

CS3000: Algorithms & Data

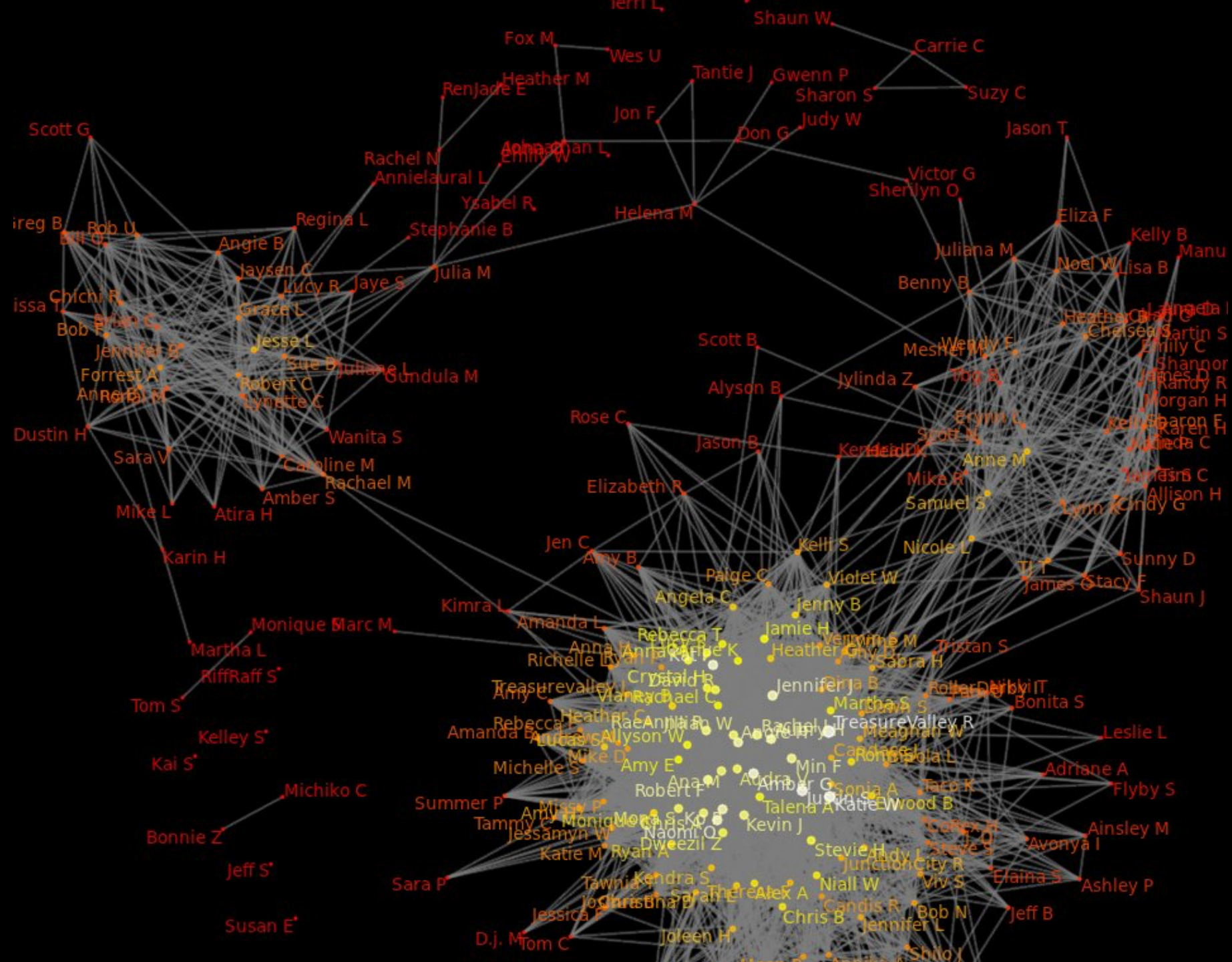
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Lecture 13:

- Introduction to Graphs
- Breadth First Search

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Graphs



Graphs Are Everywhere

- Transportation networks
- Communication networks
- WWW
- Biological networks
- Citation networks
- Social networks
- ...

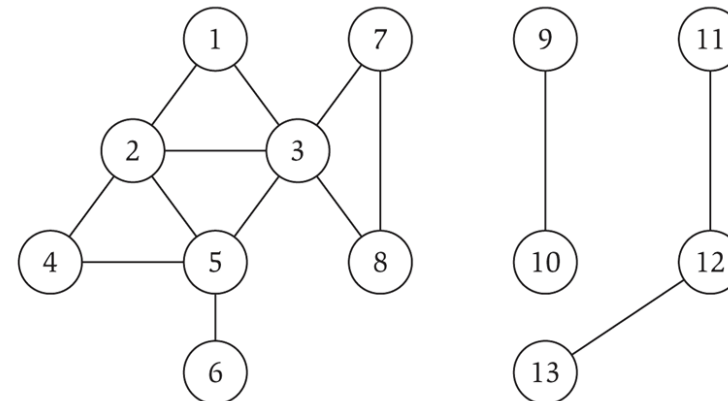
What's Next

- **Graph Algorithms:**
 - **Graphs:** Key Definitions, Properties, Representations
 - **Exploring Graphs:** Breadth/Depth First Search
 - Applications: Connectivity, Bipartiteness, Topological Sorting
 - **Shortest Paths:**
 - Dijkstra
 - Bellman-Ford (Dynamic Programming)
 - **Minimum Spanning Trees:**
 - Borůvka, Prim, Kruskal
 - **Network Flow:**
 - Algorithms
 - Reductions to Network Flow

Graphs: Key Definitions

- **Definition:** A directed graph $G = (V, E)$
 - V is the set of nodes/vertices
 - $E \subseteq V \times V$ is the set of edges
 - An edge is an ordered $e = (u, v)$ “from u to v ”
- **Definition:** An undirected graph $G = (V, E)$
 - Edges are unordered $e = (u, v)$ “between u and v ”

- **Simple Graph:**
 - No duplicate edges
 - No self-loops $e = (u, u)$



Activity

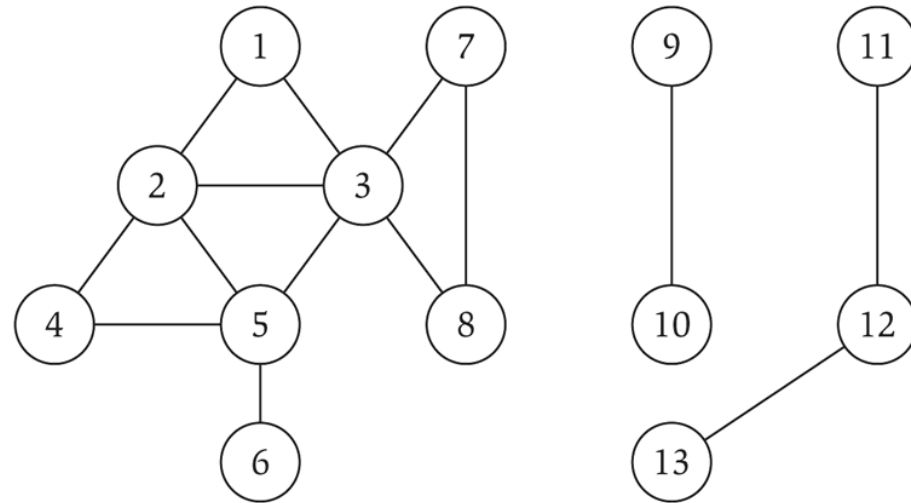
- How many edges can there be in a **simple** **directed/undirected** graph with n nodes?

Paths/Connectivity

- A **path** is a sequence of consecutive edges in E
 - $P = \{(u, w_1), (w_1, w_2), (w_2, w_3), \dots, (w_{k-1}, v)\}$
 - $P = u - w_1 - w_2 - w_3 - \dots - w_{k-1} - v$
 - The **length** of the path is the # of edges
- An **undirected** graph is **connected** if for every two vertices $u, v \in V$, there is a path from u to v
- A **directed** graph is **strongly connected** if for every two vertices $u, v \in V$, there are paths from u to v and from v to u

Cycles

- A **cycle** is a path $v_1 - v_2 - \dots - v_k - v_1$ where $k \geq 3$ and v_1, \dots, v_k are distinct



Activity: how many cycles are there in this graph?

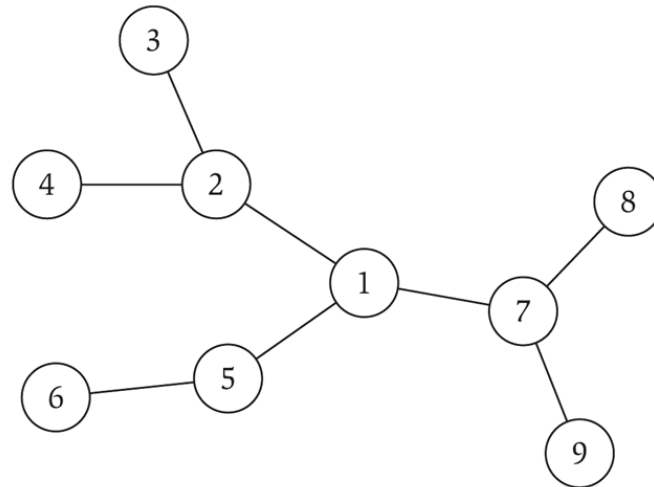
Activity

- Suppose an n -node undirected graph G is connected
 - True/False? G has at least $n - 1$ edges

- Suppose an n -node undirected graph G has $n - 1$ edges
 - True/False? G is connected

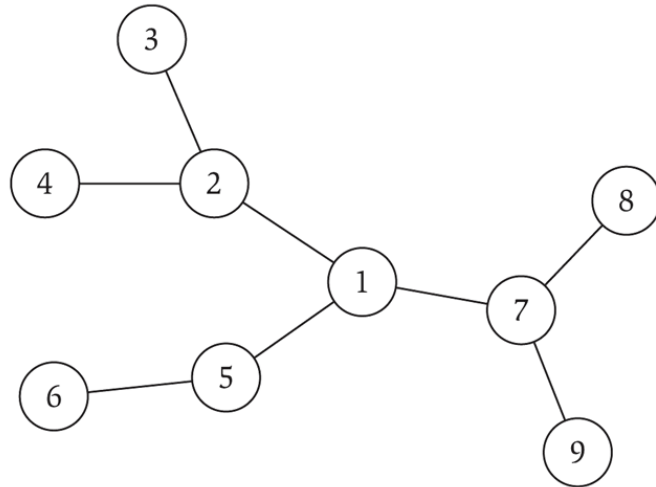
Trees

- A simple undirected graph G is a **tree** if:
 - G is connected
 - G contains no cycles
- **Theorem:** any two of the following implies the third
 - G is connected
 - G contains no cycles
 - G has $= n - 1$ edges



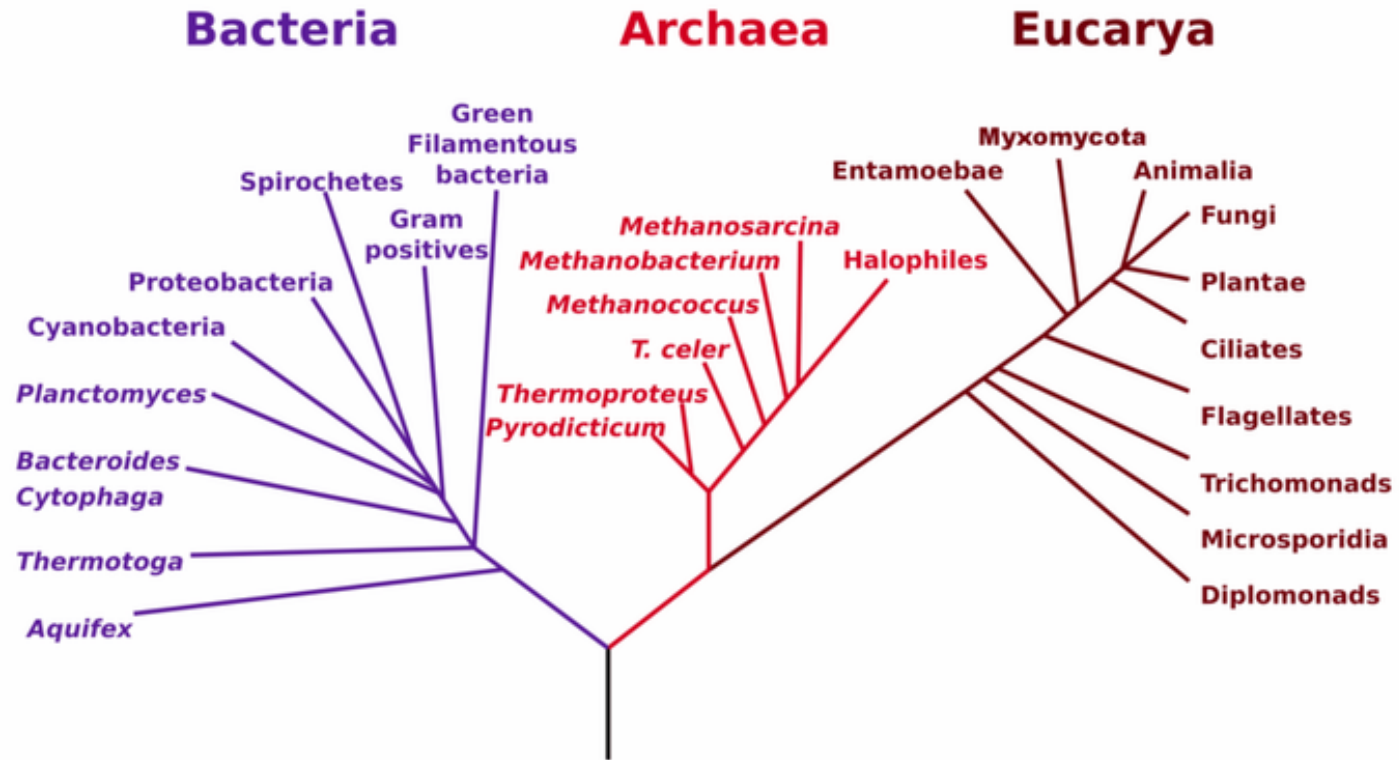
Trees

- **Rooted tree:** choose a root node r and orient edges away from r
 - Models **hierarchical structure**



Phylogeny Trees

Phylogenetic Tree of Life



Exploring a Graph

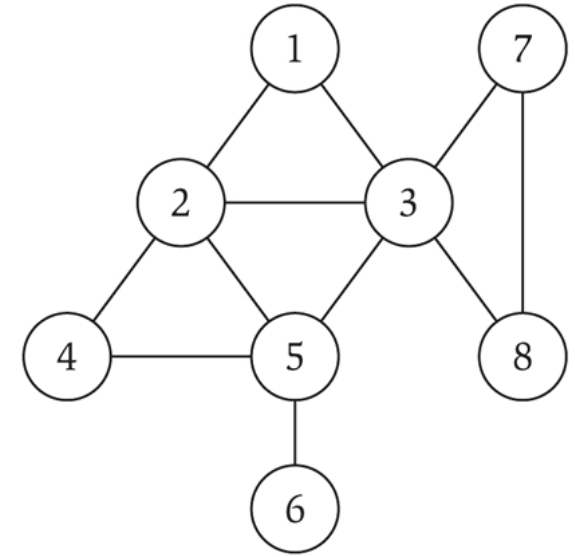
Exploring a Graph

- **Problem:** Is there a path from s to t ?
- **Idea:** Explore all nodes reachable from s .

- Two different search techniques:
 - **Breadth-First Search:** explore nearby nodes before moving on to farther away nodes
 - **Depth-First Search:** follow a path until you get stuck, then go back

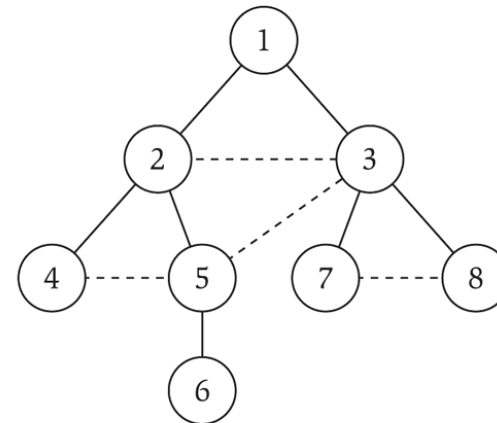
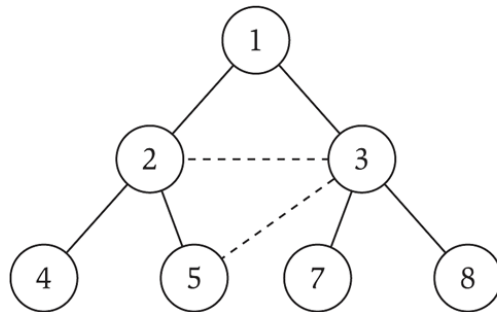
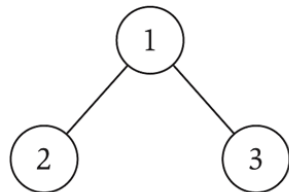
Breadth-First Search (BFS)

- **Informal Description:** start at s , find neighbors of s , find neighbors of neighbors of s , and so on...
- **BFS Tree:**
 - $L_0 = \{s\}$
 - $L_1 =$ all neighbors of L_0
 - $L_2 =$ all neighbors of L_1 that are not in $\{L_0, L_1\}$
 - $L_3 =$ all neighbors of L_2 that are not in $\{L_0, L_1, L_2\}$
 - ...
 - $L_d =$ all neighbors of L_{d-1} that are not in $\{L_0, \dots, L_{d-1}\}$
 - Stop when L_{d+1} is empty



Breadth-First Search (BFS)

- **Definition:** the **distance** between s, t is the number of edges on the shortest path from s to t
- **Thm:** BFS finds distances from s to other nodes
 - L_i contains all nodes at distance i from s
 - Nodes not in any layer are not reachable from s



Adjacency Matrices

- The **adjacency matrix** of a graph $G = (V, E)$ with n nodes is the matrix $A[1:n, 1:n]$ where

$$A[i, j] = \begin{cases} 1 & (i, j) \in E \\ 0 & (i, j) \notin E \end{cases}$$

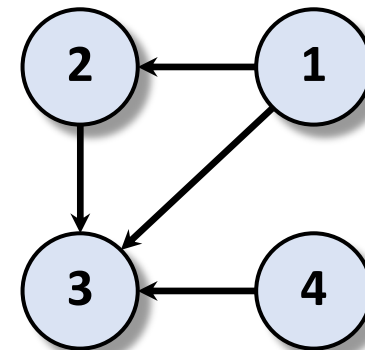
A	1	2	3	4
1	0	1	1	0
2	0	0	1	0
3	0	0	0	0
4	0	0	1	0

Cost

Space: $\Theta(n^2)$

Lookup: $\Theta(1)$ time

List Neighbors: $\Theta(n)$ time



Adjacency Lists (Undirected)

- The **adjacency list** of a vertex $v \in V$ is the list $A[v]$ of all u s.t. $(v, u) \in E$

$$A[1] = \{2,3\}$$

$$A[2] = \{1,3\}$$

$$A[3] = \{1,2,4\}$$

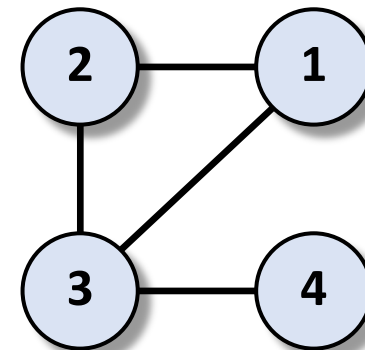
$$A[4] = \{3\}$$

Cost

Space: $\Theta(n + m)$

Lookup: $\Theta(\deg(u) + 1)$ time

List Neighbors: $\Theta(\deg(u) + 1)$ time



Breadth-First Search Implementation

```
BFS( $G = (V, E)$ ,  $s$ ):  
  Let  $\text{found}[v] \leftarrow \text{false} \ \forall v$ ,  $\text{found}[s] \leftarrow \text{true}$   
  Let  $\text{layer}[v] \leftarrow \infty \ \forall v$ ,  $\text{layer}[s] \leftarrow 0$   
  Let  $i \leftarrow 0$ ,  $L_0 = \{s\}$ ,  $T \leftarrow \emptyset$   
  
  While ( $L_i$  is not empty):  
    Initialize new layer  $L_{i+1}$   
    For ( $u$  in  $L_i$ ):  
      For ( $(u, v)$  in  $E$ ):  
        If ( $\text{found}[v] = \text{false}$ ):  
           $\text{found}[v] \leftarrow \text{true}$ ,  $\text{layer}[v] \leftarrow i+1$   
          Add  $(u, v)$  to  $T$  and add  $v$  to  $L_{i+1}$   
     $i \leftarrow i+1$ 
```

Implements BFS in $O(n + m)$ time