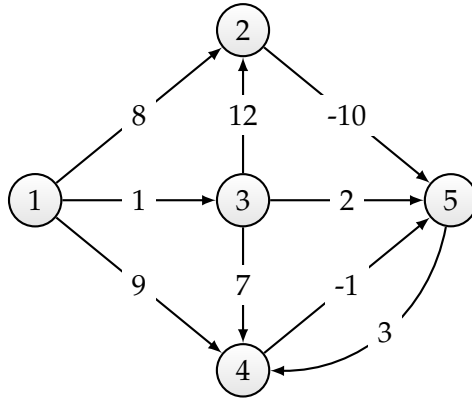
Solution:

- (d) Prove that for every $u, v \in V$, $d'(u, v) - f(u) + f(v)$ is the length of the shortest $u \rightarrow v$ path in the original graph G . Thus, the final lengths output by this algorithm are correct.

Solution:

Problem 2. Shortest Paths Practice

Solve the single-source shortest path problem on the following graph, using node 1 as the source. Write the distance from s to each node and write the parent of each node in the shortest path tree. **Hint:** Write your solution using the skeleton table provided.



Solution:

Node	1	2	3	4	5
Distance					
Parent	⊥				

Problem 3. *Priority Queues and Heaps*

Write pseudocode for a priority queue implemented via a heap. The only data structures you are allowed to use are arrays. You should keep track of the length of the arrays using a variable. You may assume that the priority queue will never hold more than N items, and you may initialize arrays to have length N . You may assume that all keys are an integer from 0 to $N - 1$. You do not need to implement error checking with user input (for example if a user calls `ExtractMin` on a queue with no entries, or if a user attempts to add an entry for a key that is already in the queue, or if a user attempts to add an entry to a queue that already contains N entries, etc.).

Use the global variable V for the array of (key,value) pairs in the heap. Use the notation $V[k].key$ and $V[k].value$ to refer to the key and value of the k th entry of V . Use the global variable K for the array of indexes within V corresponding to each key. Use the global variable L for the current number of items in the queue.

You must implement the following operations:

- `INITIALIZE(N)`. Initializes a priority queue that can handle at most N items.
- `INSERT(k, v)`. Adds the key-value pair (k, v) to the priority queue.
- `LOOKUP(k)`. Returns the value corresponding to the key k .
- `EXTRACTMIN()`. Returns the key-value pair (k, v) of minimal value and removes it from the priority queue.
- `DECREASEKEY(k, v)`. Decreases the value of k to v , which you may assume is less than its previous value.

Solution: