

Big Questions:

Setup: A signal $X \in \mathbb{R}^n$ has some sparsity structure.
Given m measurements of $X \in \mathbb{R}^n$, find X .

Qs: How many m are required?
How many m permit efficient algorithm for recovery?
What algorithm?
What types of measurements are ok?
What happens if there is noise?

Signal recovery without structure:

Let $x_0 \in \mathbb{R}^n$ be arbitrary. Let $a_i \cdot x_0 = b_i \quad i = 1 \dots m$

Given $\{a_i, b_i\}_{i=1}^m$, find x_0 .

How many m are required?

$$m \geq n$$

Consider case $m=n$. How do you find x_0 ?

$$A = \begin{pmatrix} -a_1 & - \\ -a_2 & - \\ \vdots & - \\ -a_n & - \end{pmatrix} \in \mathbb{R}^{n \times n}$$

Solve $Ax=b$ by LU and back substitution

When does this work?

If $\{a_i\}_{i=1}^n$ are linearly independent,
then x_0 is unique solution to $Ax=b$.

How robust to errors?

Suppose $b = Ax_0 + e$.

Solve $Ax=b$.

How big is error in x in terms of error in b ?

$$A(x-x_0) = e$$

$$x-x_0 = A^{-1}e \quad \text{spectral norm}$$

$$\|x-x_0\|_2 \leq \|A^{-1}\| \|e\|_2$$

$$\|x-x_0\|_2 \leq \frac{1}{\sigma_{\min}(A)} \|e\|_2$$

Relative error:

$$\|x\| \quad Ax_0 = b \Rightarrow \|A\| \|b\| \leq \|A\| \|x_0\|$$

$$S_6 \quad \frac{\|x - x_0\|_2}{\|x_0\|_2} \leq \|A\| \|A^{-1}\| \frac{\|e\|_2}{\|b\|_2}$$

$$\frac{\|x - x_0\|_2}{\|x_0\|_2} \leq \frac{\sigma_{\max}(A)}{\sigma_{\min}(A)} \frac{\|e\|_2}{\|b\|_2}$$

κ - condition number

What measurement ^{vectors} ~~matrices~~ lead to better error bands?

If a_i are all orthogonal and normal, $\sigma_{\min}^K = 1$

If a_i are nearly parallel, σ_{\min}^K is ~~small~~ ^{K largest}

What if $m > n$?

Let $b_i = a_i \cdot x_0$ $i = 1 \dots m \geq n$, $a_i \in \mathbb{R}^n$, $x_0 \in \mathbb{R}^n$

Find x by solving least squares

$$\min_x \|Ax - b\|_2^2 \quad \text{w/ } A = \begin{pmatrix} -a_1- \\ -a_2- \\ \vdots \\ -a_m- \end{pmatrix}$$

How to solve:

~~Lagrange Multiplier~~
Take deriv & set to 0

$$\begin{aligned} &\langle A(x+\delta x) - b, A(x+\delta x) - b \rangle \\ &= \langle Ax - b, Ax - b \rangle + \langle Ax - b, A\delta x \rangle \\ &\quad + \langle A\delta x, Ax - b \rangle \\ &\quad + o(\delta x^2) \end{aligned}$$

$$\begin{aligned} \nabla \frac{1}{2} \|Ax - b\|_2^2 &= \nabla \frac{1}{2} \langle Ax - b, Ax - b \rangle = \langle Ax - b, Ax - b \rangle + \langle A^t(Ax - b), \dots \\ &= A^t(Ax - b) \end{aligned}$$

So $A^t(Ax - b)$

$$\begin{aligned} \text{s. } A^t Ax &= A^t b \\ x &= (A^t A)^{-1} A^t b \end{aligned}$$

If $A = \hat{Q}\hat{R}$ is reduced QR

$$A = \hat{Q}\hat{R} \\ \begin{pmatrix} & & \\ & & \\ & & \end{pmatrix}_{m \times n} = \begin{pmatrix} & & \\ & & \\ & & \end{pmatrix}_{m \times n} \begin{pmatrix} & & \\ & & \\ & & \end{pmatrix}_{n \times n}$$

$$\begin{aligned} x &= (\hat{R}^t \hat{R})^{-1} \hat{R}^t \hat{Q}^t b \\ x &= \hat{R}^{-1} \hat{Q}^t b \end{aligned}$$

Claim: If A is $m \times n$, $m > n$, full rank, $b_0 = Ax_0$
then $\arg \min_x \|Ax - b_0\|$ is x_0 .

If $b = Ax_0 + e$, then

$$\frac{\|x - x_0\|_2}{\|x_0\|_2} \leq K(\hat{R}) \frac{\|e\|_2}{\|b_0\|_2}$$

where $A = \hat{Q}\hat{R}$.